# The 'Structural After Measurement' (SAM) approach to SEM

Yves Rosseel
Department of Data Analysis
Ghent University – Belgium

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## literature

Rosseel, Y., & Loh, W.W. (2024). A structural after measurement approach to structural equation modeling. *Psychological Methods*, 29(3), 561–588.

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Levy, R. (2023). Precluding interpretational confounding in factor analysis with a covariate or outcome via measurement and uncertainty preserving parametric modeling. *Structural Equation Modeling: A Multidisciplinary Journal*.

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https://doi.org/10.1111/bmsp.12227(Open Access)

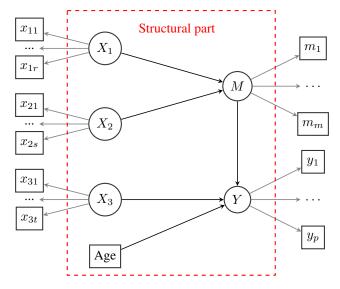
Kuha, J., & Bakk, Z. (arxiv.org). Two-step estimation of latent trait models.

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Vermunt, J. (2024). Stepwise latent variable modeling: An overview of approaches.

https://jeroenvermunt.nl/stepwiseLVM2024.pdf

# the setting: structural equation models



# the setting (2)

- structural equation models
- we focus on 'large' models with many (say, > 100) parameters:
  - many constructs (motivation, ability, personality traits, ...)
  - each construct is measured by a set of (observed) indicators
  - many 'background' variables (age, gender, ...)
  - multilevel data, missing data, ...
- we are mostly interested in the structural part of the model:
  - regression model: variables are either dependent or independent
  - path analysis model: includes mediating effects, perhaps non-recursive
- assumption: the measurement instruments for the latent variables are well established, and usually fit (reasonably) well
- BUT: the sample size is not large (say, N = 150)

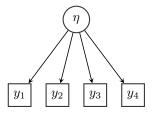
# model parameters

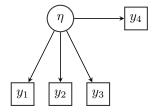
- the majority of the model parameters (in SEM) are related to the measurement part of the model:
  - factor loadings
  - residual variances for the indicators
  - factor (co)variances
- only a small portion ( <10% ) of the model parameters is related to the structural part of the model:
  - regression coefficients (usually the focus of the analysis)
  - (residual) (co)variances

# the standard estimation approach in SEM: 'system-wide' estimation

- all parameters (measurement and structural) are estimated jointly
- frequentist: typically using an iterative optimization approach (e.g., ML); Bayesian: typically using MCMC
- advantages:
  - one-step, and therefore efficient (in terms of sampling variability)
  - inference is straightforward (standard errors, hypothesis testing)
  - (relatively) easy to handle constraints, missing data, ...
- works very well if the following conditions are met:
  - correctly specified model, large sample size
  - (normally distributed data)
- but under less ideal circumstances, system-wide estimation does not (always) work well (bias, instability, nonconvergence, improper solutions, ...)
- in addition: combining 'structural' and 'measurement' is not a good idea

# example (stolen from Roy Levy, 2023)





- left panel: only measurement
- right panel: measurement + structural
- · conceptually very different
- mathematically identical (in system-wide SEM)

# generate some data

```
> library(lavaan)
> Sigma <- matrix(c(2.0, 1.0, 1.0, 1.0, 1.5,
                    1.0, 2.0, 1.0, 1.0, 0.1,
                    1.0, 1.0, 2.0, 1.0, 0.1,
                    1.0, 1.0, 1.0, 2.0, 0.1,
                    1.5, 0.1, 0.1, 0.1, 2.0), nrow = 5, ncol = 5
> rownames(Sigma) <- colnames(Sigma) <- c("y1", "y2", "y3", "y4", "z")
> Sigma
   y1 y2 y3 y4 z
v1 2.0 1.0 1.0 1.0 1.5
v2 1.0 2.0 1.0 1.0 0.1
v3 1.0 1.0 2.0 1.0 0.1
v4 1.0 1.0 1.0 2.0 0.1
z 1.5 0.1 0.1 0.1 2.0
> set.seed(3)
> Data <- MASS::mvrnorm(n = 200L, mu = rep(0, 5), Sigma = Sigma)
```

# R code left panel (model1)

```
> model1 <- '
    f = " y1 + y2 + y3 + y4
'
> fit1 <- sem(model1, data = Data)
> summary(fit1)
```

lavaan 0.6-20.2234 ended normally after 25 iterations

Estimator	ML
Optimization method	NLMINB
Number of model parameters	8

Model Test User Model:

Number of observations

 Test statistic
 0.140

 Degrees of freedom
 2

 P-value (Chi-square)
 0.932

Parameter Estimates:

Standard errors Standard Information Expected Information saturated (h1) model Structured

200

#### Latent Variables:

	Estimate	Std.Err	z-va⊥ue	P(> z )
f =~				
y1	1.000			
y2	0.996	0.123	8.122	0.000
у3	0.894	0.116	7.689	0.000
y <b>4</b>	0.911	0.120	7.608	0.000

## Variances:

	Estimate	Std.Err	z-value	P(> z )
. y1	1.096	0.148	7.388	0.000
. y2	0.837	0.127	6.601	0.000
. y3	0.987	0.128	7.694	0.000
. y4	1.081	0.138	7.820	0.000
f	1.031	0.208	4.959	0.000

# R code right panel (model2)

```
> model2 <- '
    f = "y1 + y2 + y3
    y4 " f
'
> fit2 <- sem(model2, data = Data)
> summary(fit2)
```

lavaan 0.6-20.2234 ended normally after 26 iterations

Estimator	ML
Optimization method	NLMINB
Number of model parameters	8

Number of observations 200

Model Test User Model:

Test statistic	0.140
Degrees of freedom	2
P-value (Chi-square)	0.932

## Parameter Estimates:

Standard errors	Standard
Information	Expected
Information saturated (h1) model	Structured

## Latent Variables:

	ESCIMACE	Stu.EII	z-varue	P(/ 2 )
f =~				
y1	1.000			
y2	0.996	0.123	8.122	0.000
у3	0.894	0.116	7.689	0.000

## Regressions:

	Docamacc	DCG. DII	z varac	- (-   -   /
y4 ~				
f	0.911	0.120	7.608	0.000

#### Variances:

	Estimate	Sta.Err	z-value	P(> Z )
. y1	1.096	0.148	7.388	0.000
. y2	0.837	0.127	6.601	0.000
. y3	0.987	0.128	7.694	0.000
. y4	1.081	0.138	7.820	0.000
f	1.031	0.208	4.959	0.000

# change outcome variable (y4 becomes z) (model3)

```
> model3 <- '
    f = "y1 + y2 + y3
    z " f
'
> fit3 <- sem(model3, data = Data)
> summary(fit3)
```

lavaan 0.6-20.2234 ended normally after 58 iterations

Estimator	ML
Optimization method	NLMINB
Number of model parameters	8

Number of observations 200

Model Test User Model:

Test statistic	50.659
Degrees of freedom	2
P-value (Chi-square)	0.000

## Parameter Estimates:

Standard errors	Standard
Information	Expected
Information saturated (h1) model	Structured

## Latent Variables:

	Estimate	Std.Eff	z-varue	P(> Z )
f =~				
y1	1.000			
y2	0.138	0.053	2.601	0.009
<b>y</b> 3	0.133	0.051	2.591	0.010

## Regressions:

		Estimate	Sta.Err	z-value	P(> Z )
z	~				
	f	0.276	0.087	3.156	0.002

#### Variances:

	Estimate	Std.Err	z-value	P(> z )
.y1	-4.169	1.801	-2.315	0.021
. y2	1.740	0.173	10.071	0.000
. y3	1.699	0.168	10.086	0.000
. z	1.677	0.211	7.953	0.000
f	6.296	1.715	3.671	0.000

# interpretational confounding

- replacing  $y_4$  by z (= changing the structural part) also changes the parameters of the measurement model
- if the resulting parameters of the measurement model imply a different 'meaning' of the latent variable than was intended by the researcher, we have a problem
- this problem was coined "interpretational confounding" by Burt (1976)
  - Burt, R.S. (1976). Interpretational confounding of unobserved variables in structural equation models. *Sociological Methods & Research*, *5*(1), 3–52.
- Burt (1976) already suggested the solution: first fit the measurement part of the model, and then fit the structural part of the model

# solution: replace sem() by sam()

- > fit3.sam <- sam(model3, data = Data)</pre>

## Latent Variables:

	Step E	stimate	Sta.Err	z-value	P(> Z )
f =~	_				
y1	1	1.000			
y2	1	0.969	0.139	6.977	0.000
у3	1	0.884	0.127	6.979	0.000

## Regressions:

		Step	Estimate	Std.Err	z-value	P(> z )
z	~					
	f	2	0.540	0.121	4.471	0.000

## Variances:

	Step	Estimate	Std.Err	z-value	P(> z )
. y1	1	1.067	0.170	6.287	0.000
. y2	1	0.865	0.151	5.723	0.000
. y3	1	0.983	0.142	6.900	0.000
. <b>z</b>	2	1.846	0.195	9.462	0.000
f	2	1.059	0.226	4.678	0.000

# the structural-after-measurement (SAM) approach

- SAM is an umbrella term to describe many different (estimation) approaches that have the following in common:
  - first step: we estimate the parameters related to the measurement part
  - second step: we estimate the parameters related to the structural part
- the term SAM was used by Rosseel & Loh (2024), to avoid the overloaded terms 'two-step', 'two-stage', ...
- various SAM approaches have been suggested in the literature:
  - early references: Burt (1976), Hunter & Gerbing (1982), Lance, Cornwell & Mulaik (1988)
  - (uncorrected and bias-corrected) factor score regression (FSR)
  - SAM is the default approach in many other fields
- ...but they never received much attention in the SEM literature/community
- Rosseel & Loh (2024) proposed a special case: 'local SAM' (LSAM)

## local SAM: rationale

the measurement model:

$$y = 
u + \Lambda \eta + \epsilon$$

• to solve this for  $\eta$ , we proceed as follows:

$$egin{aligned} 
u + \Lambda \, \eta + \epsilon &= y \ & \Lambda \, \eta &= y - 
u - \epsilon \ & ext{M} \Lambda \, \eta &= ext{M} \left[ y - 
u - \epsilon 
ight] \ & \eta &= ext{M} \left[ y - 
u - \epsilon 
ight] \end{aligned}$$

where M is  $M \times P$  mapping matrix such that  $M\Lambda = I_M$ 

• we assume  $E(\epsilon) = 0$  and write  $Var(\epsilon) = \Theta$ ; it follows that

$$\mathbf{E}(\boldsymbol{\eta}) = \mathbf{M} \left[ \mathbf{E}(\boldsymbol{y}) - \boldsymbol{\nu} \right]$$
  
 $\mathbf{Var}(\boldsymbol{\eta}) = \mathbf{M} \left[ \mathbf{Var}(\boldsymbol{y}) - \boldsymbol{\Theta} \right] \mathbf{M}^T$ 

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## local SAM: estimation

• first stage: estimation of the measurement part of the model (only)

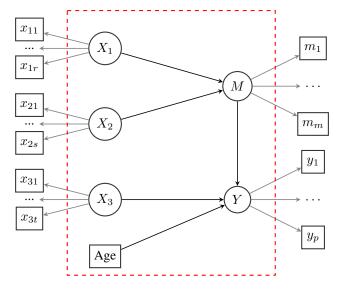
- this results in estimates of:
  - $E(\eta)$ : the mean vector of the latent variables
  - $Var(\eta)$ : the variance-covariance matrix of the latent variables
  - $\Gamma(\eta)$  ('Gamma'): capturing the sampling variability of these sample statistics
- second stage: a regression or path analysis is performed, using the sample statistics of the latent variables as input
  - twostep-corrected standard errors and fit measures
  - we can use ML, GLS, ... or we can use noniterative estimators (OLS, TSLS)
- typical choice for the mapping matrix: the 'ML/Bartlett' matrix

$$\mathbf{M} = (\mathbf{\Lambda}^T \mathbf{\Theta}^{-1} \mathbf{\Lambda})^{-1} \mathbf{\Lambda}^T \mathbf{\Theta}^{-1}$$

# example: generate population data mediation model

```
> library(lavaan)
> pop.model <- '
     # factor loadings
     Y = 1*y1 + 1.2*y2 + 0.8*y3 + 0.5*y4
    M = 1*m1 + 0.5*m2 + 0.5*m3 + 0.7*m4
    X1 = 1*x1 + 0.7*x2 + 0.6*x3 + 1.1*x4
    X2 = 1*x5 + 0.7*x6 + 0.6*x7 + 0.9*x8
    X3 = 1*x9 + 0.7*x10 + 0.6*x11 + 1.1*x12
     # covariances among exogenous X1-X3
    X1 ~~ 0.4*X2; X1 ~~ -0.2*X3; X2 ~~ 0.4*X3
     # regression part
     Y \sim 0.25*X3 + 0.4*M + (-0.1)*Age
    M^{\sim} -0.30*X1 + 1.1*X2
> set.seed(1234)
> Data <- simulateData(pop.model, sample.nobs = 200L, empirical = TRUE)
```

# example: diagram



# example: fitting the model using traditional SEM

```
> model <- '
     # measurement part
     Y = v1 + v2 + v3
                         + v4
    M = m1 + m2 + m3 + m4
    X1 = x1 + x2 + x3 + x4
    X2 = x5 + x6 + x7 + x8
    X3 = x9 + x10 + x11 + x12
     # structural part
     Y \sim X3 + M + Aae
    M ~ X1 + X2
> fit.sem <- sem(model, data = Data, estimator = "ML")</pre>
> parameterEstimates(fit.sem, ci = FALSE, output = "text")[21:25,]
Regressions:
                  Estimate Std.Err z-value P(>|z|)
 Y ~
                                      2.308
   X3
                     0.250
                              0.108
                                               0.021
   м
                     0.400
                              0.079
                                      5.078
                                               0.000
                                               0.229
                    -0.100
                              0.083
                                     -1.203
    Age
   X1
                    -0.300
                              0.133
                                     -2.258
                                               0.024
   X2
                              0.165
                                      6.670
                     1.100
                                               0.000
```

# example: model-implied variance-covariance matrix latent variables

> lavInspect(fit.sem, "cov.lv")

	Y	М	X1	X2	х3
Y	1.498				
М	0.939	2.036			
X1	0.006	0.140	1.000		
X2	0.492	0.980	0.400	1.000	
х3	0.450	0.500	-0.200	0.400	1.000

# example: fit measurement blocks, using B=M

```
> fit.Y < -sem('Y = v1 + v2 + v3 + v4', data = Data)
> fit.M < - sem('M = m1 + m2 + m3 + m4', data = Data)
> fit.X1 < - sem('X1 = x1 + x2 + x3 + x4', data = Data)
> fit.X2 < - sem('X2 = x5 + x6 + x7 + x8', data = Data)
> fit.X3 < - sem('X3 = x9 + x10 + x11 + x12', data = Data)
> # assemble Lambda and Theta
> Lambda <- matrix(0, 20, 5)</pre>
> Lambda[ 1:4, 1] <- lavInspect(fit.Y, "est")$lambda</pre>
> Lambda[ 5:8, 21 <- lavInspect(fit.M, "est")$lambda</pre>
> Lambda[ 9:12, 3] <- lavInspect(fit.X1, "est")$lambda</pre>
> Lambda[13:16, 4] <- lavInspect(fit.X2,</pre>
                                          "est") $lambda
> Lambda[17:20, 5] <- lavInspect(fit.X3, "est")$lambda</pre>
> Theta <- lav matrix bdiaq(lavInspect(fit.Y, "est")$theta,
                           lavInspect(fit.M.
                                               "est") $theta.
                           lavInspect(fit.X1,
                                               "est")$theta,
                           lavInspect(fit.X2,
                                               "est") $theta,
                           lavInspect(fit.X3, "est")$theta)
```

# example: compute ML version of the mapping matrix M

```
> Theta.inv <- solve(Theta)
> M <- solve(t(Lambda) %*% Theta.inv %*% Lambda) %*% t(Lambda) %*% Theta.inv
> # add age
       <- lav matrix bdiaq(M, matrix(1, nrow = 1L, ncol = 1L))</pre>
> Theta <- law matrix bdiag(Theta, matrix(0, nrow = 1L, ncol = 1L))
> rownames(M) <- c("Y", "M", "X1", "X2", "X3", "Age")
> # compute (biased) sample covariance matrix 'S'
> N <- nrow(Data)</pre>
> S <- cov(Data) * (N - 1L)/N
> # compute Var(Eta)
> Var.eta <- M %*% (S - Theta) %*% t(M)
> round(Var.eta, 3)
                    X1
                          X2
                                х3
                                    Age
Υ
    1.498 0.939 0.006 0.492 0.45 -0.1
M
    0.939 2.036 0.140 0.980 0.50 0.0
X1
    0.006 0.140 1.000 0.400 -0.20 0.0
X2 0.492 0.980 0.400 1.000 0.40 0.0
X3
    0.450 0.500 -0.200 0.400 1.00 0.0
Age -0.100 0.000 0.000 0.000 0.00 1.0
```

# example: second stage – using OLS

```
> # compute regression coefficients for M
> beta.M <- ( solve(Var.eta[c("X1", "X2"), c("X1", "X2")]) ***
             Var.eta[c("X1", "X2"), "M", drop = FALSE])
> round(beta.M, 3)
     М
x1 - 0.3
X2 1.1
> # compute regression coefficients for Y
> beta.Y <- ( solve(Var.eta[c("X3", "M", "Age"), c("X3", "M", "Age")]) %*%
             Var.eta[c("X3", "M", "Age"), "Y", drop = FALSE])
> round(beta.Y, 3)
        Y
x3
     0.25
M
     0.40
Age -0.10
```

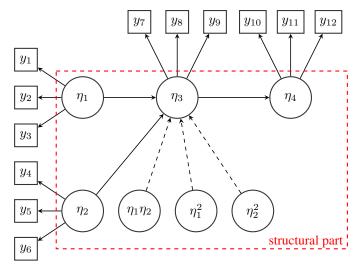
# example: using the sam() function

```
> fit.lsam <- sam(model = model, data = Data)
> parameterEstimates(fit.lsam, ci = FALSE, output = "text")[1:5,]
```

#### Regressions:

		Estimate	Std.Err	z-value	P(> z )
Y	~				
	х3	0.250	0.109	2.301	0.021
	M	0.400	0.080	4.971	0.000
	Age	-0.100	0.083	-1.203	0.229
М	~ _				
	X1	-0.300	0.133	-2.251	0.024
	X2	1.100	0.176	6.235	0.000

# application 1: adding latent quadratic and interaction terms



# application 1: adding latent quadratic and interaction terms (2)

- in the joint setting, adding latent quadratic/interaction terms is not trivial
- two popular methods are the product-indicator (PI) approach, and the socalled 'Latent Moderated Structural Equations' (LMS) approach
- none of these scale well: they cannot handle many quadratic and latent interaction terms simultaneously
- but if you can decouple the measurement and structural part, this becomes feasible
- a very general SAM solution (allowing for polynomial relations between latent variables) was already described in Wall & Amemiya (2000)
- the local SAM approach: find an explicit expression for

$$E(\boldsymbol{\eta} \otimes \boldsymbol{\eta})$$
 and  $Var(\boldsymbol{\eta} \otimes \boldsymbol{\eta})$ 

where  $\otimes$  denotes the tensor (or Kronecker) product

# local SAM and interaction/quadratic terms

- creating the 'augmented' vector  $\eta\otimes\eta$ :
- several elements are duplicated
- · based on the model, we select what we need

$$oldsymbol{\eta} = \left(egin{array}{c} 1 \ \eta_1 \ \eta_2 \ \eta_3 \end{array}
ight)$$

$$\eta \otimes \eta =$$

1	١	/ 1	١
$\eta_1$		$\eta_1$	
$\eta_2$		$\eta_2$	
$\eta_3$		$\eta_3$	
$\eta_1 1$		$\eta_1$	
$\eta_1\eta_1$		$\eta_1^2$	
$\eta_1\eta_2$		$\eta_1\eta_2$	
$\eta_1\eta_3$	_	$\eta_1\eta_3$	
$\eta_2 1$	-	$\eta_2\eta_1$	
$\eta_2\eta_1$		$\eta_2$	
$\eta_2\eta_2$		$\eta_2^2$	
$\eta_2\eta_3$		$\eta_2\eta_3$	
$\eta_3 1$		$\eta_3$	
$\eta_3\eta_1$		$\eta_3\eta_1$	
$\eta_3\eta_2$		$\eta_3\eta_2$	
$\eta_3\eta_3$ )	/	$\eta_3^2$	,

# the augmented (latent) sample statistics

augmented mean vector:

$$E(\boldsymbol{\eta} \otimes \boldsymbol{\eta}) = \text{vec}[\text{Var}(\boldsymbol{\eta})] + E(\boldsymbol{\eta}) \otimes E(\boldsymbol{\eta})$$

• augmented variance-covariance matrix (simple version, assuming normality for the measurement error):

$$Var(\boldsymbol{\eta} \otimes \boldsymbol{\eta}) \approx Var(\mathbf{f} \otimes \mathbf{f}) - \left[ \mathbf{Q} + \mathbf{K}_m \mathbf{Q} + \mathbf{Q} \mathbf{K}_m^T + \mathbf{K}_m \mathbf{Q} \mathbf{K}_m^T + \mathbf{\Gamma}_{22}^{\star (NT)}(\mathbf{r}) \right]$$

where

$$\mathbf{Q} = \operatorname{Var}(\boldsymbol{\eta}) \otimes \operatorname{Var}(\mathbf{r}) + \operatorname{E}(\boldsymbol{\eta}) \operatorname{E}(\boldsymbol{\eta})^T \otimes \operatorname{Var}(\mathbf{r})$$

and

$$\Gamma_{22}^{\star (NT)}(\mathbf{r}) = (\mathbf{I}_{m^2} + \mathbf{K}_m) \left( \text{Var}(\mathbf{r}) \otimes \text{Var}(\mathbf{r}) \right)$$

- $\mathbf{K}_m$  is the commutation matrix
- $\Gamma_{22}^{\star (NT)}(\mathbf{r})$  is the 'Gamma' matrix of the measurement error (r)

# implementation in lavaan

```
> model <- '
    # measurement part
    f1 = ~ y1 + y2 + y3
    f2 = ~ y4 + y5 + y6
    f3 = ~ y7 + y8 + y9

    # structural part
    f3 ~ f1 + f2 + f1:f1 + f2:f2 + f1:f2

/ 
/ 
/ 
/ fit <- sam(model, data = Data, se = "none") # or se = "bootstrap"</pre>
```

- no two-step analytic standard errors yet; but bootstrapping is possible
- forthcoming paper:

Rosseel, Y., Burghgraeve, E., Loh, W.W., Schermelleh-Engel, K. (in press). Structural after Measurement (SAM) approaches for accommodating latent quadratic and interaction effects. *Behavior Research Methods*.

# application 2: noniterative SEM

• for CFA, many noniterative estimators are available; some (i.e., the multiple group method) perform better than ML in terms of mean squared error

Dhaene, S. & Rosseel, Y. (2023). An Evaluation of Non-Iterative Estimators in Confirmatory Factor Analysis. *Structural Equation Modeling:* A Multidisciplinary Journal.

• we can use these noniterative estimators for the measurement part in SAM

Dhaene, S., & Rosseel, Y. (2023). An Evaluation of Non-Iterative Estimators in the Structural after Measurement (SAM) Approach to Structural Equation Modeling (SEM). *Structural Equation Modeling: A Multidisciplinary Journal*, 30(6), 926–940

• "[the] local SAM approach outperforms traditional SEM in small to moderate samples (both in terms of convergence and MSE values), especially when reliability drops."

# application 3: comparing structural relations across many groups

• reference (open access):

Perez Alonso, A.F., Rosseel, Y., Vermunt, J.K., & De Roover, K. (in press). Mixture Multigroup Structural Equation Modeling: A Novel Method for Comparing Structural Relations Across Many Groups. *Psychological Methods*. https://doi.org/10.1037/met0000667

- relationships between latent variables are often different across groups (e.g., countries); but some groups may be similar in the sense that they have similar values for the regression coefficients
- we like to 'discover' these hidden clusters of similar groups
- in a first step, we estimated the measurement part across all groups (fixing the factor loadings to be the same across groups); this resulted in (model-implied) latent (co)variance matrices for all the groups
- in a second step, a mixture modeling approach is used to find homogeneous clusters that share similar regression coefficients

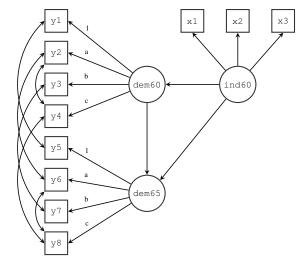
# **SAM:** software implementation

- the SAM approach has been implemented in the sam() function in the R
  package lavaan
- available methods:

```
- sam.method = "local" (default)
- sam.method = "global"
- sam.method = "fsr" (using Bartlett factor scores)
```

• typical call:

# diagram of the Political Democracy model



# sam() output

```
> # just for illustration, we also show the estimated parameters
> # of the measurement blocks
> #
> summary(fit.sam, remove.step1 = FALSE)
This is lavaan 0.6-20.2234 -- using the SAM approach to SEM
 SAM method
                                                 LOCAL
 Mapping matrix M method
                                                    MT.
 Number of measurement blocks
 Estimator measurement part
                                                    ML
 Estimator structural part
                                                   GT.S
 Number of observations
                                                    75
Summary Information Measurement + Structural:
 Block
            Latent Nind Chisq Df
             ind60
                       3 0.00 0
     2 dem60, dem65
                       8 15.32 16
 Model-based reliability latent variables:
 ind60 dem60 dem65
```

0.966 0.868 0.87

## Summary Information Structural part:

chisq df cfi rmsea srmr 0 0 1 0 0

#### Parameter Estimates:

Standard errors Twostep
Information Expected
Information saturated (h1) model Structured

#### Latent Variables:

		Step	Estimate	Std.Err	z-value	P(> z )
ind60 =~						
x1		1	1.000			
<b>x</b> 2		1	2.193	0.142	15.403	0.000
<b>x</b> 3		1	1.824	0.153	11.883	0.000
dem60 =						
y1		1	1.000			
y2	(a)	1	1.213	0.143	8.483	0.000
у3	(b)	1	1.210	0.125	9.690	0.000
y4	(c)	1	1.273	0.122	10.453	0.000
dem65 =						
<b>y</b> 5		1	1.000			
y6	(a)	1	1.213	0.143	8.483	0.000
<b>y</b> 7	(b)	1	1.210	0.125	9.690	0.000
у8	(c)	1	1.273	0.122	10.453	0.000

Regressions:					
	Step	Estimate	Std.Err	z-value	P(> z )
dem60 ~					
ind60	2	1.454	0.389	3.741	0.000
dem65 ~					
ind60	2			2.480	
dem60	2	0.871	0.076	11.497	0.000
Covariances:					
	Step	Estimate	Std.Err	z-value	P(> z )
.y1 ~~					
. <b>y</b> 5	1	0.577	0.364	1.585	0.113
.y2 ~~					
. y4	1	1.390			
.y6	1	2.068	0.733	2.822	0.005
.y3 ~~					
. y7	1	0.727	0.611	1.190	0.234
. y4 ~~	-				
. у8	1	0.476	0.453	1.049	0.294
. y6 ~~	1	1 057	0 500	0 156	0 001
. у8	1	1.257	0.583	2.156	0.031
Variances:					
	Step	Estimate	Std.Err	z-value	P(> z )
.x1	1	0.084			
. x2	1	0.108			
. <b>x</b> 3	1				
.y1	1	1.879	0.431	4.355	0.000

. y2	1	7.530	1.363	5.523	0.000
. y3	1	4.966	0.966	5.141	0.000
. y4	1	3.214	0.722	4.449	0.000
. y5	1	2.499	0.518	4.824	0.000
. y6	1	4.809	0.924	5.202	0.000
. y7	1	3.302	0.699	4.722	0.000
. y8	1	3.227	0.720	4.482	0.000
ind60	2	0.446	0.087	5.135	0.000
.dem60	2	3.766	0.848	4.439	0.000
.dem65	2	0.189	0.224	0.843	0.399

## last slide

- why should we decouple the measurement and structural part?
  - because we should (avoid interpretational confounding)
  - because we can (we can still do SEM)
  - this is what is done in most fields outside SEM
  - good performance in simulation studies (small/moderate sample sizes)
  - opens up modeling possibilities that were (computationally) difficult (if not impossible) in a joint estimation approach
- but still some obstacles:
  - analytic standard errors not always available (yet)
  - limitations (e.g., no higher-order measurement models)
  - more studies are needed to discover potential weaknesses
- the SAM approach deserves the (renewed) interest of the SEM community

Thank you!

(questions?)

https://lavaan.org

https://lavaan.ugent.be/about/donate.html

Department of Data Analysis Ghent University

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