

The well-posedness of a mathematical model for an intermediate state between type-I and type-II superconductivity

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Outline

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Features of superconductivity

Kammerlingh Onnes (1911): perfect conductivity



For various cooled down materials the electrical resistance not only decreases with temperature, but also has a sudden drop at some critical absolute temperature T_c

- ► Meissner and Ochsenfeld (1933): perfect diamagnetism ⇒ i.e. expulsion of the magnetic induction B
- Kammerlingh Onnes (1914): threshold field

 \Rightarrow restore the normal state through the application of a large magnetic field

A way to classify superconductors: type-I and type-II

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Type-I versus type-II superconductivity

- Similar behaviour for a very weak external magnetic field when the temperature T < T_c is fixed
- As the external magnetic field becomes stronger it turns out that two possibilities can happen ⇒ phase diagram in the *T*-*H* plane



- ► Type-I (a): the **B** field remains zero inside the superconductor until suddenly, as the critical field H_c is reached, the superconductivity is destroyed
- Type-II (b): a mixed state occurs in addition to the superconductive and the normal state (two different critical fields)
- What are the macroscopic models which are used in the modelling of type-I and type-II superconductors?

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Type-I

- $\Omega \subset \mathbb{R}^3$: bounded Lipschitz domain, u unit normal vector on Γ
- ► The quasi-static Maxwell equations for linear materials are considered

$ abla imes oldsymbol{H} = oldsymbol{J}$	Ampère's law	н	magnetic field		
$ abla imes \mathbf{E} = -\mu \partial_t \mathbf{H}$	Faraday's law	Ε	electric field	$\mu > 0$	magnetic permeability
$ abla \cdot \pmb{H}_0 = 0$		J	current density		

London and London (1935): a macroscopic description of type-I superconductors involves a two-fluid model

- $\begin{array}{c} {J} = {J}_n + {J}_s \\ {J}_n = \sigma {E} \end{array} \quad \begin{array}{c} \nabla \times {H} = \sigma {E} + {J}_s \\ \nabla \times {E} = -\mu \partial_t H \\ \nabla \cdot {H}_0 = 0 \end{array} \quad \begin{array}{c} {J}_n \quad \text{normal current density} \\ {J}_s \quad \text{superconducting current density} \\ \sigma \cdot {H}_0 = 0 \end{array}$
- Below the critical temperature T_c, the current consists of superconducting electrons and normal electrons

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Macroscopic models for type-I superconductors				

London equations (1935) \Rightarrow local law for J_s

 $\begin{array}{ll} \partial_t \boldsymbol{J}_s = \boldsymbol{\Lambda}^{-1} \boldsymbol{E} & n_s & \text{density of superelectrons} \\ \nabla \times \boldsymbol{J}_s = -\boldsymbol{\Lambda}^{-1} \boldsymbol{B} & m_e & \text{mass of an electron} \\ \boldsymbol{\Lambda} = \frac{m_e}{n_s e^2} & -e & \text{electric charge of an electron} \end{array}$

 \Rightarrow Correct description of two basic properties of superconductors: perfect conductivity and perfect diamagnetism (Meissner effect)

 $\nabla \cdot \boldsymbol{B} = 0 \Rightarrow \exists \boldsymbol{A} \text{ such that } \boldsymbol{B} = \nabla \times \boldsymbol{A} \text{ and } \nabla \cdot \boldsymbol{A} = 0$ $\nabla \times \boldsymbol{J}_{s} = -\Lambda^{-1} \boldsymbol{B} \quad \Rightarrow \quad \boldsymbol{J}_{s}(\boldsymbol{x}, t) = -\Lambda^{-1} \boldsymbol{A}(\boldsymbol{x}, t), \quad (\boldsymbol{x}, t) \in \Omega \times (0, T)$

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Macroscopic models for type-I superconductors

Generalization of London and London: nonlocal laws

[Pippard, 1953]

$$\boldsymbol{J}_{\boldsymbol{s},\boldsymbol{\rho}}(\boldsymbol{x},t) = \int_{\Omega} Q(\boldsymbol{x}-\boldsymbol{x}') \boldsymbol{A}(\boldsymbol{x}',t) \, \mathrm{d}\boldsymbol{x}', \qquad (\boldsymbol{x},t) \in \Omega \times (0,T)$$

with

$$Q(\mathbf{x} - \mathbf{x}')\mathbf{A}(\mathbf{x}', t) = -\widetilde{C} \frac{\mathbf{x} - \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|^4} \left[\mathbf{A}(\mathbf{x}', t) \cdot (\mathbf{x} - \mathbf{x}')\right] \exp\left(-\frac{|\mathbf{x} - \mathbf{x}'|}{r_0}\right),$$
$$\widetilde{C} := \frac{3}{4\pi\xi_0\Lambda} > 0, \qquad r_0 := \frac{\xi_0 I}{\xi_0 + I}$$

 ξ_0 the coherence length of the material, / is the mean free path

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Macroscopic models for type-I superconductors

[Eringen, 1984]

$$\begin{aligned} \mathbf{J}_{s,e}(\mathbf{x},t) &= \int_{\Omega} \sigma_0 \left(|\mathbf{x} - \mathbf{x}'| \right) \left(\mathbf{x} - \mathbf{x}' \right) \times \mathbf{H}(\mathbf{x}',t) \, \mathrm{d}\mathbf{x}' =: -(\mathcal{K}_0 \star \mathbf{H})(\mathbf{x},t), \\ & (\mathbf{x},t) \in \Omega \times (0,T) \end{aligned}$$

with

$$\sigma_0(s) = \begin{cases} \frac{\widetilde{C}}{2s^2} \exp\left(-\frac{s}{r_0}\right) & s < r_0; \\ 0 & s \ge r_0 \end{cases}$$

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Macroscopic models for type-I superconductors				

- Pippard's nonlocal law fails to explain the vanishing of electrical resistance
- It is possible to recover from Eringen's law the London equations and the form given by Pippard

$$\Rightarrow \mathbf{J}_{s} = \mathbf{J}_{s,e} = -\mathcal{K}_{0} \star \mathbf{H} \quad \text{in} \quad \left\{ \begin{array}{l} \nabla \times \mathbf{H} &= \sigma \mathbf{E} + \mathbf{J}_{s} \\ \nabla \times \mathbf{E} &= -\mu \partial_{t} \mathbf{H} \end{array} \right.$$

Taking the curl of Ampère's law result in

$$\sigma \mu \partial_t \boldsymbol{H} + \nabla \times \nabla \times \boldsymbol{H} + \nabla \times (\mathcal{K}_0 \star \boldsymbol{H}) = \boldsymbol{0}$$

- Well-posedness is studied into detail in [Slodička and Van Bockstal, 2014].
- Also the error estimates for two time-discrete schemes (an implicit and a semi-implicit) based on backward Euler method are derived in [Slodička and Van Bockstal, 2014].

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Type-II

Dependency between current density J and the electric field E



- Ohm's law for non-superconducting metal (dashed)
- ▶ Bean's critical-state model for type-II superconductors (fine dashed): current either flows at the critical level J_c or not at all ⇒ not fully applicable
- ► The power law by Rhyner for type-II superconductors (continuous)

$$E = \sigma_c^{-n} |J|^{n-1} J, \qquad n \in (7, 1000)$$

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Macroscopic models for type-II superconductors				

► Take the curl of the power law and use Faraday's law ⇒ nonlinear and degenerate partial differential equation for the magnetic field

$$\mu \partial_t \boldsymbol{H} + \sigma_c^{-n} \nabla \times \left(|\nabla \times \boldsymbol{H}|^{n-1} \nabla \times \boldsymbol{H} \right) = \boldsymbol{0}$$

 Studied by: [Barrett and Prigozhin, 2000, Yin et al., 2002, Prigozhin and Sokolovsky, 2004, Wei and Yin, 2005]

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Intermediate state between type-I and type-II superconductivity				

- The classification into type-I and type-II is insufficient for multiband superconductors [Babaev and Speight, 2005]
- > This are superconductors with several superconducting components
- The material 'magnesium diboride' combines the characteristics of both types [Nagamatsu et al., 2001]
- New kind of superconductor: type-1.5 superconductors [Moshchalkov et al., 2009, Babaev et al., 2012]
- Allows coexistence of various properties of type-I and type-II superconductors

Problem

Is it possible to derive macroscopic models for an intermediate state between type-I and type-II superconductors?

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► Type-I:

$$u\partial_t \boldsymbol{H} + \sigma^{-1} \nabla \times \nabla \times \boldsymbol{H} + \sigma^{-1} \nabla \times (\mathcal{K}_0 \star \boldsymbol{H}) = \boldsymbol{0}$$

▶ Type-II (*n* ∈ (7, 1000)):

$$\mu \partial_t \boldsymbol{H} + \sigma_c^{-n} \nabla \times \left(|\nabla \times \boldsymbol{H}|^{n-1} \nabla \times \boldsymbol{H} \right) = \boldsymbol{0}$$

By introducing a real parameter β ≥ 1 and a real function f(β), we propose to combine both equations to

$$\mu \partial_t \boldsymbol{H} + \sigma^{-1} f(\beta) \nabla \times \nabla \times \boldsymbol{H} + \sigma_c^{-\beta} g(\beta) \nabla \times (|\nabla \times \boldsymbol{H}|^{\beta - 1} \nabla \times \boldsymbol{H}) + \sigma^{-1} f(\beta) \nabla \times (\mathcal{K}_0 \star \boldsymbol{H}) = \boldsymbol{0}$$

with

- ▶ $f \in C([1,\infty))$ monotonically decreasing, f(1) = 1 and $0 \leqslant f(\beta) \leqslant 1$ for $\beta > 1$
- f equals zero or is very small for $\beta > 7$
- $g(\beta) := 1 f(\beta)$
- Intermediate state: $1 < \beta \leqslant 7$

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- It is assumed (for simplicity) that $\mu = \sigma = \sigma_c = 1$
- \blacktriangleright The aim of this paper is to address the well-posedness of the following problem for $\beta \geqslant 1$:

$$\begin{array}{l} \partial_t \boldsymbol{H} + f(\beta) \nabla \times \nabla \times \boldsymbol{H} + g(\beta) \nabla \times \left(|\nabla \times \boldsymbol{H}|^{\beta-1} \nabla \times \boldsymbol{H} \right) \\ + f(\beta) \nabla \times (\mathcal{K}_0 \star \boldsymbol{H}) &= \boldsymbol{F} & \text{ in } \Omega \times (0, T); \\ \boldsymbol{H} \times \boldsymbol{\nu} &= \boldsymbol{0} & \text{ on } \Gamma \times (0, T); \\ \boldsymbol{H}(\boldsymbol{x}, 0) &= \boldsymbol{H}_0 & \text{ in } \Omega; \end{array}$$

to design a numerical scheme for computations and to derive error estimates for the time discretization

Some possible choices for *f*:

$$f(eta) = egin{cases} rac{(-1)^lpha}{6^lpha} (eta-7)^lpha & 1\leqslanteta\leqslant7\ 0 & eta>7 \end{cases}, \quad lpha\in\mathbb{N}$$

 $f(\beta) = \exp(-k\beta), \quad k \in \mathbb{R}^+$

► Focus on mathematical analysis, not on implementation.

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Usefull estimates

Using spherical coordinates one can deduce that

• $\sigma_0(|\mathbf{x}|)\mathbf{x} \in \mathbf{L}^p(\Omega)$ for $p \in [1,3)$:

$$\begin{split} \int_{\Omega} \left| \sigma_{0}\left(|\mathbf{x}| \right) \mathbf{x} \right|^{p} \, \mathrm{d}\mathbf{x} &\leq \int_{\mathcal{B}\left(\mathbf{0}, r_{0} \right)} \frac{C}{|\mathbf{x}|^{2p}} \left| \exp\left(- \frac{|\mathbf{x}|}{r_{0}} \right) \right|^{p} |\mathbf{x}|^{p} \, \mathrm{d}\mathbf{x} \\ &\leq C \int_{0}^{2\pi} \mathrm{d}\varphi \int_{0}^{\pi} \sin(\theta) \mathrm{d}\theta \int_{0}^{r_{0}} r^{2-p} \mathrm{d}\mathbf{r} \leqslant C \left[\frac{r^{3-p}}{3-p} \right]_{0}^{r_{0}} < \infty \end{split}$$

 $\blacktriangleright |\mathbf{J}_{s}(\mathbf{x},t)| = |(\mathcal{K}_{0} \star \mathbf{H})(\mathbf{x},t)| \leqslant C(q) \|\mathbf{H}(t)\|_{q} \text{ for } q > \frac{3}{2}, \quad \forall \mathbf{x} \in \Omega:$

$$\begin{aligned} |J_{\mathfrak{s}}(\mathbf{x},t)| &= \left| \int_{\Omega} \sigma_{0} \left(\left| \mathbf{x} - \mathbf{x}' \right| \right) (\mathbf{x} - \mathbf{x}') \times \mathbf{H}(\mathbf{x}',t) \, \mathrm{d}\mathbf{x}' \right| \leq \int_{\Omega} \left| \sigma_{0} \left(\left| \mathbf{x} - \mathbf{x}' \right| \right) (\mathbf{x} - \mathbf{x}') \right| \, \left| \mathbf{H}(\mathbf{x}',t) \right| \, \mathrm{d}\mathbf{x}' \\ &\leq \sqrt[p]{\int_{\Omega} \left| \sigma_{0} \left(\left| \mathbf{x} - \mathbf{x}' \right| \right) (\mathbf{x} - \mathbf{x}') \right|^{p} \, \mathrm{d}\mathbf{x}'} \sqrt[q]{\int_{\Omega} \left| \mathbf{H}(\mathbf{x}',t) \right|^{q} \, \mathrm{d}\mathbf{x}'} \leq C \left\| \mathbf{H}(t) \right\|_{q} \end{aligned}$$

For instance, it holds that

$$\left(\mathcal{K}_{\mathbf{0}}\star\boldsymbol{h},\nabla\times\boldsymbol{h}\right)\leqslant \textit{C}_{\varepsilon}\left\|\boldsymbol{h}\right\|^{2}+\varepsilon\left\|\nabla\times\boldsymbol{h}\right\|^{2},\quad\forall\boldsymbol{h}\in\mathsf{H}(\mathsf{curl}\,,\Omega)$$

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Variational formulation

The suitable choise for the space of test functions is

$$\boldsymbol{\mathsf{V}}_0 = \left\{\boldsymbol{\varphi} \in \boldsymbol{\mathsf{L}}^2(\Omega) \,:\, \nabla \times \boldsymbol{\varphi} \in \boldsymbol{\mathsf{L}}^{\beta+1}(\Omega) \text{ and } \boldsymbol{\varphi} \times \boldsymbol{\nu} = \boldsymbol{\mathsf{0}} \text{ on } \boldsymbol{\mathsf{\Gamma}} \right\} \subset \boldsymbol{\mathsf{H}}_0(\boldsymbol{\mathsf{curl}}\,,\Omega).$$

This is a closed subspace of the space

$$\mathbf{V} = \left\{ \boldsymbol{\varphi} \in \mathbf{L}^2(\Omega) \, : \, \nabla \times \boldsymbol{\varphi} \in \mathbf{L}^{\beta+1}(\Omega) \right\} \subset \mathbf{H}(\mathbf{curl}\,, \Omega),$$

and is endowed with the same graph norm

$$\|\varphi\|_{\mathbf{V}} = \|\varphi\|_{\mathbf{V}_0} = \|\varphi\|_{\mathsf{L}^2(\Omega)} + \|\nabla \times \varphi\|_{\mathsf{L}^{\beta+1}(\Omega)}$$

Definition

Let $\beta \ge 1$, $H_0 \in \mathbf{V}$ and $\mathbf{F} \in L^2((0, T), \mathbf{L}^2(\Omega))$. The variational formulation of (14) reads as: find $\mathbf{H} \in C([0, T], \mathbf{L}^2(\Omega))$ with $\nabla \times \mathbf{H} \in L^{\beta+1}((0, T), \mathbf{L}^{\beta+1}(\Omega))$ and $\partial_t \mathbf{H} \in L^2([0, T], \mathbf{L}^2(\Omega))$ such that

$$\begin{split} (\partial_t \boldsymbol{H}(t), \varphi) + f(\beta) \left(\nabla \times \boldsymbol{H}(t), \nabla \times \varphi \right) + g(\beta) \left(|\nabla \times \boldsymbol{H}(t)|^{\beta - 1} \nabla \times \boldsymbol{H}(t), \nabla \times \varphi \right) \\ &+ f(\beta) \left(\mathcal{K}_0 \star \boldsymbol{H}(t), \nabla \times \varphi \right) = (\boldsymbol{F}(t), \varphi), \quad \forall \varphi \in \boldsymbol{V}_0, \end{split}$$

for a.e. $t \in [0, T]$.

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Variational formulation

Lemma (reflexivity)

The vector spaces V and V_0 are reflexive Banach spaces.

Lemma (monotonicity)

Let $\beta \ge 1$. There exists a positive constant $C_0(\beta) = \frac{1}{4 \cdot 12^{\frac{\beta+1}{2}}}$ such that for any $H_1, H_2 \in V$ hold

$$\begin{split} \left(|\nabla \times \boldsymbol{H}_1|^{\beta-1} \nabla \times \boldsymbol{H}_1 - |\nabla \times \boldsymbol{H}_2|^{\beta-1} \nabla \times \boldsymbol{H}_2, \nabla \times (\boldsymbol{H}_1 - \boldsymbol{H}_2) \right) \\ & \geqslant C_0(\beta) \left\| \nabla \times (\boldsymbol{H}_1 - \boldsymbol{H}_2) \right\|_{\mathbf{L}^{\beta+1}(\Omega)}^{\beta+1}. \end{split}$$

Theorem (uniqueness)

The problem (14) admits at most one solution $\partial_t \mathbf{H} \in L^2([0, T], \mathbf{L}^2(\Omega))$ with $\nabla \times \mathbf{H} \in L^{\beta+1}((0, T), \mathbf{L}^{\beta+1}(\Omega))$ if $\mathbf{H}_0 \in \mathbf{L}^2(\Omega)$.

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Variational formulation

Proof uniqueness:

Assume that we have two solutions H_1 and H_2 . Set $H = H_1 - H_2$. Subtract the variational equation for $H = H_1$ from for $H = H_2$, set $\varphi = H$ into the resulting equation and integrating in time for $t \in (0, T)$:

$$\begin{split} \left\|\boldsymbol{H}(t)\right\|^{2} + f(\beta) \int_{0}^{t} \left\|\nabla \times \boldsymbol{H}\right\|^{2} + g(\beta)C_{0} \int_{0}^{t} \left\|\nabla \times \boldsymbol{H}\right\|_{\boldsymbol{\mathsf{L}}^{\beta+1}(\Omega)}^{\beta+1} \\ \leqslant -f(\beta) \int_{0}^{t} \left(\mathcal{K}_{0} \star \boldsymbol{H}, \nabla \times \boldsymbol{H}\right) \leqslant C_{\varepsilon} \int_{0}^{t} \left\|\boldsymbol{H}\right\|^{2} + \varepsilon \int_{0}^{t} \left\|\nabla \times \boldsymbol{H}\right\|^{2}. \end{split}$$

We consider four cases:

- ▶ $\beta = 1$: then $f(\beta) = 1$ and $g(\beta) = 0$. Fixing a sufficiently small positive ε and applying the Grönwall argument, we get that H = 0 a.e. in Q_T ;
- ▶ $1 < \beta < 7$: then f and g are strict positive $\Rightarrow H = 0$ a.e. in Q_T ;
- $\beta \ge 7$ and $f(\beta) = 0$ for $\beta \ge 7$: H = 0 a.e. in Q_T ;
- ▶ $\beta \ge 7$ and $f(\beta) > 0$ for $\beta \ge 7$ but very small: analogously as the case $1 < \beta < 7$.

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Time discretization: existence of a solution

Numerical scheme to approximate the solution

▶ Rothe's method [Kačur, 1985]: divide [0, T] into $n \in \mathbb{N}$ equidistant subintervals (t_{i-1}, t_i) for $t_i = i\tau$, where $\tau = T/n < 1$ and for any function z

$$z_i pprox z(t_i) ext{ and } \quad \partial_t z(t_i) pprox \delta z_i := rac{z_i - z_{i-1}}{ au}$$

• Convolution explicitly (from the previous time step):

$$\begin{array}{l} \left(\delta \boldsymbol{h}_{i},\boldsymbol{\varphi}\right)+f(\beta)\left(\nabla\times\boldsymbol{h}_{i},\nabla\times\boldsymbol{\varphi}\right)\\ +g(\beta)\left(|\nabla\times\boldsymbol{h}_{i}|^{\beta-1}\nabla\times\boldsymbol{h}_{i},\nabla\times\boldsymbol{\varphi}\right) &=\left(\boldsymbol{f}_{i},\boldsymbol{\varphi}\right)-f(\beta)\left(\mathcal{K}_{0}\star\boldsymbol{h}_{i-1},\nabla\times\boldsymbol{\varphi}\right);\\ \boldsymbol{h}_{0} &=\boldsymbol{H}_{0} \end{array}$$

Monotone operator theory [Vainberg, 1973]:

Theorem (uniqueness on a single time step)

Assume $H_0 \in L^2(\Omega)$ and $F \in L^2((0, T), L^2(\Omega))$. Then there exists a $\tau_0 > 0$ such that the variational problem has a unique solution for any i = 1, ..., n and any $\tau < \tau_0$.

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Time discretization: existence of a solution

Convergence: a priori estimates as uniform bounds Suppose that $\mathbf{F} \in L^2((0, T), \mathbf{L}^2(\Omega))$

(i) Let $H_0 \in L^2(\Omega)$. Then, there exists a positive constant C such that

$$\max_{1\leqslant i\leqslant n} \|\boldsymbol{h}_i\|^2 + \sum_{i=1}^n \|\boldsymbol{h}_i - \boldsymbol{h}_{i-1}\|^2 + \sum_{i=1}^n \|\nabla \times \boldsymbol{h}_i\|_{\mathsf{L}^{\beta+1}(\Omega)}^{\beta+1} \tau \leqslant C$$

for all $\tau < \tau_0$.

(*ii*) If $\nabla \cdot \boldsymbol{H}_0 = 0 = \nabla \cdot \boldsymbol{f}_i$ then $\nabla \cdot \boldsymbol{h}_i = 0$ for all $i = 1, \dots, n$. (*iii*) If $\boldsymbol{H}_0 \in \boldsymbol{V}$ then

$$\max_{1 \leq i \leq n} \|\nabla \times \boldsymbol{h}_i\|_{\boldsymbol{\mathsf{L}}^{\beta+1}(\Omega)}^{\beta+1} + \sum_{i=1}^n \|\delta \boldsymbol{h}_i\|^2 \tau \leq C$$

for all $\tau < \tau_0$.

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Time discretization: existence of a solution			

- H_n : piecewise linear in time spline of the solutions h_i , i = 1, ..., n
- ▶ \overline{H}_n : piecewise constant in time spline of the solutions h_i , i = 1, ..., n
- The variational formulaton on a single timestep can be rewritten on the whole time frame as

$$\begin{aligned} (\partial_t \boldsymbol{H}_n(t), \boldsymbol{\varphi}) + f(\beta) \left(\nabla \times \overline{\boldsymbol{H}}_n(t), \nabla \times \boldsymbol{\varphi} \right) \\ &+ g(\beta) \left(|\nabla \times \overline{\boldsymbol{H}}_n(t)|^{\beta - 1} \nabla \times \overline{\boldsymbol{H}}_n(t), \nabla \times \boldsymbol{\varphi} \right) \\ &= \left(\overline{\boldsymbol{F}}_n(t), \boldsymbol{\varphi} \right) - f(\beta) \left(\mathcal{K}_0 \star \overline{\boldsymbol{H}}_n(t - \tau), \nabla \times \boldsymbol{\varphi} \right). \end{aligned}$$

Convergence of the sequences *H_n* and *H_n* to the unique weak solution is proved if *τ* → 0 or *n* → ∞

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Time discretization: existence of a solution

Main ideas of the proof:

Compact embedding [Palatucci et al., 2013, Lemma 10]:

$$\mathbf{H}^{\frac{1}{2}}(\Omega) \hookrightarrow \mathbf{L}^{2}(\Omega) \cong \mathbf{L}^{2}(\Omega)^{*} \hookrightarrow \mathbf{H}_{0}^{-1}(\mathbf{curl}\,,\Omega)$$

implies [Kačur, 1985]

$$H_n \rightarrow H$$
 in $C([0, T], L^2(\Omega))$

and

$$\overline{\boldsymbol{H}}_n \to \boldsymbol{H} \text{ in } L^2\left([0,T], \boldsymbol{L}^2(\Omega)\right)$$

- Minty-Browder's trick for the convergence of the nonlinear term
- H is the weak solution of the problem

Theorem (Existence solution)

Let $\mathbf{H}_0 \in \mathbf{V}$ and $\mathbf{F} \in L^2((0, T), \mathbf{L}^2(\Omega))$. Assume that $\nabla \cdot \mathbf{H}_0 = 0 = \nabla \cdot \mathbf{F}(t)$ for any time $t \in [0, T]$. Then there exists a weak solution $\mathbf{H} \in C([0, T], \mathbf{L}^2(\Omega))$ with $\partial_t \mathbf{H} \in L^2((0, T), \mathbf{L}^2(\Omega))$.

Time discretization: existence of a solution

Error estimates for the time discretization

Theorem (Error)

Suppose that $\mathbf{F} \in \operatorname{Lip}([0, T], \mathbf{L}^2(\Omega))$. If $\mathbf{H}_0 \in \mathbf{V}$ then

$$\max_{t\in[0,T]} \left\| \boldsymbol{H}_n(t) - \boldsymbol{H}(t) \right\|^2 + \int_0^T \left\| \nabla \times [\overline{\boldsymbol{H}}_n - \boldsymbol{H}] \right\|_{\boldsymbol{\mathsf{L}}^{\beta+1}(\Omega)}^{\beta+1} \leqslant C\tau.$$

Please note that the positive constant C in this estimates is of the form Ce^{CT} .

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Conclusion:

- Macroscopic model for an intermediate state between type-I and type-II superconductivity is proposed
- Well-posedness is proved
- Numerical scheme for calculations is provided

Future research:

- Numerical implementation
- Comparison with available results about neither type-I nor type-II superconductors

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