

Efficient computation of Sturm-Liouville eigenvalues using modified Neumann schemes

V. Ledoux and M. Van Daele

Department of Applied Mathematics and Computer Science
Ghent university

ICNAAM 2009

The Sturm-Liouville problem



Jacques Sturm (1803-1855)



Joseph Liouville (1809-1882)

$$-\frac{d}{dx} \left[p(x) \frac{dy(x)}{dx} \right] + q(x)y(x) = Ew(x)y(x)$$

The Sturm-Liouville problem

$$-\frac{d}{dx} \left[p(x) \frac{dy(x)}{dx} \right] + q(x)y(x) = Ew(x)y(x), \quad x \in (a, b)$$

- One-dimensional model of many important physical processes which often exhibit a pronounced **oscillatory** behaviour
 - behaviour of pendulum-like systems
 - vibrations
 - resonances
 - wave propagation
- Description of quantum mechanical systems (atoms, transistors): the **Schrödinger equation**

$$\frac{d^2 y}{dx^2} = [V(x) - E]y(x)$$

The Sturm-Liouville boundary value problem

$$-\frac{d}{dx} \left[p(x) \frac{dy(x)}{dx} \right] + q(x)y(x) = Ew(x)y(x), \quad x \in [a, b]$$

- Boundary conditions (BCs):

$$\begin{cases} a_0y(a) + b_0p(a)y'(a) = 0, \\ a_1y(b) + b_1p(b)y'(b) = 0 \end{cases}$$

- **Eigenvalue**: E for which there exists a nonzero solution y satisfying the BCs.
- **Eigenfunction**: corresponding solution y .

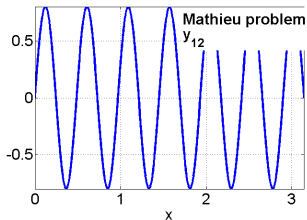
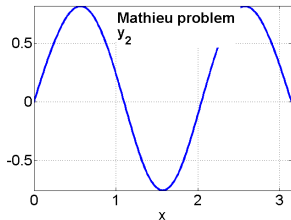
Oscillatory character of the eigenfunctions

For a regular Sturm-Liouville problem

- The E_k can be ordered as an increasing sequence tending to infinity,

$$E_0 < E_1 < E_2 < \dots$$

- The eigenfunction $y_k(x)$ corresponding to E_k has **exactly k zeros** on (a, b) .
- A higher eigenfunction is oscillating 'more rapidly' than a lower eigenfunction.



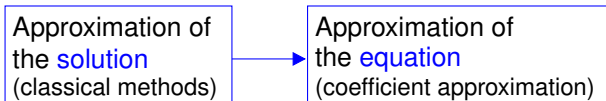
Numerical solution of SLPs

Naive methods

- The oscillatory behaviour of the solutions forces a standard integrator to take increasingly smaller steps.

Coefficient approximation

- Special techniques are needed which adequately take into account the oscillatory character of the solution.
- Replace the diff. eq. (piecewisely) by a diff. eq. which can be solved exactly.



Coefficient approximation methods

$$-(p(x)y'(x))' + q(x)y(x) = Ew(x)y(x)$$

p, q, w are replaced piecewisely by **low degree polynomials**

Coefficient approximation methods

$$-(p(x)y'(x))' + q(x)y(x) = Ew(x)y(x)$$

p, q, w are replaced piecewisely by **low degree polynomials**

Constants (Pruess method)

S. Pruess and C. T. Fulton, ACM Trans. Math. Software 19 (1993)

- The problem is solved analytically on the piecewise-constant intervals
- Eigenvalues E_k are computed in a shooting process
- The accuracy is maintained or even improves when k increases.
- But only second order

Coefficient approximation methods

$$-(p(x)y'(x))' + q(x)y(x) = Ew(x)y(x)$$

p, q, w are replaced piecewisely by **low degree polynomials**

Higher order polynomials?

- Analytic integration not so easy
- Schrödinger: piecewise perturbation methods

L. Gr. Ixaru, H. De Meyer and G. Vanden Berghe, JCAM 88 (1997)

V. L., M. Van Daele and G. Vanden Berghe, CPC 162 (2004)

...

- General SLP: **Modified Neumann schemes**

Neumann expansion

Consider a matrix linear ODE

$$y' = A(t)y, \quad y(0) = y_0 \in \mathbb{R}$$

The Neumann expansion is

$$\begin{aligned} y(t) = & y_0 \left(1 + \int_0^t A(\tau) d\tau + \int_0^t A(\tau) \int_0^\tau A(\tau_1) d\tau_1 d\tau \right. \\ & \left. + \int_0^t A(\tau) \int_0^\tau A(\tau_1) \int_0^{\tau_1} A(\tau_2) d\tau_2 d\tau_1 d\tau + \dots \right) \end{aligned}$$

Neumann expansion

Consider a matrix linear ODE

$$y' = A(t)y, \quad y(0) = y_0 \in \mathbb{R}$$

The Neumann expansion is

$$\begin{aligned} y(t) = & y_0 \left(1 + \int_0^t A(\tau) d\tau + \int_0^t A(\tau) \int_0^\tau A(\tau_1) d\tau_1 d\tau \right. \\ & \left. + \int_0^t A(\tau) \int_0^\tau A(\tau_1) \int_0^{\tau_1} A(\tau_2) d\tau_2 d\tau_1 d\tau + \dots \right) \end{aligned}$$

- A SLP can be written in the form $Y' = A(x)Y$:

$$\begin{bmatrix} y(x) \\ p(x)y'(x) \end{bmatrix}' = \begin{bmatrix} 0 & 1/p(x) \\ q(x) - Ew(x) & 0 \end{bmatrix} \begin{bmatrix} y(x) \\ p(x)y'(x) \end{bmatrix}.$$

- Apply Neumann series integrator directly?

The modified Neumann method

Iserles (2002), Degani and Schiff (2006): when the solution of $y' = A(x)y$ oscillates rapidly, a modified scheme should be used

Over each step:

- The variables are changed locally:

$$Y(x) = e^{(x-x_i)\bar{A}}U(x - x_i), \quad x \in [x_i, x_{i+1}]$$

where

$$\bar{A}(E) = \begin{bmatrix} 0 & 1/\bar{\rho} \\ \bar{q} - E\bar{w} & 0 \end{bmatrix}$$

i.e. we precondition Y locally by the known solution of a linear system with constant coefficients.

The modified Neumann method

Iserles (2002), Degani and Schiff (2006): when the solution of $y' = A(x)y$ oscillates rapidly, a modified scheme should be used

Over each step:

- The variables are changed locally:

$$Y(x) = e^{(x-x_i)\bar{A}}U(x - x_i), \quad x \in [x_i, x_{i+1}]$$

where

$$\bar{A}(E) = \begin{bmatrix} 0 & 1/\bar{\rho} \\ \bar{q} - E\bar{w} & 0 \end{bmatrix}$$

i.e. we precondition Y locally by the known solution of a linear system with constant coefficients.

- We solve

$$U'(\delta) = B(\delta)U(\delta), \quad U(0) = Y_i, \quad \delta = x - x_i \in [0, h_i]$$

by the Neumann method

The modified Neumann method

The new linear system $U'(\delta) = B(\delta)U(\delta)$ has some crucial advantages over the original system:

- The entries of $B = e^{-\delta\bar{A}} (A(x_i + \delta) - \bar{A}) e^{\delta\bar{A}}$ are rapidly oscillating functions.
- Integration is a “smoothing” operator:
The faster B oscillates, the smaller are the Neumann integrals, thus the faster the convergence and the smaller the error

The modified Neumann scheme

Over interval step size h :

$$\textcircled{1} U(h) = Y_i + \int_0^h B(x) dx Y_i + \int_0^h \int_0^{x_1} B(x_1) B(x_2) dx_2 dx_1 Y_i + \dots$$

$$\textcircled{2} Y_{i+1} = e^{h\bar{A}} U(h)$$

Note: $e^{h\bar{A}}$ is known solution of system with constant coeff. functions

Practical Implementation

- Truncation of the integral series
- Replacement of integrals by quadrature:
 - Classical methods useless in the presence of high oscillation
 - Filon quadrature delivers accuracy which improves with higher oscillation. (A. Iserles, S. Nørsett,...)

Results: Collatz problem

$$y'' + \frac{3}{4x^2}y = -\frac{1}{x^6}Ey \quad \text{in } [1, 2], \quad y(1) = y(2) = 0.$$

Collatz				
k	E_k		Pruess	MNM6
0	70.1836836876		2.1(-6)	1.9(-9)
25	47444.18579306		2.1(-6)	5.0(-6)
50	182548.2030025		2.1(-6)	3.3(-6)
75	405381.9379249		2.1(-6)	3.1(-6)
100	715945.489746		2.2(-6)	4.1(-6)
125	1114238.858465		2.2(-6)	3.0(-6)
150	1600262.044083		2.3(-6)	7.5(-7)
nsteps			1024	32
nfevs			3072	288

Table: The relative errors in some eigenvalue approximations computed by the second order Pruess method and the sixth order Modified Neumann Method (MNM6). The notation $a(-b)$ stands for $a \cdot 10^{-b}$.

Results: Paine problem

$$p(x) = (\gamma + x)^3, \quad q(x) = 4(\gamma + x), \quad w(x) = (\gamma + x)^5, \quad \gamma = \sqrt{0.2}$$

$$y(0) = y(-\gamma + \sqrt{\gamma^2 + 2\pi}) = 0$$

Paine				
k	E_k		Pruess	MNM6
0	1.5198658211		3.4(-6)	1.2(-9)
5	37.9644258619		5.6(-6)	6.0(-8)
10	123.4977068009		6.0(-6)	2.1(-7)
20	443.8529598352		6.2(-6)	7.1(-7)
30	963.9644462621		6.2(-6)	1.7(-6)
40	1684.0120143379		6.2(-6)	2.4(-6)
50	2604.0363320246		6.2(-6)	5.2(-6)
nsteps			1024	48
nfevs			3072	432

Table: The relative errors in some eigenvalue approximations computed by the second order Pruess method and the sixth order Modified Neumann Method (MNM6).

Results: Collatz problem

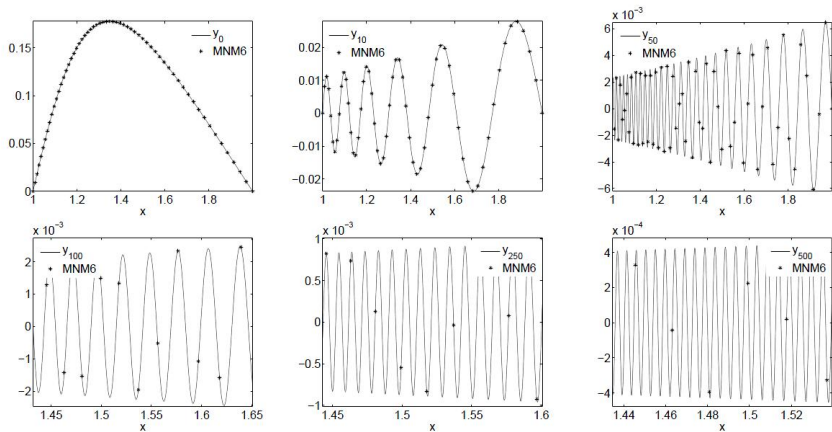


FIG. 6.1. Sample eigenfunction computations of Collatz problem for $k = 0, 10, 50, 100, 250, 500$. For $k = 100, 250, 500$ only part of the eigenfunction is shown. The mesh contains only 31 mesh points.

Summary

- For high eigenvalues the solution is severely oscillatory and standard numerical integrators have to advance in small steps.
- Better results are obtained using coefficient approximation methods in a shooting procedure.
- Neumann series integrators allow the construction of higher order coefficient approximation methods.
 - modified schemes should be used.
 - “Oscillation-proof” quadrature
 - Can be applied directly to a Sturm-Liouville problem (no expensive Liouville’s transformation needed)