Hitting Times and Probabilities for Imprecise Markov Chains

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Markov Chains

Stochastically evolving dynamical system with uncertain state X_n

- Time $n \in \mathbb{N}_0$ (discrete time model)
- \blacksquare Finite state space $\mathscr X$

A stochastic process P is called a Markov chain if

$$P(X_{n+1} = x_{n+1} | X_{0:n} = x_{0:n}) = P(X_{n+1} = x_{n+1} | X_n = x_n)$$

A Markov chain is called homogeneous if, moreover,

$$P(X_{n+1} = y | X_n = x) = P(X_1 = y | X_0 = x)$$

Markov Chains and Transition Matrices

A transition matrix T is an $|\mathscr{X}| \times |\mathscr{X}|$ matrix that is row-stochastic:

• $\sum_{y \in \mathscr{X}} T(x,y) = 1$ and $T(x,y) \ge 0$

Such a T determines a homogeneous Markov chain P for which

$$P(X_{n+1} = y \mid X_n = x) = T(x, y)$$
 for all $x, y \in \mathscr{X}$ and $n \in \mathbb{N}_0$.

- What if we don't know T?
- Or: what if Markov assumption is unwarranted?
- \Rightarrow Instead use an *imprecise* Markov chain

Imprecise Markov Chains

Parameterised by a set \mathscr{T} of transition matrices.

• \mathcal{T} must satisfy some technical closure properties.

Inferences are the *lower* and *upper expectations* of quantities of interest.

These depend on the type of imprecise Markov chain!

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For the set $\mathscr{P}^{\mathrm{H}}_{\mathscr{T}}$ of homogeneous Markov chains with transition matrix T in \mathscr{T} ,

$$\underline{\mathbb{E}}_{\mathscr{T}}^{\mathrm{H}}[\cdot | \cdot] = \inf_{P \in \mathscr{P}_{\mathscr{T}}^{\mathrm{H}}} \mathbb{E}_{P}[\cdot | \cdot] \quad \text{and} \quad \overline{\mathbb{E}}_{\mathscr{T}}^{\mathrm{H}}[\cdot | \cdot] = \sup_{P \in \mathscr{P}_{\mathscr{T}}^{\mathrm{H}}} \mathbb{E}_{P}[\cdot | \cdot]$$

What other types are there?

Set of homogeneous Markov chains with transition matrix $T \in \mathscr{T}$.

Set of homogeneous Markov chains with transition matrix $T \in \mathcal{T}$.

• Game-theoretic probability model with local uncertainty models described by \mathcal{T} .

$\underline{\mathbb{E}}_{\mathscr{T}}^{\mathbf{V}}[\cdot | \cdot] \leq \underline{\mathbb{E}}_{\mathscr{T}}^{\mathbf{H}}[\cdot | \cdot]$

Set of homogeneous Markov chains with transition matrix $T \in \mathcal{T}$.

• Set of *general* stochastic processes "compatible" with \mathscr{T} . Always some $T \in \mathscr{T}$ such that

$$P(X_{n+1} = x_{n+1} | X_{0:n} = x_{0:n}) = T(x_n, x_{n+1}),$$

but can be different T for each $x_{0:n}$. Called an imprecise Markov chain under *epistemic irrelevance*.

• Game-theoretic probability model with local uncertainty models described by \mathcal{T} .

$$\underline{\mathbb{E}}_{\mathscr{T}}^{\mathbf{V}}[\cdot | \cdot] \leq \underline{\mathbb{E}}_{\mathscr{T}}^{\mathbf{I}}[\cdot | \cdot] \leq \underline{\mathbb{E}}_{\mathscr{T}}^{\mathbf{H}}[\cdot | \cdot]$$

Set of homogeneous Markov chains with transition matrix $T \in \mathscr{T}$.

Set of Markov chains such that for all $n \in \mathbb{N}_0$ there is some $T \in \mathscr{T}$ for which

$$P(X_{n+1} = x_{n+1} | X_n = x_n) = T(x_n, x_{n+1}).$$

Called a Markov set chain, or an imprecise Markov chain under strong independence.
Set of general stochastic processes "compatible" with 𝒮. Always some 𝔅 𝔅 𝔅 such that

$$P(X_{n+1} = x_{n+1} | X_{0:n} = x_{0:n}) = T(x_n, x_{n+1}),$$

but can be different T for each $x_{0:n}$.

Called an imprecise Markov chain under epistemic irrelevance.

• Game-theoretic probability model with local uncertainty models described by \mathcal{T} .

$\underline{\mathbb{E}}^{V}_{\mathscr{T}}[\cdot \,|\, \cdot] \leq \underline{\mathbb{E}}^{I}_{\mathscr{T}}[\cdot \,|\, \cdot] \leq \underline{\mathbb{E}}^{M}_{\mathscr{T}}[\cdot \,|\, \cdot] \leq \underline{\mathbb{E}}^{H}_{\mathscr{T}}[\cdot \,|\, \cdot]$

Lower and Upper Expected Hitting Times

Given a fixed set $A \subset \mathscr{X}$ of states:

How long will it take before the system visits an element of A?

What is $\mathbb{E}_{P}[H_{A} | X_{0}]$, where H_{A} is the number of steps before A is visited?

What can we say about this for the various types of imprecise Markov chains?

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Theorem

$$\underline{\mathbb{E}}_{\mathscr{T}}^{\mathrm{V}}[H_{A} | X_{0}] = \underline{\mathbb{E}}_{\mathscr{T}}^{\mathrm{I}}[H_{A} | X_{0}] = \underline{\mathbb{E}}_{\mathscr{T}}^{\mathrm{M}}[H_{A} | X_{0}] = \underline{\mathbb{E}}_{\mathscr{T}}^{\mathrm{H}}[H_{A} | X_{0}]$$

(and similarly for the upper expected hitting time)