

The East and Southeast Asia Workshop on Inverse Problems and Optimal Control (ESEAW: IPOC)

# EXISTENCE OF A WEAK SOLUTION TO A NONLINEAR INDUCTION HARDENING PROBLEM FOR A STEEL WORKPIECE

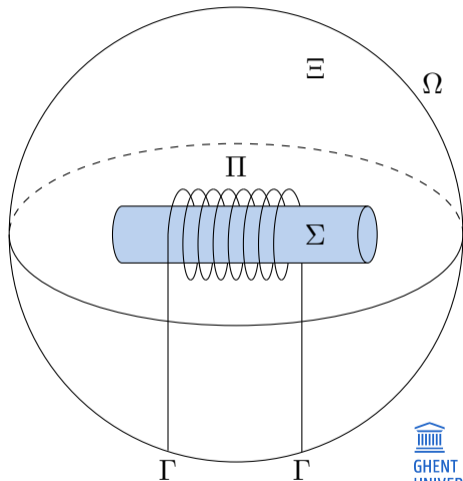
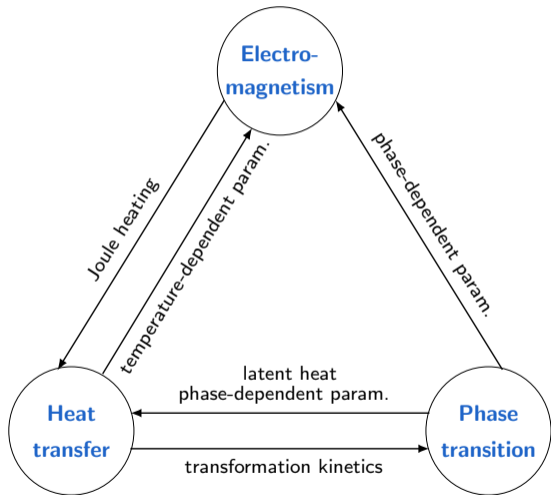
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# Outline

- 1 Mathematical model
- 2 Variational formulation
- 3 Time discretization
- 4 Existence of a solution

# Induction hardening



## Jumping material coefficients

The subscripts  $\Sigma$ ,  $\Pi$  and  $\Xi$  are used to distinguish the value of material coefficients on subdomains. For instances,

$$\mu = \begin{cases} \mu_{\Pi} & \text{in } \Pi, \\ \mu_{\Sigma} & \text{in } \Sigma, \\ \mu_{\Xi} & \text{in } \Xi. \end{cases} \quad \text{and} \quad \sigma = \begin{cases} \sigma_{\Pi} & \text{in } \Pi, \\ \sigma_{\Sigma} & \text{in } \Sigma, \\ 0 & \text{in } \Xi. \end{cases}$$

In general, material coefficients have jumps at the interfaces of different subdomains.

$$[[\mu]]_{\partial\Sigma} := \mu_{\Xi} - \mu_{\Sigma} \neq 0,$$

$$[[\mu]]_{\partial\Pi \setminus \Gamma} := \mu_{\Xi} - \mu_{\Pi} \neq 0.$$

# Electromagnetic subproblem

Maxwell's equations

$$\nabla \cdot \mathbf{B} = 0, \quad (\text{Gauss's law})$$

$$\nabla \times \mathbf{E} = -\partial_t \mathbf{B}, \quad (\text{Faraday's law})$$

$$\nabla \times \mathbf{H} = \mathbf{J}, \quad (\text{Ampère's law})$$

with the constitutive relations

$$\mathbf{B} = \mu \mathbf{H},$$

$$\mathbf{J} = \sigma \mathbf{E}. \quad (\text{Ohm's law})$$

Boundary condition

$$\mathbf{B} \cdot \mathbf{n} = 0.$$

Interface conditions

$$[[\mathbf{B} \cdot \mathbf{n}]] = 0, \quad [[\mathbf{H} \times \mathbf{n}]] = 0, \quad [[\mathbf{E} \times \mathbf{n}]] = 0.$$

## Nonlinear $B - H$ relation

Suppose that

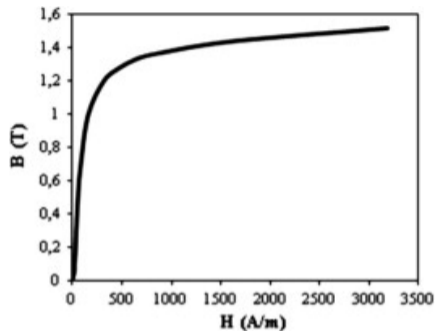
$$\mu_{\Sigma}(\mathbf{B}) = \hat{\mu}_{\Sigma} m^{-1}(|\mathbf{B}|),$$

then the magnetization curve

$$\mathbf{H} = \hat{\mu}^{-1} \mathbf{M}(\mathbf{B}),$$

where

$$\hat{\mu} = \begin{cases} \hat{\mu}_{\Sigma} & \text{in } \Sigma, \\ \mu & \text{in } \Pi \cup \Xi, \end{cases} \quad \text{and} \quad \mathbf{M}(\mathbf{b}) = \begin{cases} m(|\mathbf{b}|) \mathbf{b} & \text{in } \Sigma, \\ \mathbf{b} & \text{in } \Pi \cup \Xi. \end{cases}$$



## Assumptions on the function $m$

The function  $m : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is supposed to be differentiable and satisfy

$$m(s) + |m'(s)| s \leq C_M \quad \forall s \in \mathbb{R}^+.$$

In addition, for each  $s \in \mathbb{R}^+$ , one of the following conditions is satisfied

$$m(s) - |m'(s)| s \geq c_M > 0,$$

or

$$m(s) \geq c_M \quad \text{and} \quad m'(s) \geq 0.$$

### Lemma

*Under these assumptions, the nonlinear operator  $\mathbf{M}$  is strongly monotone, coercive and Lipschitz continuous.*

## $\mathbf{A} - \phi$ potential formulation

The BVP for the electric scalar potential  $\phi$

$$\begin{cases} \nabla \cdot (-\sigma_{\Pi} \nabla \phi) = 0 & \text{in } \Pi \times (0, T), \\ -\sigma_{\Pi} \nabla \phi \cdot \mathbf{n} = 0 & \text{on } (\partial\Pi \setminus \Gamma) \times (0, T), \\ -\sigma_{\Pi} \nabla \phi \cdot \mathbf{n} = j & \text{on } \Gamma \times (0, T). \end{cases}$$

The IBVP for the magnetic vector potential  $\mathbf{A}$  ( $\mathbf{B} := \nabla \times \mathbf{A}$ )

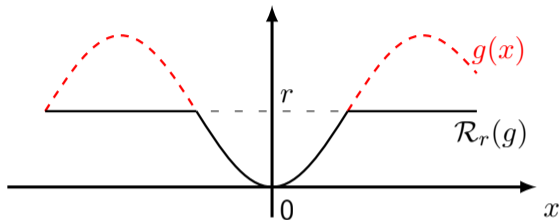
$$\begin{cases} \sigma \partial_t \mathbf{A} + \nabla \times \hat{\mu}^{-1} \mathbf{M}(\nabla \times \mathbf{A}) + \chi_{\Pi} \sigma \nabla \phi = \mathbf{0} & \text{in } \Omega \times (0, T), \\ \nabla \cdot \mathbf{A} = 0 & \text{in } \Omega \times (0, T), \\ \mathbf{A} \times \mathbf{n} = \mathbf{0} & \text{on } \partial\Omega \times (0, T), \\ \llbracket \hat{\mu}^{-1} \mathbf{M}(\nabla \times \mathbf{A}) \times \mathbf{n} \rrbracket = \mathbf{0} & \text{on } (\partial\Theta \setminus \Gamma) \times (0, T), \\ \mathbf{A}(\cdot, 0) = \mathbf{A}_0 & \text{in } \Theta := \Sigma \cup \Pi. \end{cases}$$



# Energy balance in the steel workpiece

The Joule heat caused by the eddy current

$$\mathbf{J} = \sigma_{\Sigma} |\partial_t \mathbf{A}|^2.$$



The IBVP for the temperature  $\mathcal{T}$

$$\begin{cases} \rho c_p(\mathcal{T}) \partial_t \mathcal{T} - \nabla \cdot (\kappa(\mathcal{T}) \nabla \mathcal{T}) = \mathcal{R}_r \left( \sigma_{\Sigma} |\partial_t \mathbf{A}|^2 \right) - \rho f(z, \mathcal{T}) \partial_t z & \text{in } \Sigma \times (0, T), \\ -\kappa(\mathcal{T}) \nabla \mathcal{T} \cdot \mathbf{n} = \alpha(\mathcal{T} - u^c) & \text{on } \partial \Sigma \times (0, T), \\ \mathcal{T}(\cdot, 0) = \mathcal{T}_0 & \text{in } \Sigma, \end{cases}$$

where

$$f(z, \mathcal{T}) = -L \left( z_{\text{eq}}(\mathcal{T}) - z - \mathcal{T} z'_{\text{eq}}(\mathcal{T}) \right).$$

# Kirchhoff transformation

We introduce the primitive function  $\hat{\kappa}$  from  $\kappa$

$$\hat{\kappa}(x) = \int_0^x \kappa(s) \, ds.$$

Let  $u := \hat{\kappa}(\mathcal{T})$  and  $u_0 := \hat{\kappa}(\mathcal{T}_0)$ . The IBVP for the transformed temperature  $u$

$$\begin{cases} \beta(\hat{\kappa}^{-1}(u))\partial_t u - \Delta u = \mathcal{R}_r \left( \sigma_\Sigma |\partial_t \mathbf{A}|^2 \right) - \rho f(z, \hat{\kappa}^{-1}(u))\partial_t z & \text{in } \Sigma \times (0, T), \\ -\nabla u \cdot \mathbf{n} = \alpha(\hat{\kappa}^{-1}(u) - u^c) & \text{on } \partial\Sigma \times (0, T), \\ u(\cdot, 0) = u_0 & \text{in } \Sigma. \end{cases}$$

# Leblond-Devaux model

Leblond-Devaux model for the austenite proportion  $z$

$$\begin{cases} \partial_t z = \frac{z_{\text{eq}}(\mathcal{T}) - z}{\vartheta(\mathcal{T})} & \text{in } \Sigma \times (0, T), \\ z(\cdot, 0) = z_0 = 0 & \text{in } \Sigma. \end{cases}$$

or with the transformed temperature  $u$

$$\begin{cases} \partial_t z = \frac{z_{\text{eq}}(\hat{\kappa}^{-1}(u)) - z}{\vartheta(\hat{\kappa}^{-1}(u))} & \text{in } \Sigma \times (0, T), \\ z(\cdot, 0) = z_0 = 0 & \text{in } \Sigma. \end{cases}$$

# Induction hardening problem

Electric potential  $\phi$

$$\begin{cases} \nabla \cdot (-\sigma_{\Pi} \nabla \phi) = 0, \\ -\sigma_{\Pi} \nabla \phi \cdot \mathbf{n} = 0, \\ -\sigma_{\Pi} \nabla \phi \cdot \mathbf{n} = j. \end{cases}$$

Magnetic potential  $\mathbf{A}$

$$\begin{cases} \sigma(z) \partial_t \mathbf{A} + \nabla \times \hat{\mu}^{-1} \mathbf{M}(\nabla \times \mathbf{A}) \\ \quad + \chi_{\Pi} \sigma \nabla \phi = \mathbf{0}, \\ \nabla \cdot \mathbf{A} = 0, \\ \mathbf{A} \times \mathbf{n} = \mathbf{0}, \\ \llbracket \hat{\mu}^{-1} \mathbf{M}(\nabla \times \mathbf{A}) \times \mathbf{n} \rrbracket = \mathbf{0}, \\ \mathbf{A}(\cdot, 0) = \mathbf{A}_0. \end{cases}$$

Temperature  $u$

$$\begin{cases} \beta(z, \hat{\kappa}^{-1}(u)) \partial_t u - \Delta u \\ \quad = \mathcal{R}_r \left( \sigma_{\Sigma}(z) |\partial_t \mathbf{A}|^2 \right) - \rho(z) f(z, \hat{\kappa}^{-1}(u)) \partial_t z, \\ -\nabla u \cdot \mathbf{n} = \alpha(\hat{\kappa}^{-1}(u) - u^c), \\ u(\cdot, 0) = u_0. \end{cases}$$

Austenite proportion  $z$

$$\begin{cases} \partial_t z = \frac{z_{\text{eq}}(\hat{\kappa}^{-1}(u)) - z}{\vartheta(\hat{\kappa}^{-1}(u))}, \\ z(\cdot, 0) = z_0 = 0. \end{cases}$$

# Function spaces

Let us introduce the following Hilbert spaces

$$Z := H^1(\Pi)/\mathbb{R},$$

$$\mathbf{W}_0 := \{ \mathbf{f} \in \mathbf{H}(\operatorname{div}, \Omega) \cap \mathbf{H}_0(\operatorname{curl}, \Omega) : \nabla \cdot \mathbf{f} = 0 \},$$

equipped with the norms

$$\|f\|_Z := \|\nabla f\|_{\mathbf{L}^2(\Pi)},$$

$$\|\mathbf{f}\|_{\mathbf{W}_0} := \|\nabla \times \mathbf{f}\|_{\mathbf{L}^2(\Omega)}.$$

**Remark:** The space  $\mathbf{W}_0$  is continuously embedded into  $\mathbf{H}^1(\Omega)$  if the domain  $\Omega$  is bounded and either the boundary  $\partial\Omega$  is of class  $C^{1,1}$  or  $\Omega$  is a convex polyhedron.

## Variational formulation

Find  $\phi \in \mathbf{Z}$ ,  $z \in L^2(\Sigma)$ ,  $\mathbf{A} \in \mathbf{W}_0$  and  $u \in H^1(\Sigma)$  such that

$$\sigma_{\Pi} (\nabla \phi, \nabla \psi)_{\Pi} + (j, \psi)_{\Gamma} = 0,$$

$$(\partial_t z, \varsigma)_{\Sigma} = \left( \frac{z_{\text{eq}}(\hat{\kappa}^{-1}(u)) - z}{\vartheta(\hat{\kappa}^{-1}(u))}, \varsigma \right)_{\Sigma},$$

$$(\sigma(z) \partial_t \mathbf{A}, \boldsymbol{\varphi})_{\Theta} + \left( \hat{\mu}^{-1} \mathbf{M}(\nabla \times \mathbf{A}), \nabla \times \boldsymbol{\varphi} \right)_{\Omega} + \sigma_{\Pi} (\nabla \phi, \boldsymbol{\varphi})_{\Pi} = 0,$$

$$\begin{aligned} & \left( \beta(z, \hat{\kappa}^{-1}(u)) \partial_t u, w \right)_{\Sigma} + (\nabla u, \nabla w)_{\Sigma} + \alpha \left( \hat{\kappa}^{-1}(u) - u^c, w \right)_{\partial \Sigma} \\ & = \left( \mathcal{R}_r \left( \sigma_{\Sigma}(z) |\partial_t \mathbf{A}|^2 \right), w \right)_{\Sigma} - \left( \rho(z) f(z, \hat{\kappa}^{-1}(u)) \partial_t z, w \right)_{\Sigma} \end{aligned}$$

are valid for any  $\psi \in \mathbf{Z}$ ,  $\varsigma \in L^2(\Sigma)$ ,  $\boldsymbol{\varphi} \in \mathbf{W}_0$  and  $w \in H^1(\Sigma)$ .

# Time discretization

Let  $[0, T]$  be partitioned into  $n$  equidistant subintervals with time step

$$\tau = \frac{T}{n}.$$

For any function  $v$ , we introduce the notations

$$v_i = v(t_i), \quad \delta v_i = \frac{v_i - v_{i-1}}{\tau},$$

which stand for the value of function  $v$  and the approximation of its time derivative at the time-point  $t_i := i\tau, i = 1, 2, \dots, n$ .

## Time discretization (cont.)

For every  $i = 1, 2, \dots, n$ , find  $\phi_i \in \mathbf{Z}$ ,  $z_i \in L^2(\Sigma)$ ,  $\mathbf{A}_i \in \mathbf{W}_0$  and  $u_i \in H^1(\Sigma)$  such that

$$\sigma_{\Pi} (\nabla \phi_i, \nabla \psi)_{\Pi} + (j_i, \psi)_{\Gamma} = 0,$$

$$(\delta z_i, \varsigma)_{\Sigma} = \left( \frac{z_{\text{eq}}(\hat{\kappa}^{-1}(u_{i-1})) - z_i}{\vartheta(\hat{\kappa}^{-1}(u_{i-1}))}, \varsigma \right)_{\Sigma},$$

$$(\sigma(z_i) \delta \mathbf{A}_i, \boldsymbol{\varphi})_{\Theta} + \left( \hat{\mu}^{-1} \mathbf{M}(\nabla \times \mathbf{A}_i), \nabla \times \boldsymbol{\varphi} \right)_{\Omega} + \sigma_{\Pi} (\nabla \phi_i, \boldsymbol{\varphi})_{\Pi} = 0,$$

$$\begin{aligned} & \left( \beta(z_i, \hat{\kappa}^{-1}(u_{i-1})) \delta u_i, w \right)_{\Sigma} + (\nabla u_i, \nabla w)_{\Sigma} + \alpha \left( \hat{\kappa}^{-1}(u_{i-1}) - u_i^c, w \right)_{\partial \Sigma} \\ & = \left( \mathcal{R}_r \left( \sigma_{\Sigma}(z_i) |\delta \mathbf{A}_i|^2 \right), w \right)_{\Sigma} - \left( \rho(z_i) f(z_i, \hat{\kappa}^{-1}(u_{i-1})) \delta z_i, w \right)_{\Sigma} \end{aligned}$$

are valid for any  $\psi \in \mathbf{Z}$ ,  $\varsigma \in L^2(\Sigma)$ ,  $\boldsymbol{\varphi} \in \mathbf{W}_0$  and  $w \in H^1(\Sigma)$ .



# Solvability of the discretized problem

## Lemma

*There exists a unique solution  $(\phi_i, z_i, \mathbf{A}_i, u_i) \in \mathbf{Z} \times L^2(\Sigma) \times \mathbf{W}_0 \times H^1(\Sigma)$  to the discretized variational problem for any  $i = 1, 2, \dots, n$ .*

*Proof:*

- The existence of a unique solution  $(\phi_i, z_i, u_i)$  is guaranteed by using the Lax-Milgram lemma.
- Thanks to the properties of the nonlinear operator  $\mathbf{M}$ , we invoke the Browder-Minty theorem to prove the existence of a unique solution  $\mathbf{A}_i$ .

# A priori estimates

## Lemma

There exists a constant  $C > 0$  such that

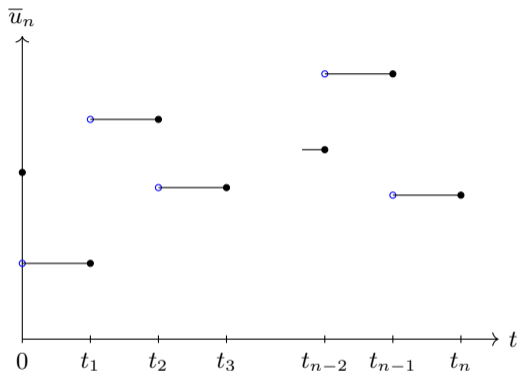
$$(i) \quad \max_{1 \leq l \leq n} \|\nabla \delta \phi_l\|_{\mathbf{L}^2(\Pi)} \leq C,$$

$$(ii) \quad 0 \leq z_i(\mathbf{x}) \leq 1, \quad |\delta z_i(\mathbf{x})| \leq C, \quad \max_{1 \leq l \leq n} \|\nabla z_l\|_{\mathbf{L}^2(\Sigma)} \leq C,$$

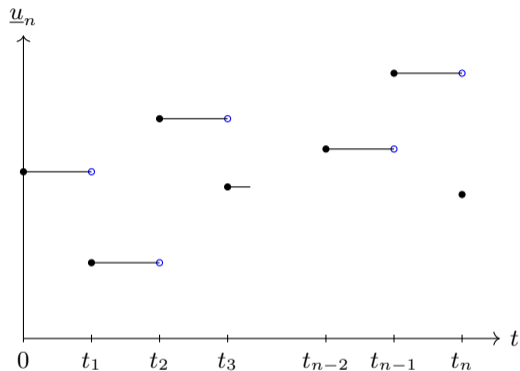
$$(iii) \quad \max_{1 \leq l \leq n} \|\delta \mathbf{A}_l\|_{\mathbf{L}^2(\Theta)}^2 + \sum_{i=1}^n \|\delta \mathbf{A}_i - \delta \mathbf{A}_{i-1}\|_{\mathbf{L}^2(\Theta)}^2 + \sum_{i=1}^n \|\nabla \times \delta \mathbf{A}_i\|_{\mathbf{L}^2(\Omega)}^2 \tau \leq C,$$

$$(iv) \quad \sum_{i=1}^n \|\delta u_i\|_{\mathbf{L}^2(\Sigma)}^2 \tau + \max_{1 \leq l \leq n} \|\nabla u_l\|_{\mathbf{L}^2(\Sigma)}^2 + \sum_{i=1}^n \|\nabla u_i - \nabla u_{i-1}\|_{\mathbf{L}^2(\Sigma)}^2 + \max_{1 \leq l \leq n} \|u_l\|_{\mathbf{L}^2(\partial \Sigma)}^2 \leq C.$$

# Rothe's piecewise constant in time functions

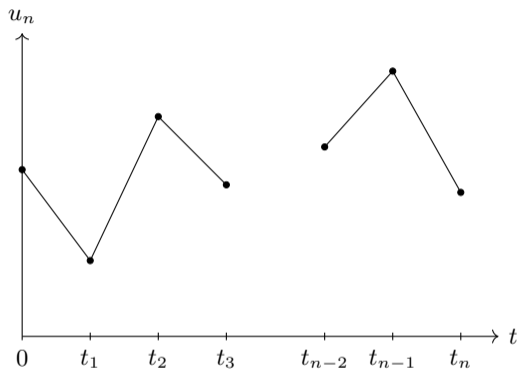


$$\bar{u}_n(t) = u_i, \quad t \in (t_{i-1}, t_i].$$



$$\underline{u}_n(t) = u_{i-1}, \quad t \in [t_{i-1}, t_i)$$

# Rothe's piecewise affine in time function



$$u_n(t) = u_{i-1} + (t - t_{i-1})\delta u_i, \quad t \in [t_{i-1}, t_i].$$

## Discretized problem in the continuous sense

The following identities are valid for any  $\psi \in \mathbf{Z}$ ,  $\varsigma \in L^2(\Sigma)$ ,  $\varphi \in \mathbf{W}_0$  and  $w \in H^1(\Sigma)$

$$\sigma_{\Pi} \left( \nabla \bar{\phi}_n, \nabla \psi \right)_{\Pi} + \left( \bar{j}_n, \psi \right)_{\Gamma} = 0,$$

$$\left( \partial_t z_n, \varsigma \right)_{\Sigma} = \left( \frac{z_{\text{eq}}(\hat{\kappa}^{-1}(\underline{u}_n)) - \bar{z}_n}{\vartheta(\hat{\kappa}^{-1}(\underline{u}_n))}, \varsigma \right)_{\Sigma},$$

$$\left( \sigma(\bar{z}_n) \partial_t \mathbf{A}_n, \varphi \right)_{\Theta} + \left( \hat{\mu}^{-1} \mathbf{M}(\nabla \times \bar{\mathbf{A}}_n), \nabla \times \varphi \right)_{\Omega} + \sigma_{\Pi} \left( \nabla \bar{\phi}_n, \varphi \right)_{\Pi} = 0,$$

$$\begin{aligned} & \left( \beta(\bar{z}_n, \hat{\kappa}^{-1}(\underline{u}_n)) \partial_t u_n, w \right)_{\Sigma} + \left( \nabla \bar{u}_n, \nabla w \right)_{\Sigma} + \alpha \left( \hat{\kappa}^{-1}(\underline{u}_n) - \bar{u}_n^c, w \right)_{\partial \Sigma} \\ & = \left( \mathcal{R}_r \left( \sigma(\bar{z}_n) |\partial_t \mathbf{A}_n|^2 \right), w \right)_{\Sigma} - \left( \rho(\bar{z}_n) f(\bar{z}_n, \hat{\kappa}^{-1}(\underline{u}_n)) \partial_t z_n, w \right)_{\Sigma}. \end{aligned}$$

# Existence of a weak solution

## Theorem

*There exists a weak solution*

$$(\phi, z, u, \mathbf{A}) \in \text{Lip}([0, T], Z) \times \left[ C([0, T], L^2(\Sigma)) \cap L^\infty((0, T), H^1(\Sigma)) \right]^2 \times C([0, T], \mathbf{W}_0)$$

*to the variational system. Moreover, the following convergences hold for subsequences*

$$\begin{array}{ll} \bar{\phi}_{n_k} \rightarrow \phi & \text{in } C([0, T], Z), \\ z_{n_k} \rightarrow z, \quad u_{n_k} \rightarrow u & \text{in } C([0, T], L^2(\Sigma)), \\ \partial_t z_{n_k} \rightarrow \partial_t z, \quad \partial_t u_{n_k} \rightarrow \partial_t u & \text{in } L^2((0, T), L^2(\Sigma)), \\ \bar{z}_{n_k} \rightarrow z, \quad \bar{u}_{n_k} \rightarrow u, \quad \underline{u}_{n_k} \rightarrow u & \text{in } L^2((0, T), L^2(\Sigma)), \\ \mathbf{A}_{n_k} \rightarrow \mathbf{A} & \text{in } C([0, T], \mathbf{L}^2(\Omega)), \\ \bar{\mathbf{A}}_{n_k} \rightarrow \mathbf{A}, \quad \partial_t \mathbf{A}_{n_k} \rightarrow \partial_t \mathbf{A} & \text{in } L^2((0, T), \mathbf{W}_0). \end{array}$$

# Reference



V. C. Le, M. Slodička, and K. Van Bockstal.

Existence of a weak solution to a nonlinear induction hardening problem with Leblond-Devaux model for a steel workpiece.

*Communications in Nonlinear Science and Numerical Simulation*, 107:106156, 2022.

# Conclusions

- A mathematical model has been introduced for the induction hardening process.
- A time discretization scheme has been proposed.
- Numerical analysis have been performed, and the existence of a weak solution has been proved.
- The uniqueness of a solution to the nonlinear induction hardening problem is still a challenge.



