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## The well-posedness of a mathematical model for an intermediate state between type-I and type-II superconductivity

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## Features of superconductivity

- Kammerlingh Onnes (1911): perfect conductivity


For various cooled down materials the electrical resistance not only decreases with temperature, but also has a sudden drop at some critical absolute temperature $T_{c}$

- Meissner and Ochsenfeld (1933): perfect diamagnetism
$\Rightarrow$ i.e. expulsion of the magnetic induction $\boldsymbol{B}$
- Kammerlingh Onnes (1914): threshold field
$\Rightarrow$ restore the normal state through the application of a large magnetic field
- A way to classify superconductors: type-I and type-II
- Similar behaviour for a very weak external magnetic field when the temperature $T<T_{c}$ is fixed
- As the external magnetic field becomes stronger it turns out that two possibilities can happen $\Rightarrow$ phase diagram in the $T-H$ plane

- Type-I (a): the $\boldsymbol{B}$ field remains zero inside the superconductor until suddenly, as the critical field $H_{c}$ is reached, the superconductivity is destroyed
- Type-II (b): a mixed state occurs in addition to the superconductive and the normal state (two different critical fields)
- What are the macroscopic models which are used in the modelling of type-I and type-II superconductors?


## Type-I

- $\Omega \subset \mathbb{R}^{3}$ : bounded Lipschitz domain, $\boldsymbol{\nu}$ unit normal vector on $\Gamma$
- The quasi-static Maxwell equations for linear materials are considered

| $\nabla \times \boldsymbol{H}=\boldsymbol{J}$ | Ampère's law | $\boldsymbol{H}$ | magnetic field |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| $\nabla \times \boldsymbol{E}=-\mu \partial_{t} \boldsymbol{H}$ | Faraday's law | $\boldsymbol{E}$ | electric field | $\mu>0$ | magnetic permeability |
| $\nabla \cdot \boldsymbol{H}_{0}=0$ |  | $\boldsymbol{J}$ | current density |  |  |

- London and London (1935): a macroscopic description of type-I superconductors involves a two-fluid model

$$
\begin{array}{lllll}
\boldsymbol{J} & =\boldsymbol{J}_{n}+\boldsymbol{J}_{s} & & \nabla \times \boldsymbol{H}=\sigma \boldsymbol{E}+\boldsymbol{J}_{s} & \boldsymbol{J}_{n} \\
\boldsymbol{J}_{n} & =\sigma \boldsymbol{E} & \text { Ohm's law } & \nabla \times \boldsymbol{E}=-\mu \partial_{t} \boldsymbol{H} & \boldsymbol{J}_{s}
\end{array} \text { superconducting current density }
$$

- Below the critical temperature $T_{c}$, the current consists of superconducting electrons and normal electrons

London equations (1935) $\Rightarrow$ local law for $J_{s}$

$$
\begin{aligned}
\partial_{t} \boldsymbol{J}_{s} & =\Lambda^{-1} \boldsymbol{E} \\
\nabla \times \boldsymbol{J}_{s} & =-\Lambda^{-1} \boldsymbol{B}
\end{aligned}
$$

$$
\Lambda=\frac{m_{e}}{n_{s} e^{2}} \quad-e \quad \text { electric charge of an electron }
$$

$\Rightarrow$ Correct description of two basic properties of superconductors: perfect conductivity and perfect diamagnetism (Meissner effect)

$$
\nabla \cdot \boldsymbol{B}=0 \Rightarrow \exists \boldsymbol{A} \text { such that } \boldsymbol{B}=\nabla \times \boldsymbol{A} \text { and } \nabla \cdot \boldsymbol{A}=0
$$

$$
\nabla \times \boldsymbol{J}_{s}=-\Lambda^{-1} \boldsymbol{B} \quad \Rightarrow \quad \boldsymbol{J}_{s}(x, t)=-\Lambda^{-1} \boldsymbol{A}(\boldsymbol{x}, t), \quad(x, t) \in \Omega \times(0, T)
$$

## Generalization of London and London: nonlocal laws

[Pippard, 1953]

$$
J_{s, p}(x, t)=\int_{\Omega} Q\left(x-x^{\prime}\right) \boldsymbol{A}\left(x^{\prime}, t\right) \mathrm{d} \boldsymbol{x}^{\prime}, \quad(x, t) \in \Omega \times(0, T)
$$

with

$$
\begin{aligned}
& Q\left(\boldsymbol{x}-\boldsymbol{x}^{\prime}\right) \boldsymbol{A}\left(\boldsymbol{x}^{\prime}, t\right)=-\widetilde{C} \frac{\boldsymbol{x}-\boldsymbol{x}^{\prime}}{\left|\boldsymbol{x}-\boldsymbol{x}^{\prime}\right|^{4}}\left[\boldsymbol{A}\left(\boldsymbol{x}^{\prime}, t\right) \cdot\left(\boldsymbol{x}-\boldsymbol{x}^{\prime}\right)\right] \exp \left(-\frac{\left|\boldsymbol{x}-\boldsymbol{x}^{\prime}\right|}{r_{0}}\right), \\
& \widetilde{C}:=\frac{3}{4 \pi \xi_{0} \Lambda}>0, \quad r_{0}:=\frac{\xi_{0} l}{\xi_{0}+l}
\end{aligned}
$$

$\xi_{0}$ the coherence length of the material, $I$ is the mean free path
[Eringen, 1984]

$$
\begin{aligned}
\boldsymbol{J}_{s, e}(\boldsymbol{x}, t)=\int_{\Omega} \sigma_{0}\left(\left|\boldsymbol{x}-\boldsymbol{x}^{\prime}\right|\right)\left(\boldsymbol{x}-\boldsymbol{x}^{\prime}\right) \times \boldsymbol{H}\left(\boldsymbol{x}^{\prime}, t\right) \mathrm{d} \boldsymbol{x}^{\prime}=: & -\left(\mathcal{K}_{0} \star \boldsymbol{H}\right)(\boldsymbol{x}, t), \\
& (\boldsymbol{x}, t) \in \Omega \times(0, T)
\end{aligned}
$$

with

$$
\sigma_{0}(s)= \begin{cases}\frac{\widetilde{C}}{2 s^{2}} \exp \left(-\frac{s}{r_{0}}\right) & s<r_{0} \\ 0 & s \geqslant r_{0}\end{cases}
$$

- Pippard's nonlocal law fails to explain the vanishing of electrical resistance
- It is possible to recover from Eringen's law the London equations and the form given by Pippard

$$
\Rightarrow \boldsymbol{J}_{s}=\boldsymbol{J}_{s, e}=-\mathcal{K}_{0} \star \boldsymbol{H} \quad \text { in } \quad \begin{cases}\nabla \times \boldsymbol{H} & =\sigma \boldsymbol{E}+\boldsymbol{J}_{s} \\ \nabla \times \boldsymbol{E} & =-\mu \partial_{t} \boldsymbol{H}\end{cases}
$$

- Taking the curl of Ampère's law result in

$$
\sigma \mu \partial_{t} \boldsymbol{H}+\nabla \times \nabla \times \boldsymbol{H}+\nabla \times\left(\mathcal{K}_{0} \star \boldsymbol{H}\right)=\mathbf{0}
$$

- Well-posedness is studied into detail in [Slodička and Van Bockstal, 2014].
- Also the error estimates for two time-discrete schemes (an implicit and a semi-implicit) based on backward Euler method are derived in [Slodička and Van Bockstal, 2014].


## Type-II

- Dependency between current density $\boldsymbol{J}$ and the electric field $\boldsymbol{E}$


Electric Field

- Ohm's law for non-superconducting metal (dashed)
- Bean's critical-state model for type-II superconductors (fine dashed): current either flows at the critical level $\boldsymbol{J}_{c}$ or not at all $\Rightarrow$ not fully applicable
- The power law by Rhyner for type-II superconductors (continuous)

$$
\boldsymbol{E}=\sigma_{c}^{-n}|\boldsymbol{J}|^{n-1} \boldsymbol{J}, \quad n \in(7,1000)
$$

- Take the curl of the power law and use Faraday's law $\Rightarrow$ nonlinear and degenerate partial differential equation for the magnetic field

$$
\mu \partial_{t} \boldsymbol{H}+\sigma_{c}^{-n} \nabla \times\left(|\nabla \times \boldsymbol{H}|^{n-1} \nabla \times \boldsymbol{H}\right)=\mathbf{0}
$$

- Studied by: [Barrett and Prigozhin, 2000, Yin et al., 2002, Prigozhin and Sokolovsky, 2004, Wei and Yin, 2005]
- The classification into type-I and type-II is insufficient for multiband superconductors [Babaev and Speight, 2005]
- This are superconductors with several superconducting components
- The material 'magnesium diboride' combines the characteristics of both types [Nagamatsu et al., 2001]
- New kind of superconductor: type-1.5 superconductors [Moshchalkov et al., 2009, Babaev et al., 2012]
- Allows coexistence of various properties of type-I and type-II superconductors


## Problem

Is it possible to derive macroscopic models for an intermediate state between type-I and type-Il superconductors?

- Type-I:

$$
\mu \partial_{t} \boldsymbol{H}+\sigma^{-1} \nabla \times \nabla \times \boldsymbol{H}+\sigma^{-1} \nabla \times\left(\mathcal{K}_{0} \star \boldsymbol{H}\right)=\mathbf{0}
$$

- Type-II $(n \in(7,1000))$ :

$$
\mu \partial_{t} \boldsymbol{H}+\sigma_{c}^{-n} \nabla \times\left(|\nabla \times \boldsymbol{H}|^{n-1} \nabla \times \boldsymbol{H}\right)=\mathbf{0}
$$

- By introducing a real parameter $\beta \geqslant 1$ and a real function $f(\beta)$, we propose to combine both equations to

$$
\begin{aligned}
\mu \partial_{t} \boldsymbol{H}+\sigma^{-1} f(\beta) \nabla \times \nabla \times \boldsymbol{H}+\sigma_{c}^{-\beta} g(\beta) & \nabla
\end{aligned} \begin{aligned}
& \left(|\nabla \times \boldsymbol{H}|^{\beta-1} \nabla \times \boldsymbol{H}\right) \\
& +\sigma^{-1} f(\beta) \nabla \times\left(\mathcal{K}_{0} \star \boldsymbol{H}\right)=\mathbf{0}
\end{aligned}
$$

with

- $f \in C([1, \infty))$ monotonically decreasing, $f(1)=1$ and $0 \leqslant f(\beta) \leqslant 1$ for $\beta>1$
- $f$ equals zero or is very small for $\beta>7$
- $g(\beta):=1-f(\beta)$
- Intermediate state: $1<\beta \leqslant 7$
- It is assumed (for simplicity) that $\mu=\sigma=\sigma_{c}=1$
- The aim of this paper is to address the well-posedness of the following problem for $\beta \geqslant 1$ :

$$
\left\{\begin{array}{rlll}
\partial_{t} \boldsymbol{H}+f(\beta) \nabla \times \nabla \times \boldsymbol{H}+g(\beta) \nabla \times\left(|\nabla \times \boldsymbol{H}|^{\beta-1} \nabla \times \boldsymbol{H}\right) & & \\
+f(\beta) \nabla \times\left(\mathcal{K}_{0} \times \boldsymbol{H}\right) & =\boldsymbol{F} & \text { in } \Omega \times(0, T) ; \\
\boldsymbol{H} \times \boldsymbol{\nu} & =\mathbf{0} & \text { on } \Gamma \times(0, T) ; \\
\boldsymbol{H}(\boldsymbol{x}, 0) & =\boldsymbol{H}_{0} & \text { in } \Omega ;
\end{array}\right.
$$

to design a numerical scheme for computations and to derive error estimates for the time discretization

- Some possible choices for $f$ :

$$
\begin{gathered}
f(\beta)=\left\{\begin{array}{ll}
\frac{(-1)^{\alpha}}{6^{\alpha}}(\beta-7)^{\alpha} & 1 \leqslant \beta \leqslant 7 \\
0 & \beta>7
\end{array}, \quad \alpha \in \mathbb{N}\right. \\
f(\beta)=\exp (-k \beta), \quad k \in \mathbb{R}^{+}
\end{gathered}
$$

- Focus on mathematical analysis, not on implementation.

Using spherical coordinates one can deduce that

- $\sigma_{0}(|\boldsymbol{x}|) \boldsymbol{x} \in \mathbf{L}^{p}(\Omega)$ for $p \in[1,3)$ :

$$
\begin{aligned}
\int_{\Omega}\left|\sigma_{0}(|x|) x\right|^{p} \mathrm{dx} \leqslant & \int_{B\left(0, r_{0}\right)} \frac{c}{\frac{1}{|x|^{2 p}}}\left|\exp \left(-\frac{|x|}{r_{0}}\right)\right|^{p}|x|^{p} \mathrm{dx} \\
& \leqslant c \int_{0}^{2 \pi} \mathrm{~d} \varphi \int_{0}^{\pi} \sin (\theta) \mathrm{d} \theta \int_{0}^{r_{0}} r^{2-p_{\mathrm{d} r} \leqslant c\left[\frac{r^{3-p}}{3-p}\right]_{0}^{r_{0}}<\infty}
\end{aligned}
$$

- $\left|\boldsymbol{J}_{s}(\boldsymbol{x}, t)\right|=\mid\left(\mathcal{K}_{0}\right.$ 大 $\left.\boldsymbol{H}\right)(\boldsymbol{x}, t) \mid \leqslant C(q)\|\boldsymbol{H}(t)\|_{q}$ for $q>\frac{3}{2}, \quad \forall \boldsymbol{x} \in \Omega$ :

$$
\begin{aligned}
\left|S_{s}(x, t)\right|=\mid & \left|\int_{\Omega} \sigma_{0}\left(\left|x-x^{\prime}\right|\right)\left(x-x^{\prime}\right) \times H\left(x^{\prime}, t\right) d x^{\prime}\right| \leqslant \int_{\Omega}\left|\sigma_{0}\left(\left|x-x^{\prime}\right|\right)\left(x-x^{\prime}\right)\right|\left|H\left(x^{\prime}, t\right)\right| d x^{\prime} \\
& \leqslant \sqrt[p]{\int_{\Omega}\left|\sigma_{0}\left(\left|x-x^{\prime}\right|\right)\left(x-x^{\prime}\right)\right|^{p} d x^{\prime}} \sqrt{\int_{\Omega}\left|H\left(x^{\prime}, t\right)\right| q \mathrm{~d} x^{\prime}} \leqslant c\|\boldsymbol{H}(t)\|_{q}
\end{aligned}
$$

- For instance, it holds that

$$
\left(\mathcal{K}_{0} \star \boldsymbol{h}, \nabla \times \boldsymbol{h}\right) \leqslant C_{\varepsilon}\|\boldsymbol{h}\|^{2}+\varepsilon\|\nabla \times \boldsymbol{h}\|^{2}, \quad \forall \boldsymbol{h} \in \mathbf{H}(\text { curl }, \Omega)
$$

The suitable choise for the space of test functions is

$$
\mathbf{V}_{0}=\left\{\varphi \in \mathbf{L}^{2}(\Omega): \nabla \times \varphi \in \mathbf{L}^{\beta+1}(\Omega) \text { and } \varphi \times \boldsymbol{\nu}=\mathbf{0} \text { on } \Gamma\right\} \subset \mathbf{H}_{0}(\text { curl }, \Omega) .
$$

This is a closed subspace of the space

$$
\mathbf{V}=\left\{\varphi \in \mathbf{L}^{2}(\Omega): \nabla \times \varphi \in \mathbf{L}^{\beta+1}(\Omega)\right\} \subset \mathbf{H}(\mathbf{c u r l}, \Omega)
$$

and is endowed with the same graph norm

$$
\|\boldsymbol{\varphi}\|_{\mathbf{V}}=\|\boldsymbol{\varphi}\|_{\mathbf{V}_{0}}=\|\boldsymbol{\varphi}\|_{\mathbf{L}^{2}(\Omega)}+\|\nabla \times \boldsymbol{\varphi}\|_{\mathbf{L}^{\beta+1}(\Omega)} .
$$

## Definition

Let $\beta \geqslant 1, \boldsymbol{H}_{0} \in \mathbf{V}$ and $\boldsymbol{F} \in \mathrm{L}^{2}\left((0, T), \mathbf{L}^{2}(\Omega)\right)$. The variational formulation of (14) reads as: find $\boldsymbol{H} \in C\left([0, T], \mathbf{L}^{2}(\Omega)\right)$ with $\nabla \times \boldsymbol{H} \in L^{\beta+1}\left((0, T), \mathbf{L}^{\beta+1}(\Omega)\right)$ and $\partial_{t} \boldsymbol{H} \in L^{2}\left([0, T], \mathbf{L}^{2}(\Omega)\right)$ such that

$$
\begin{aligned}
\left(\partial_{t} \boldsymbol{H}(t), \varphi\right)+f(\beta)(\nabla \times \boldsymbol{H}(t), \nabla \times \varphi) & +g(\beta)\left(|\nabla \times \boldsymbol{H}(t)|^{\beta-1} \nabla \times \boldsymbol{H}(t), \nabla \times \varphi\right) \\
& +f(\beta)\left(\mathcal{K}_{0} \star \boldsymbol{H}(t), \nabla \times \varphi\right)=(\boldsymbol{F}(t), \varphi), \quad \forall \varphi \in \mathbf{V}_{0}
\end{aligned}
$$

for a.e. $t \in[0, T]$.

## Lemma (reflexivity)

The vector spaces $\mathbf{V}$ and $\mathbf{V}_{0}$ are reflexive Banach spaces.

## Lemma (monotonicity)

Let $\beta \geqslant 1$. There exists a positive constant $C_{0}(\beta)=\frac{1}{4 \cdot 11^{\frac{\beta+1}{2}}}$ such that for any $\boldsymbol{H}_{1}, \boldsymbol{H}_{2} \in \mathbf{V}$ hold

$$
\begin{aligned}
\left(\left|\nabla \times \boldsymbol{H}_{1}\right|^{\beta-1} \nabla \times \boldsymbol{H}_{1}-\left|\nabla \times \boldsymbol{H}_{2}\right|^{\beta-1} \nabla\right. & \left.\times \boldsymbol{H}_{2}, \nabla \times\left(\boldsymbol{H}_{1}-\boldsymbol{H}_{2}\right)\right) \\
& \geqslant C_{0}(\beta)\left\|\nabla \times\left(\boldsymbol{H}_{1}-\boldsymbol{H}_{2}\right)\right\|_{\mathbf{L}^{\beta+1}(\Omega)}^{\beta+1}
\end{aligned}
$$

## Theorem (uniqueness)

The problem (14) admits at most one solution $\partial_{t} \boldsymbol{H} \in L^{2}\left([0, T], \mathbf{L}^{2}(\Omega)\right)$ with $\nabla \times \boldsymbol{H} \in L^{\beta+1}\left((0, T), \mathbf{L}^{\beta+1}(\Omega)\right)$ if $\boldsymbol{H}_{0} \in \mathbf{L}^{2}(\Omega)$.

Proof uniqueness:
$\overline{\text { Assume that we have two solutions } \boldsymbol{H}_{1} \text { and } \boldsymbol{H}_{2} \text {. Set } \boldsymbol{H}=\boldsymbol{H}_{1}-\boldsymbol{H}_{2} \text {. Subtract } 1 \text {. }{ }^{\text {a }} \text {. }}$ the variational equation for $\boldsymbol{H}=\boldsymbol{H}_{1}$ from for $\boldsymbol{H}=\boldsymbol{H}_{2}$, set $\boldsymbol{\varphi}=\boldsymbol{H}$ into the resulting equation and integrating in time for $t \in(0, T)$ :

$$
\begin{aligned}
\|\boldsymbol{H}(t)\|^{2} & +f(\beta) \int_{0}^{t}\|\nabla \times \boldsymbol{H}\|^{2}+g(\beta) C_{0} \int_{0}^{t}\|\nabla \times \boldsymbol{H}\|_{L^{\beta+1}(\Omega)}^{\beta+1} \\
& \leqslant-f(\beta) \int_{0}^{t}\left(\mathcal{K}_{0} \star \boldsymbol{H}, \nabla \times \boldsymbol{H}\right) \leqslant C_{\varepsilon} \int_{0}^{t}\|\boldsymbol{H}\|^{2}+\varepsilon \int_{0}^{t}\|\nabla \times \boldsymbol{H}\|^{2}
\end{aligned}
$$

We consider four cases:

- $\beta=1$ : then $f(\beta)=1$ and $g(\beta)=0$. Fixing a sufficiently small positive $\varepsilon$ and applying the Grönwall argument, we get that $\boldsymbol{H}=\mathbf{0}$ a.e. in $Q_{T}$;
- $1<\beta<7$ : then $f$ and $g$ are strict positive $\Rightarrow \boldsymbol{H}=\mathbf{0}$ a.e. in $Q_{T}$;
- $\beta \geqslant 7$ and $f(\beta)=0$ for $\beta \geqslant 7: \boldsymbol{H}=\mathbf{0}$ a.e. in $Q_{T}$;
- $\beta \geqslant 7$ and $f(\beta)>0$ for $\beta \geqslant 7$ but very small: analogously as the case $1<\beta<7$.


## Numerical scheme to approximate the solution

- Rothe's method [Kačur, 1985]: divide [0, T] into $n \in \mathbb{N}$ equidistant subintervals $\left(t_{i-1}, t_{i}\right)$ for $t_{i}=i \tau$, where $\tau=T / n<1$ and for any function $z$

$$
z_{i} \approx z\left(t_{i}\right) \text { and } \quad \partial_{t} z\left(t_{i}\right) \approx \delta z_{i}:=\frac{z_{i}-z_{i-1}}{\tau}
$$

- Convolution explicitly (from the previous time step):

$$
\left\{\begin{aligned}
&\left(\delta \boldsymbol{h}_{i}, \boldsymbol{\varphi}\right)+f(\beta)\left(\nabla \times \boldsymbol{h}_{i}, \nabla \times \varphi\right) \\
&+g(\beta)\left(\left|\nabla \times \boldsymbol{h}_{i}\right|^{\beta-1} \nabla \times \boldsymbol{h}_{i}, \nabla \times \boldsymbol{\varphi}\right)=\left(\boldsymbol{f}_{i}, \boldsymbol{\varphi}\right)-f(\beta)\left(\mathcal{K}_{0} \star \boldsymbol{h}_{i-1}, \nabla \times \boldsymbol{\varphi}\right) ; \\
& \boldsymbol{h}_{0}=\boldsymbol{H}_{0}
\end{aligned}\right.
$$

- Monotone operator theory [Vainberg, 1973]:


## Theorem (uniqueness on a single time step)

Assume $\boldsymbol{H}_{0} \in \mathbf{L}^{2}(\Omega)$ and $\boldsymbol{F} \in L^{2}\left((0, T), \mathbf{L}^{2}(\Omega)\right)$. Then there exists a $\tau_{0}>0$ such that the variational problem has a unique solution for any $i=1, \ldots, n$ and any $\tau<\tau_{0}$.

Convergence: a priori estimates as uniform bounds
Suppose that $\boldsymbol{F} \in L^{2}\left((0, T), \mathbf{L}^{2}(\Omega)\right)$
(i) Let $\boldsymbol{H}_{0} \in \mathbf{L}^{2}(\Omega)$. Then, there exists a positive constant $C$ such that

$$
\max _{1 \leqslant i \leqslant n}\left\|\boldsymbol{h}_{i}\right\|^{2}+\sum_{i=1}^{n}\left\|\boldsymbol{h}_{i}-\boldsymbol{h}_{i-1}\right\|^{2}+\sum_{i=1}^{n}\left\|\nabla \times \boldsymbol{h}_{i}\right\|_{\mathbf{L}^{\beta+1}(\Omega)}^{\beta+1} \tau \leqslant C
$$

for all $\tau<\tau_{0}$.
(ii) If $\nabla \cdot \boldsymbol{H}_{0}=0=\nabla \cdot \boldsymbol{f}_{i}$ then $\nabla \cdot \boldsymbol{h}_{i}=0$ for all $i=1, \ldots, n$.
(iii) If $\boldsymbol{H}_{0} \in \mathbf{V}$ then

$$
\max _{1 \leqslant i \leqslant n}\left\|\nabla \times \boldsymbol{h}_{i}\right\|_{L^{\beta+1}(\Omega)}^{\beta+1}+\sum_{i=1}^{n}\left\|\delta \boldsymbol{h}_{i}\right\|^{2} \tau \leqslant C
$$

for all $\tau<\tau_{0}$.

- $\boldsymbol{H}_{n}$ : piecewise linear in time spline of the solutions $\boldsymbol{h}_{i}, i=1, \ldots, n$
- $\overline{\boldsymbol{H}}_{n}$ : piecewise constant in time spline of the solutions $\boldsymbol{h}_{i}, i=1, \ldots, n$
- The variational formulaton on a single timestep can be rewritten on the whole time frame as

$$
\begin{aligned}
\left(\partial_{t} \boldsymbol{H}_{n}(t), \boldsymbol{\varphi}\right)+f(\beta) & \left(\nabla \times \overline{\boldsymbol{H}}_{n}(t), \nabla \times \boldsymbol{\varphi}\right) \\
+g(\beta) & \left(\left|\nabla \times \overline{\boldsymbol{H}}_{n}(t)\right|^{\beta-1} \nabla \times \overline{\boldsymbol{H}}_{n}(t), \nabla \times \boldsymbol{\varphi}\right) \\
& =\left(\overline{\boldsymbol{F}}_{n}(t), \boldsymbol{\varphi}\right)-f(\beta)\left(\mathcal{K}_{0} \star \overline{\boldsymbol{H}}_{n}(t-\tau), \nabla \times \boldsymbol{\varphi}\right)
\end{aligned}
$$

- Convergence of the sequences $\boldsymbol{H}_{n}$ and $\boldsymbol{H}_{n}$ to the unique weak solution is proved if $\tau \rightarrow 0$ or $n \rightarrow \infty$
- Main ideas of the proof:
- Compact embedding [Palatucci et al., 2013, Lemma 10]:

$$
\mathbf{H}^{\frac{1}{2}}(\Omega) \hookrightarrow \hookrightarrow \mathbf{L}^{2}(\Omega) \cong \mathbf{L}^{2}(\Omega)^{*} \hookrightarrow \mathbf{H}_{0}^{-1}(\operatorname{curl}, \Omega)
$$

implies [Kačur, 1985]

$$
\boldsymbol{H}_{n} \rightarrow \boldsymbol{H} \text { in } C\left([0, T], \mathbf{L}^{2}(\Omega)\right)
$$

and

$$
\overline{\boldsymbol{H}}_{n} \rightarrow \boldsymbol{H} \text { in } L^{2}\left([0, T], \mathbf{L}^{2}(\Omega)\right)
$$

- Minty-Browder's trick for the convergence of the nonlinear term
- $\boldsymbol{H}$ is the weak solution of the problem


## Theorem (Existence solution)

Let $\boldsymbol{H}_{0} \in \mathbf{V}$ and $\boldsymbol{F} \in L^{2}\left((0, T), \mathbf{L}^{2}(\Omega)\right)$. Assume that $\nabla \cdot \boldsymbol{H}_{0}=0=\nabla \cdot \boldsymbol{F}(t)$ for any time $t \in[0, T]$. Then there exists a weak solution $\mathbf{H} \in C\left([0, T], \mathbf{L}^{2}(\Omega)\right)$ with $\partial_{t} \boldsymbol{H} \in L^{2}\left((0, T), \mathbf{L}^{2}(\Omega)\right)$.

## Error estimates for the time discretization

Theorem (Error)
Suppose that $\boldsymbol{F} \in \operatorname{Lip}\left([0, T], \mathbf{L}^{2}(\Omega)\right)$. If $\mathbf{H}_{0} \in \mathbf{V}$ then

$$
\max _{t \in[0, T]}\left\|\boldsymbol{H}_{n}(t)-\boldsymbol{H}(t)\right\|^{2}+\int_{0}^{T}\left\|\nabla \times\left[\overline{\boldsymbol{H}}_{n}-\boldsymbol{H}\right]\right\|_{\mathbf{L}^{\beta+1}(\Omega)}^{\beta+1} \leqslant C \tau .
$$

Please note that the positive constant $C$ in this estimates is of the form $C e^{C T}$.

Conclusion:

- Macroscopic model for an intermediate state between type-I and type-II superconductivity is proposed
- Well-posedness is proved
- Numerical scheme for calculations is provided

Future research:

- Numerical implementation
- Comparison with available results about neither type-I nor type-II superconductors


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