

The ‘Structural After Measurement’ (SAM) approach to SEM

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paper

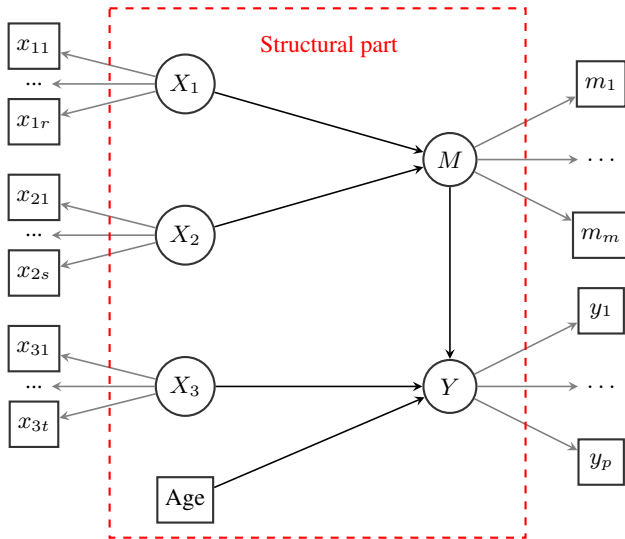
Rosseeel, Y., & Loh, W.W. (2024). A structural after measurement approach to structural equation modeling. *Psychological Methods*, 29(3), 561–588.

<https://doi.org/10.1037/met0000503>

slides

<https://lavaan.org>

the setting: structural equation models



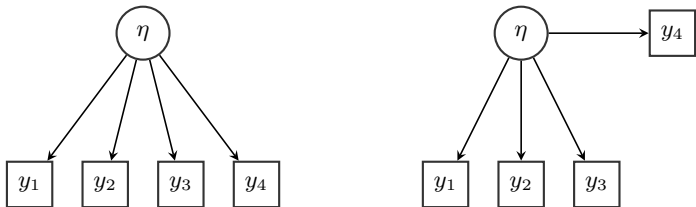
the setting (2)

- structural equation models
- we focus on ‘large’ models with many (say, > 100) parameters:
 - many constructs (motivation, ability, personality traits, ...)
 - each construct is measured by a set of (observed) indicators
 - many ‘background’ variables (age, gender, ...)
 - multilevel data, missing data, ...
- we are mostly interested in the structural part of the model:
 - regression model: variables are either dependent or independent
 - path analysis model: includes mediating effects, perhaps non-recursive
- assumption: the measurement instruments for the latent variables are well established, and usually fit (reasonably) well
- BUT: the sample size is not large (say, $N = 150$)

the standard estimation approach in SEM: 'system-wide' estimation

- all parameters (measurement and structural) are estimated jointly
- frequentist: typically using an iterative optimization approach (e.g., ML); Bayesian: typically using MCMC
- advantages:
 - one-step, and therefore efficient (in terms of sampling variability)
 - inference is straightforward (standard errors, hypothesis testing)
 - (relatively) easy to handle constraints, missing data, . . .
- works very well if the following conditions are met:
 - correctly specified model, large sample size
 - (normally distributed data)
- but under less ideal circumstances, system-wide estimation does not (always) work well (bias, instability, nonconvergence, improper solutions, . . .)
- in addition: combining 'structural' and 'measurement' may lead to interpretational confounding (the meaning of the latent variables changes, if the structural model changes)

example (stolen from Roy Levy, 2023)



- left panel: only measurement
- right panel: measurement + structural
- conceptually very different
- mathematically identical (in system-wide SEM)

generate some data

```
> library(lavaan)
> Sigma <- matrix(c(2.0, 1.0, 1.0, 1.0, 1.5,
                  1.0, 2.0, 1.0, 1.0, 0.1,
                  1.0, 1.0, 2.0, 1.0, 0.1,
                  1.0, 1.0, 1.0, 2.0, 0.1,
                  1.5, 0.1, 0.1, 0.1, 2.0), nrow = 5, ncol = 5)
> rownames(Sigma) <- colnames(Sigma) <- c("y1", "y2", "y3", "y4", "z")
> Sigma
```

```
      y1 y2 y3 y4 z
y1 2.0 1.0 1.0 1.0 1.5
y2 1.0 2.0 1.0 1.0 0.1
y3 1.0 1.0 2.0 1.0 0.1
y4 1.0 1.0 1.0 2.0 0.1
z  1.5 0.1 0.1 0.1 2.0
```

```
> set.seed(3)
> Data <- MASS::mvrnorm(n = 200L, mu = rep(0, 5), Sigma = Sigma)
```

R code left panel (model1)

```
> modell <- '  
  f =~ y1 + y2 + y3 + y4  
,  
> fit1 <- sem(modell, data = Data)  
> summary(fit1)
```

lavaan 0.6-20.2250 ended normally after 25 iterations

Estimator	ML
Optimization method	NLMINB
Number of model parameters	8
Number of observations	200

Model Test User Model:

Test statistic	0.140
Degrees of freedom	2
P-value (Chi-square)	0.932

Parameter Estimates:

Standard errors	Standard
Information	Expected
Information saturated (h1) model	Structured

Latent Variables:

	Estimate	Std.Err	z-value	P(> z)
f =~				
y1	1.000			
y2	0.996	0.123	8.122	0.000
y3	0.894	0.116	7.689	0.000
y4	0.911	0.120	7.608	0.000

Variances:

	Estimate	Std.Err	z-value	P(> z)
.y1	1.096	0.148	7.388	0.000
.y2	0.837	0.127	6.601	0.000
.y3	0.987	0.128	7.694	0.000
.y4	1.081	0.138	7.820	0.000
f	1.031	0.208	4.959	0.000

R code right panel (model2)

```
> model2 <- '
  f =~ y1 + y2 + y3
  y4 =~ f
',
> fit2 <- sem(model2, data = Data)
> summary(fit2)
```

lavaan 0.6-20.2250 ended normally after 26 iterations

Estimator	ML
Optimization method	NLMINB
Number of model parameters	8
Number of observations	200

Model Test User Model:

Test statistic	0.140
Degrees of freedom	2
P-value (Chi-square)	0.932

Parameter Estimates:

Standard errors	Standard
Information	Expected
Information saturated (h1) model	Structured

Latent Variables:

	Estimate	Std.Err	z-value	P(> z)
f = ~				
y1	1.000			
y2	0.996	0.123	8.122	0.000
y3	0.894	0.116	7.689	0.000

Regressions:

	Estimate	Std.Err	z-value	P(> z)
y4 ~				
f	0.911	0.120	7.608	0.000

Variances:

	Estimate	Std.Err	z-value	P(> z)
.y1	1.096	0.148	7.388	0.000
.y2	0.837	0.127	6.601	0.000
.y3	0.987	0.128	7.694	0.000
.y4	1.081	0.138	7.820	0.000
f	1.031	0.208	4.959	0.000

change outcome variable (y4 becomes z) (model3)

```
> model3 <- '
  f =~ y1 + y2 + y3
  z =~ f
',
> fit3 <- sem(model3, data = Data)
> summary(fit3)
```

lavaan 0.6-20.2250 ended normally after 58 iterations

Estimator	ML
Optimization method	NLMINB
Number of model parameters	8
Number of observations	200

Model Test User Model:

Test statistic	50.659
Degrees of freedom	2
P-value (Chi-square)	0.000

Parameter Estimates:

Standard errors	Standard
Information	Expected
Information saturated (h1) model	Structured

Latent Variables:

	Estimate	Std.Err	z-value	P(> z)
f = ~				
y1	1.000			
y2	0.138	0.053	2.601	0.009
y3	0.133	0.051	2.591	0.010

Regressions:

	Estimate	Std.Err	z-value	P(> z)
z ~				
f	0.276	0.087	3.156	0.002

Variances:

	Estimate	Std.Err	z-value	P(> z)
.y1	-4.169	1.801	-2.315	0.021
.y2	1.740	0.173	10.071	0.000
.y3	1.699	0.168	10.086	0.000
.z	1.677	0.211	7.953	0.000
f	6.296	1.715	3.671	0.000

interpretational confounding

- replacing y_4 by z (= changing the structural part) also changes the parameters of the measurement model
- if the resulting parameters of the measurement model imply a different ‘meaning’ of the latent variable than was intended by the researcher, we have a problem
- this problem was coined “interpretational confounding” by Burt (1976)

Burt, R.S. (1976). Interpretational confounding of unobserved variables in structural equation models. *Sociological Methods & Research*, 5(1), 3–52.

- Burt (1976) already suggested the solution: first fit the measurement part of the model, and then fit the structural part of the model

solution: replace sem() by sam()

```
> fit3.sam <- sam(model3, data = Data)
> parameterEstimates(fit3.sam, remove.step1 = FALSE, ci = FALSE,
  output = "text")
```

Latent Variables:

	Step	Estimate	Std.Err	z-value	P(> z)
f =~					
y1	1	1.000			
y2	1	0.969	0.139	6.977	0.000
y3	1	0.884	0.127	6.979	0.000

Regressions:

	Step	Estimate	Std.Err	z-value	P(> z)
z ~					
f	2	0.540	0.121	4.471	0.000

Variances:

	Step	Estimate	Std.Err	z-value	P(> z)
.y1	1	1.067	0.170	6.287	0.000
.y2	1	0.865	0.151	5.723	0.000
.y3	1	0.983	0.142	6.900	0.000
.z	2	1.846	0.195	9.462	0.000
f	2	1.059	0.226	4.678	0.000

the structural-after-measurement (SAM) approach

- SAM is an umbrella term to describe many different (estimation) approaches that have the following in common:
 - first step: we estimate the parameters related to the measurement part
 - second step: we estimate the parameters related to the structural part
- the term SAM was used by Rosseel & Loh (2024), to avoid the overloaded terms ‘two-step’, ‘two-stage’, ...
- various SAM approaches have been suggested in the literature:
 - early references: Burt (1976), Hunter & Gerbing (1982), Lance, Cornwell & Mulaik (1988)
 - (uncorrected and bias-corrected) factor score regression (FSR)
 - SAM is the default approach in many other fields
- ... but they never received much attention in the SEM literature/community
- Rosseel & Loh (2024) proposed a special case: ‘local SAM’ (LSAM)

local SAM: rationale

- the measurement model:

$$\mathbf{y} = \boldsymbol{\nu} + \mathbf{\Lambda}\boldsymbol{\eta} + \boldsymbol{\epsilon}$$

- to solve this for $\boldsymbol{\eta}$, we proceed as follows:

$$\boldsymbol{\nu} + \mathbf{\Lambda}\boldsymbol{\eta} + \boldsymbol{\epsilon} = \mathbf{y}$$

$$\mathbf{\Lambda}\boldsymbol{\eta} = \mathbf{y} - \boldsymbol{\nu} - \boldsymbol{\epsilon}$$

$$\mathbf{M}\mathbf{\Lambda}\boldsymbol{\eta} = \mathbf{M}[\mathbf{y} - \boldsymbol{\nu} - \boldsymbol{\epsilon}]$$

$$\boldsymbol{\eta} = \mathbf{M}[\mathbf{y} - \boldsymbol{\nu} - \boldsymbol{\epsilon}]$$

where \mathbf{M} is $M \times P$ mapping matrix such that $\mathbf{M}\mathbf{\Lambda} = \mathbf{I}_M$

- we assume $E(\boldsymbol{\epsilon}) = \mathbf{0}$ and write $\text{Var}(\boldsymbol{\epsilon}) = \boldsymbol{\Theta}$; it follows that

$$E(\boldsymbol{\eta}) = \mathbf{M}[E(\mathbf{y}) - \boldsymbol{\nu}]$$

$$\text{Var}(\boldsymbol{\eta}) = \mathbf{M}[\text{Var}(\mathbf{y}) - \boldsymbol{\Theta}]\mathbf{M}^T$$

local SAM: estimation

- first stage: estimation of the measurement part of the model (only)
- this results in estimates of:
 - $E(\boldsymbol{\eta})$: the mean vector of the latent variables
 - $\text{Var}(\boldsymbol{\eta})$: the variance-covariance matrix of the latent variables
 - $\Gamma(\boldsymbol{\eta})$ ('Gamma'): capturing the sampling variability of these sample statistics
- second stage: a regression or path analysis is performed, using the sample statistics of the latent variables as input
 - twostep-corrected standard errors and fit measures
 - we can use ML, GLS, ... or we can use noniterative estimators (OLS, TSLS)
- typical choice for the mapping matrix: the 'ML/Bartlett' matrix

$$\mathbf{M} = (\boldsymbol{\Lambda}^T \boldsymbol{\Theta}^{-1} \boldsymbol{\Lambda})^{-1} \boldsymbol{\Lambda}^T \boldsymbol{\Theta}^{-1}$$

application 1: adding latent quadratic and interaction terms (2)

- in the joint setting, adding latent quadratic/interaction terms is not trivial
- two popular methods are the product-indicator (PI) approach, and the so-called 'Latent Moderated Structural Equations' (LMS) approach
- none of these scale well: they cannot handle many quadratic and latent interaction terms simultaneously
- but if you can decouple the measurement and structural part, this becomes feasible
- a very general SAM solution (allowing for polynomial relations between latent variables) was already described in Wall & Amemiya (2000)
- the local SAM approach: find an explicit expression for

$$E(\boldsymbol{\eta} \otimes \boldsymbol{\eta}) \quad \text{and} \quad \text{Var}(\boldsymbol{\eta} \otimes \boldsymbol{\eta})$$

where \otimes denotes the tensor (or Kronecker) product

the augmented (latent) sample statistics

- augmented mean vector:

$$E(\boldsymbol{\eta} \otimes \boldsymbol{\eta}) = \text{vec}[\text{Var}(\boldsymbol{\eta})] + E(\boldsymbol{\eta}) \otimes E(\boldsymbol{\eta})$$

- augmented variance-covariance matrix (simple version, assuming normality for the measurement error):

$$\text{Var}(\boldsymbol{\eta} \otimes \boldsymbol{\eta}) \approx \text{Var}(\mathbf{f} \otimes \mathbf{f}) - \left[\mathbf{Q} + \mathbf{K}_m \mathbf{Q} + \mathbf{Q} \mathbf{K}_m^T + \mathbf{K}_m \mathbf{Q} \mathbf{K}_m^T + \boldsymbol{\Gamma}_{22}^{*(NT)}(\mathbf{r}) \right]$$

where

$$\mathbf{Q} = \text{Var}(\boldsymbol{\eta}) \otimes \text{Var}(\mathbf{r}) + E(\boldsymbol{\eta})E(\boldsymbol{\eta})^T \otimes \text{Var}(\mathbf{r})$$

and

$$\boldsymbol{\Gamma}_{22}^{*(NT)}(\mathbf{r}) = (\mathbf{I}_{m^2} + \mathbf{K}_m) (\text{Var}(\mathbf{r}) \otimes \text{Var}(\mathbf{r}))$$

- \mathbf{K}_m is the commutation matrix
- $\boldsymbol{\Gamma}_{22}^{*(NT)}(\mathbf{r})$ is the ‘Gamma’ matrix of the measurement error (\mathbf{r})

implementation in lavaan

```
> model <- '  
  # measurement part  
  f1 =~ y1 + y2 + y3  
  f2 =~ y4 + y5 + y6  
  f3 =~ y7 + y8 + y9  
  
  # structural part  
  f3 ~ f1 + f2 + f1:f1 + f2:f2 + f1:f2  
,  
> fit <- sam(model, data = Data, se = "none") # or se = "bootstrap"
```

- no two-step analytic standard errors yet; but bootstrapping is possible
- forthcoming paper:

Rosseel, Y., Burghgraeve, E., Loh, W.W., Schermelleh-Engel, K. (in press). Structural after Measurement (SAM) approaches for accommodating latent quadratic and interaction effects. *Behavior Research Methods*.

application 2: noniterative SEM

- for CFA, many noniterative estimators are available; some (i.e., the multiple group method) perform better than ML in terms of mean squared error

Dhaene, S. & Rosseel, Y. (2023). An Evaluation of Non-Iterative Estimators in Confirmatory Factor Analysis. *Structural Equation Modeling: A Multidisciplinary Journal*.

- we can use these noniterative estimators for the measurement part in SAM

Dhaene, S., & Rosseel, Y. (2023). An Evaluation of Non-Iterative Estimators in the Structural after Measurement (SAM) Approach to Structural Equation Modeling (SEM). *Structural Equation Modeling: A Multidisciplinary Journal*, 30(6), 926–940

- “[the] local SAM approach outperforms traditional SEM in small to moderate samples (both in terms of convergence and MSE values), especially when reliability drops. ”

application 3: comparing structural relations across many groups

- reference (open access):

Perez Alonso, A.F., Rosseel, Y., Vermunt, J.K., & De Roover, K. (in press). Mixture Multigroup Structural Equation Modeling: A Novel Method for Comparing Structural Relations Across Many Groups. *Psychological Methods*. <https://doi.org/10.1037/met0000667>

- relationships between latent variables are often different across groups (e.g., countries); but some groups may be similar in the sense that they have similar values for the regression coefficients
- we like to ‘discover’ these hidden clusters of similar groups
- in a first step, we estimated the measurement part across all groups (fixing the factor loadings to be the same across groups); this resulted in (model-implied) latent (co)variance matrices for all the groups
- in a second step, a mixture modeling approach is used to find homogeneous clusters that share similar regression coefficients

SAM: software implementation

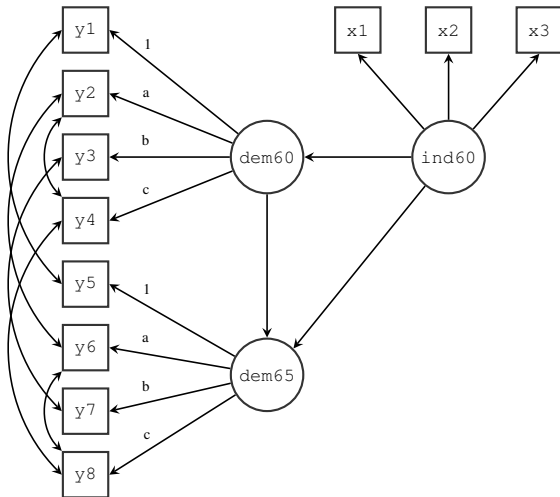
- the SAM approach has been implemented in the `sam()` function in the R package `lavaan`
- available methods:

- `sam.method = "local"` (default)
- `sam.method = "global"`
- `sam.method = "fsr"` (using Bartlett factor scores)

- typical call:

```
> fit.sam <- sam(model, data = PoliticalDemocracy,
  sam.method = "local",
  # link measurement blocks
  mm.list = list(ind = "ind60", dem = c("dem60", "dem65")),
  # measurement options
  mm.args = list(estimator = "ML"),
  # structural options
  struc.args = list(estimator = "GLS"),
  # global options
  meanstructure = FALSE)
```


diagram of the Political Democracy model



sam() output

```
> # just for illustration, we also show the estimated parameters
> # of the measurement blocks
> #
> summary(fit.sam, remove.step1 = FALSE)
```

This is lavaan 0.6-20.2250 -- using the SAM approach to SEM

SAM method	LOCAL
Mapping matrix M method	ML
Number of measurement blocks	2
Estimator measurement part	ML
Estimator structural part	GLS
Number of observations	75

Summary Information Measurement + Structural:

Block	Latent	Nind	Chisq	Df
1	ind60	3	0.00	0
2	dem60, dem65	8	15.32	16

Model-based reliability latent variables:

ind60	dem60	dem65
0.966	0.868	0.87

Summary Information Structural part:

```

chisq df cfi rmsea srmr
  0  0  1    0    0

```

Parameter Estimates:

```

Standard errors
Information
Information saturated (h1) model

Twostep
Expected
Structured

```

Latent Variables:

		Step	Estimate	Std.Err	z-value	P(> z)
ind60 =~						
x1		1	1.000			
x2		1	2.193	0.142	15.403	0.000
x3		1	1.824	0.153	11.883	0.000
dem60 =~						
y1		1	1.000			
y2	(a)	1	1.213	0.143	8.483	0.000
y3	(b)	1	1.210	0.125	9.690	0.000
y4	(c)	1	1.273	0.122	10.453	0.000
dem65 =~						
y5		1	1.000			
y6	(a)	1	1.213	0.143	8.483	0.000
y7	(b)	1	1.210	0.125	9.690	0.000
y8	(c)	1	1.273	0.122	10.453	0.000

Regressions:

	Step	Estimate	Std.Err	z-value	P(> z)
dem60 ~					
ind60	2	1.454	0.389	3.741	0.000
dem65 ~					
ind60	2	0.558	0.225	2.480	0.013
dem60	2	0.871	0.076	11.497	0.000

Covariances:

	Step	Estimate	Std.Err	z-value	P(> z)
.y1 ~~					
.y5	1	0.577	0.364	1.585	0.113
.y2 ~~					
.y4	1	1.390	0.685	2.030	0.042
.y6	1	2.068	0.733	2.822	0.005
.y3 ~~					
.y7	1	0.727	0.611	1.190	0.234
.y4 ~~					
.y8	1	0.476	0.453	1.049	0.294
.y6 ~~					
.y8	1	1.257	0.583	2.156	0.031

Variances:

	Step	Estimate	Std.Err	z-value	P(> z)
.x1	1	0.084	0.020	4.140	0.000
.x2	1	0.108	0.074	1.455	0.146
.x3	1	0.468	0.091	5.124	0.000
.y1	1	1.879	0.431	4.355	0.000
.y2	1	7.530	1.363	5.523	0.000

.y3	1	4.966	0.966	5.141	0.000
.y4	1	3.214	0.722	4.449	0.000
.y5	1	2.499	0.518	4.824	0.000
.y6	1	4.809	0.924	5.202	0.000
.y7	1	3.302	0.699	4.722	0.000
.y8	1	3.227	0.720	4.482	0.000
ind60	2	0.446	0.087	5.135	0.000
.dem60	2	3.766	0.848	4.439	0.000
.dem65	2	0.189	0.224	0.843	0.399

last slide

- why should we decouple the measurement and structural part?
 - because we should (avoid interpretational confounding)
 - because we can (we can still do SEM)
 - this is what is done in most fields outside SEM
 - good performance in simulation studies (small/moderate sample sizes)
 - opens up modeling possibilities that were (computationally) difficult (if not impossible) in a joint estimation approach
- but still some obstacles:
 - analytic standard errors not always available (yet)
 - limitations (e.g., no higher-order measurement models)
 - more studies are needed to discover potential weaknesses
- the SAM approach deserves the (renewed) interest of the SEM community

Thank you!

(questions?)

`https://lavaan.org`

`https://lavaan.ugent.be/about/donate.html`

references

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<https://osf.io/pekbm/> (includes original version)

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