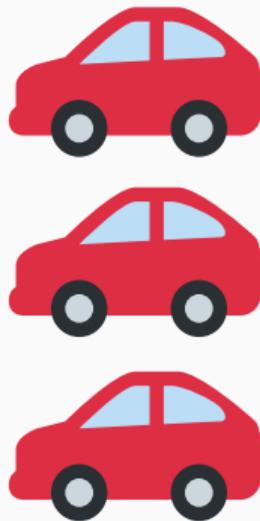


Extending the domain of Markovian imprecise jump processes

Alexander Erreygers Jasper De Bock

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Ghent University, ELIS, Foundations Lab for imprecise probabilities





The manager  is interested in things like

- the expected average number of  over the following 24 hours;
- the expected duration of  in the following hour;
- the expected time until ;
- the probability of  in the following hour.

The abstract framework

We want to make inferences about the *state* of some system 

which evolves over continuous time in a non-deterministic manner.

The *state* X_t at the time point t in $\mathbb{R}_{\geq 0}$ is an uncertain variable,

and we assume that it takes values in a **finite state space** \mathcal{X} (: $\{0, 1, 2, 3\}$).

We are interested in the expectation/probability of **idealised variables/events** like

- temporal averages: $\frac{1}{T} \int_0^T f(X_t) dt$;
- hitting times: $\inf \{t \in \mathbb{R}_{\geq 0} : X_t \in A\}$;
- hitting events: $\bigcup_{t \in \mathcal{T}} \{X_t \in A\}$.

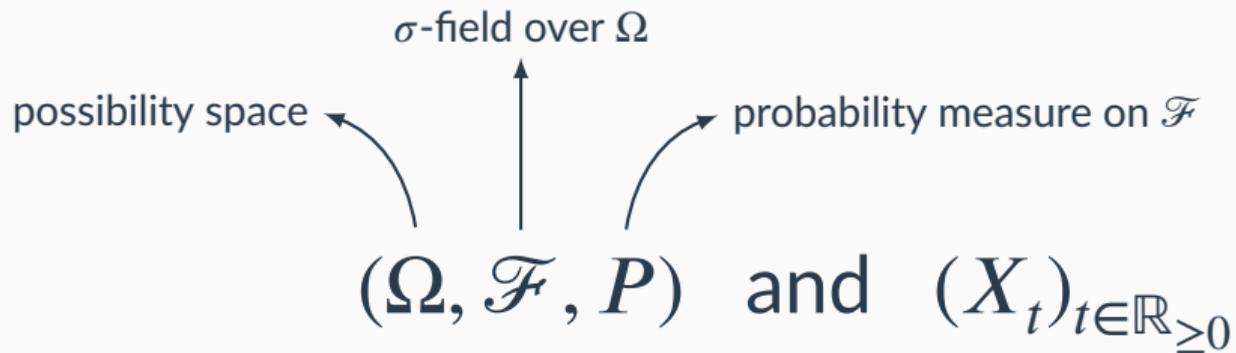
: avg. # of , dur. of 

: time until 

:  in the following hour

$$(\Omega, \mathcal{F}, P) \quad \text{and} \quad (X_t)_{t \in \mathbb{R}_{\geq 0}}$$

The measure-theoretic model



(Ω, \mathcal{F}, P) and $(X_t)_{t \in \mathbb{R}_{\geq 0}}$



X_t is an \mathcal{F} -measurable map from Ω to \mathcal{X}

Constructing a measure-theoretic model

Ω is the set of all maps from $\mathbb{R}_{\geq 0}$ to \mathcal{X}

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Ω is the set of all maps from $\mathbb{R}_{\geq 0}$ to \mathcal{X}

\mathcal{F} is the field of all *cylinder events* of the form $\{\omega \in \Omega : (\omega(t_1), \dots, \omega(t_n)) \in A\}$



$\sigma(\mathcal{F})$ is the σ -field generated by \mathcal{F}

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$\sigma(\mathcal{F})$ is the σ -field generated by \mathcal{F}

P is a probability charge on \mathcal{F}

 P is trivially σ -additive on \mathcal{F} 

P on \mathcal{F} $\xrightarrow{\text{Carathéodory's Theorem}}$ P_σ on $\sigma(\mathcal{F})$ $\xrightarrow{\text{Lebesgue integration}}$ $E_{P_\sigma}^L$ on $\sigma(\mathcal{F})$ -measurables

Constructing a measure-theoretic model

$(\Omega, \sigma(\mathcal{F}), P_\sigma)$ is a probability space, and for all time points t in $\mathbb{R}_{\geq 0}$,

$X_t : \Omega \rightarrow \mathcal{X} : \omega \mapsto \omega(t)$ is trivially $\sigma(\mathcal{F})$ -measurable.

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Unfortunately, the **idealised variables** w.r.t. $(X_t)_{t \in \mathbb{R}_{\geq 0}}$ are not $\sigma(\mathcal{F})$ -measurable!



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Unfortunately, the **idealised variables** w.r.t. $(X_t)_{t \in \mathbb{R}_{\geq 0}}$ are not $\sigma(\mathcal{F})$ -measurable!



Under some **⌘ continuity condition ⌘** on P , there is a modification $(Y_t)_{t \in \mathbb{R}_{\geq 0}}$ of $(X_t)_{t \in \mathbb{R}_{\geq 0}}$
– meaning that $Y_t : \Omega \rightarrow \mathcal{X}$ is $\sigma(\mathcal{F})$ -measurable and $P_\sigma(X_t = Y_t) = 1$ –
that has **càdlàg** sample paths.

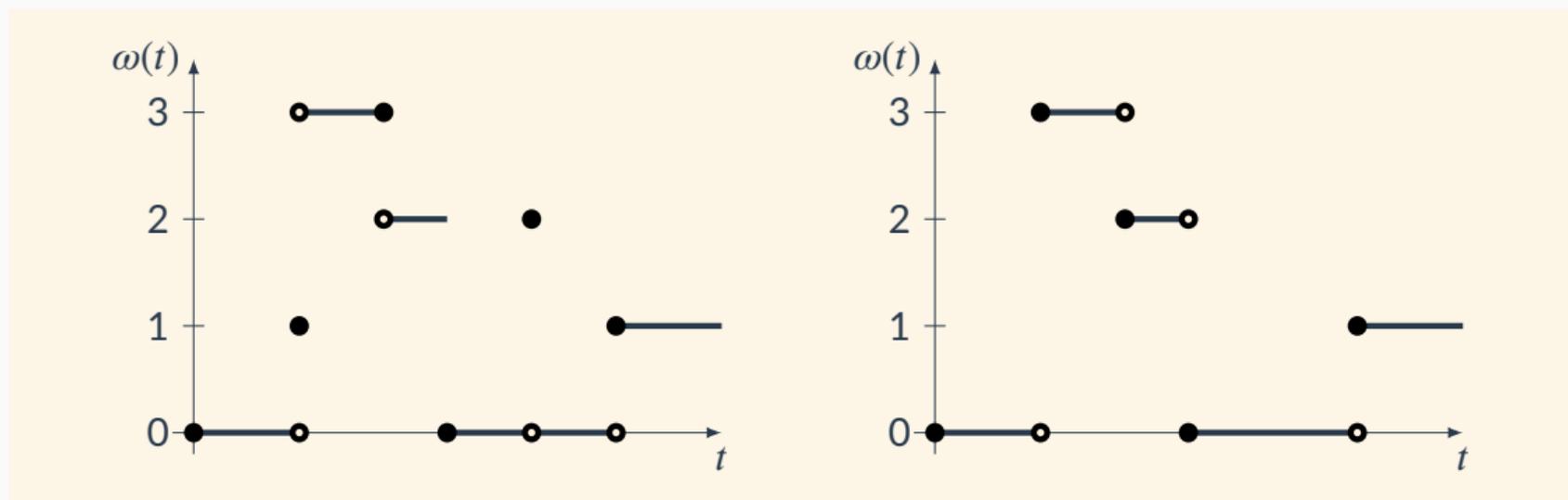
Càdlàg paths

A path $\omega : \mathbb{R}_{\geq 0} \rightarrow \mathcal{X}$ is **càdlàg** if it is continuous from the right and has limits from the left.

$$(\forall t \in \mathbb{R}_{\geq 0}) \lim_{\Delta \searrow 0} \omega(t + \Delta) = \omega(t) \quad \text{and} \quad (\forall t \in \mathbb{R}_{> 0}) \lim_{\Delta \searrow 0} \omega(t - \Delta) \text{ exists.}$$

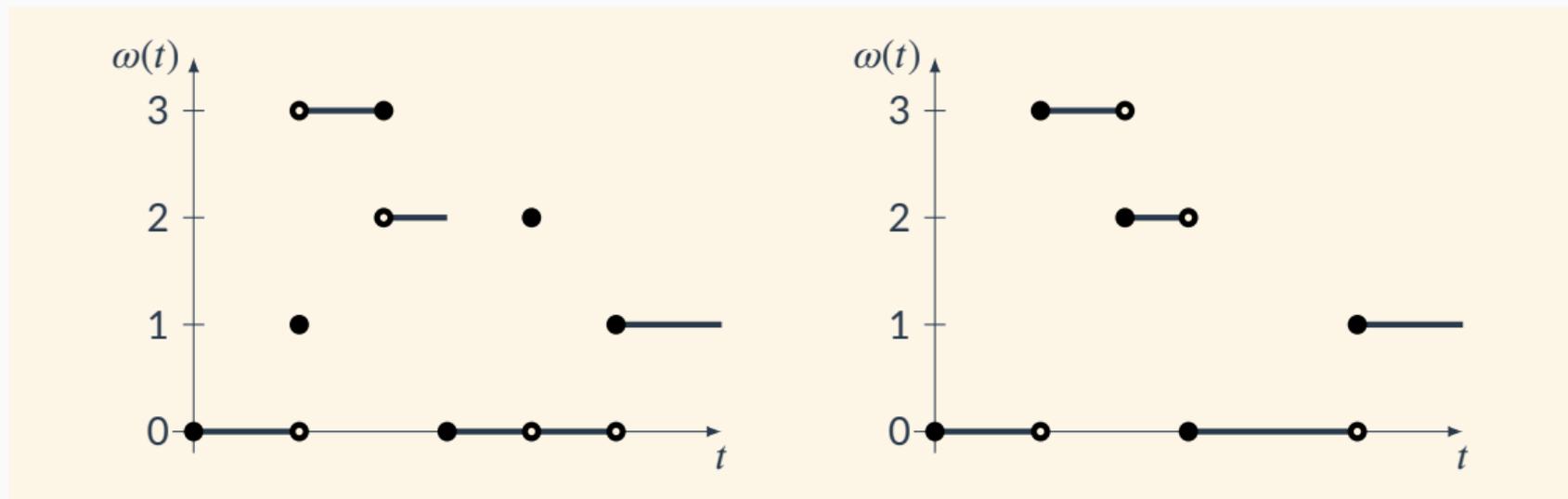
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Càdlàg paths

A path $\omega : \mathbb{R}_{\geq 0} \rightarrow \mathcal{X}$ is **càdlàg** if it is continuous from the right and has limits from the left.



Every càdlàg path $\omega : \mathbb{R}_{\geq 0} \rightarrow \mathcal{X}$ is fully defined by its values on any countable dense subset of $\mathbb{R}_{\geq 0}$.



Constructing a measure-theoretic model

$(\Omega, \sigma(\mathcal{F}), P_\sigma)$ is a probability space, and for all time points t in $\mathbb{R}_{\geq 0}$,

$X_t : \Omega \rightarrow \mathcal{X} : \omega \mapsto \omega(t)$ is trivially $\sigma(\mathcal{F})$ -measurable.



Unfortunately, the **idealised variables** w.r.t. $(X_t)_{t \in \mathbb{R}_{\geq 0}}$ are not $\sigma(\mathcal{F})$ -measurable!



Under some **⚡ continuity condition ⚡** on P , there is a modification $(Y_t)_{t \in \mathbb{R}_{\geq 0}}$ of $(X_t)_{t \in \mathbb{R}_{\geq 0}}$ that has **càdlàg** sample paths.



Therefore, the **idealised variables** w.r.t. $(Y_t)_{t \in \mathbb{R}_{\geq 0}}$ are $\sigma(\mathcal{F})$ -measurable!



Constructing a measure-theoretic model

$(\Omega, \sigma(\mathcal{F}), P_\sigma)$ is a probability space and for points $\omega \in \Omega$,
 $X_t : \Omega \rightarrow \mathbb{R}^d, \omega \mapsto \omega(t)$ is $\sigma(\mathcal{F}_t)$ -measurable.



Unfortunately, the ideal variables $(X_t)_{t \in \mathbb{R}_{\geq 0}}$ are not $\sigma(\mathcal{F})$ -measurable!



Under some ∞ continuity condition on P , there is a modification $(Y_t)_{t \in \mathbb{R}_{\geq 0}}$ of $(X_t)_{t \in \mathbb{R}_{\geq 0}}$ that has càdlàg sample paths.

Therefore, the ideal variables $(Y_t)_{t \in \mathbb{R}_{\geq 0}}$ are $\sigma(\mathcal{F})$ -measurable!



An alternative construction

Ω_{cl} is the set of all càdlàg maps from $\mathbb{R}_{\geq 0}$ to \mathcal{X}

\mathcal{F}_{cl} is the field of all cylinder events of the form $\{\omega \in \Omega_{\text{cl}} : (\omega(t_1), \dots, \omega(t_n)) \in A\}$



idealised variables are $\sigma(\mathcal{F}_{\text{cl}})$ -measurable

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P is a probability charge on \mathcal{F}_{cl}

⌘ continuity condition ⌘ $\Rightarrow P$ is σ -additive on \mathcal{F}_{cl}

P on \mathcal{F}_{cl}

↓ Carathéodory's Theorem

P_σ on $\sigma(\mathcal{F}_{\text{cl}})$

↓ Lebesgue integration

$E_{P_\sigma}^L$ on $\sigma(\mathcal{F}_{\text{cl}})$ -measurables

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idealised variables are $\sigma(\mathcal{F}_{\text{cl}})$ -measurable



idealised variables are the limit of
–monotone or uniformly bounded–
sequences of \mathcal{F}_{cl} -simples

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$E_{P_\sigma}^L$ on $\sigma(\mathcal{F}_{\text{cl}})$ -measurables

E_P on \mathcal{F}_{cl} -simples

↓ Daniell integration

E_P^D on 'limits of \mathcal{F}_{cl} -simples'

Markovian jump process

A **jump process** P on \mathcal{F}_{cl} is completely defined by the initial probabilities of the form

$$P(X_0 = x_0)$$

and the transition probabilities of the form

$$P(X_{t+\Delta} = y \mid X_{t_1} = x_1, \dots, X_{t_n} = x_n, X_t = x).$$

Markovian jump process

A **Markovian** jump process P on \mathcal{F}_{cl} is completely defined by the initial probabilities of the form

$$P(X_0 = x_0)$$

and the transition probabilities of the form

$$P(X_{t+\Delta} = y \mid X_{t_1} = x_1, \dots, X_{t_n} = x_n, X_t = x) = P(X_{t+\Delta} = y \mid X_t = x).$$

Markovian jump process

A **homogeneous** Markovian jump process P on \mathcal{F}_{c1} is completely defined by the initial probabilities of the form

$$P(X_0 = x_0)$$

and the transition probabilities of the form

$$P(X_{t+\Delta} = y \mid X_{t_1} = x_1, \dots, X_{t_n} = x_n, X_t = x) = P(X_\Delta = y \mid X_0 = x).$$

Markovian jump process

A homogeneous Markovian jump process P on \mathcal{F}_{cl} is completely defined by the initial probabilities of the form

$$P(X_0 = x_0)$$

and the transition probabilities of the form

$$P(X_{t+\Delta} = y \mid X_{t_1} = x_1, \dots, X_{t_n} = x_n, X_t = x) = P(X_\Delta = y \mid X_0 = x).$$

Whenever it satisfies the **strong continuity condition**, the homogeneous Markovian jump process P is completely defined by its

initial distribution p : $p(x_0) = P(X_0 = x_0)$

(transition) rate matrix Q : $Q(x, y) = \frac{d}{d\Delta} P(X_\Delta = y \mid X_0 = x).$

-  Damjan Škulj. “Efficient computation of the bounds of continuous time imprecise Markov chains”. In: *AMC* 250 (2015), pp. 165–180
-  Thomas Krak, Jasper De Bock, and Arno Siebes. “Imprecise continuous-time Markov chains”. In: *IJAR* 88 (2017), pp. 452–528
-  Max Nendel. *Markov chains under nonlinear expectation*. 2019. arXiv: 1803.03695
[math.PR]

Imprecise jump process



Thomas Krak, Jasper De Bock, and Arno Siebes. “Imprecise continuous-time Markov chains”. In: *IJAR* 88 (2017), pp. 452–528

a **set** \mathcal{P} of initial distributions and a **set** \mathcal{Q} of rate matrices



$\mathcal{P}_{\mathcal{P},\mathcal{Q}}$ consists of all jump processes P that are **consistent** with \mathcal{P} and \mathcal{Q}



$\underline{E}_{\mathcal{P},\mathcal{Q}}$ is the **lower envelope** of $\{E_P : P \in \mathcal{P}_{\mathcal{P},\mathcal{Q}}\}$: for any \mathcal{F}_{cl} -simple variable f ,

$$\underline{E}_{\mathcal{P},\mathcal{Q}}(f) := \inf \{E_P(f) : P \in \mathcal{P}_{\mathcal{P},\mathcal{Q}}\}$$

Extending a Markovian imprecise jump process

a set \mathcal{P} of initial distributions and a set \mathcal{Q} of rate matrices

$\mathcal{P}_{\mathcal{P},\mathcal{Q}}$ is the set of all jump processes P that are consistent with \mathcal{P} and \mathcal{Q}

\mathcal{Q} **bounded** \Rightarrow every P in $\mathcal{P}_{\mathcal{P},\mathcal{Q}}$ satisfies the \mathbb{R}^{\otimes} continuity condition \mathbb{R}^{\otimes}

$(\forall P \in \mathcal{P}_{\mathcal{P},\mathcal{Q}}) E_P$ on \mathcal{F}_{cl} -simples $\xrightarrow{\text{Daniell integration}}$ E_P^D on 'limits of \mathcal{F}_{cl} -simples'

$\underline{E}_{\mathcal{P},\mathcal{Q}}$ is the lower envelope of $\{E_P^D : P \in \mathcal{P}_{\mathcal{P},\mathcal{Q}}\}$

For a jump process P that satisfies the ϵ -continuity condition ϵ , E_P^D

⚙ satisfies monotone convergence; [~ Monotone Convergence Theorem]

⚙ satisfies uniformly bounded convergence. [~ Lebesgue's Dominated Convergence Theorem]

For a jump process P that satisfies the ⚙️ continuity condition ⚙️ , E_P^D

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If \mathcal{Q} is bounded, the lower envelope $\underline{E}_{P, \mathcal{Q}}$

🎉 satisfies monotone convergence from above;

😐 is **conservative** for monotone convergence from below;

😐 is **conservative** for uniformly bounded point-wise convergence.

For a jump process P that satisfies the ⚙️ continuity condition ⚙️ , E_P^D

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If \mathcal{Q} is bounded, the lower envelope $\underline{E}_{P, \mathcal{Q}}$

🎉 satisfies monotone convergence from above;

😐 is conservative for monotone convergence from below;

😐 is conservative for uniformly bounded point-wise convergence;

😄 is **continuous** for idealised inferences over $[0, T]$. (temporal averages, hitting times and hitting events)

 Is $\underline{E}_{\rho, \mathcal{Q}}$ continuous for idealised inferences over $\mathbb{R}_{\geq 0}$?

 Is $\underline{E}_{\rho, \mathcal{Q}}$ continuous for a larger class of idealised inferences?

 Why not extend $\underline{E}_{\rho, \mathcal{Q}}$ directly?

 How does this compare to the framework of (Nendel, 2018)?