

Exponentially fitted methods applied to fourth-order boundary value problems

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Outline

Introduction

- A model problem
- Exponential fitting

Fourth-order boundary value problems

- The problem
- Exponentially-fitted methods
- Parameter selection

Numerical Illustrations

- First example
- About the conditioning
- Second example

Conclusions

Introduction

In the past 15 years, our research group has constructed modified versions of well-known

- linear multistep methods
- Runge-Kutta methods

Aim : build methods which perform very good when the solution has a known exponential or trigonometric behaviour.

A model problem

Consider the initial value problem

$$y'' + \omega^2 y = g(y) \quad y(a) = y_a \quad y'(a) = y'_a.$$

If $|g(y)| \ll |\omega^2 y|$ then

$$y(t) \approx \alpha \cos(\omega t + \phi)$$

To mimic this oscillatory behaviour, we construct methods which yield exact results when the solution is of trigonometric (in the complex case : exponential) type.

These methods are called **Exponentially-fitted methods**.

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EF methods

To determine the coefficients of a method, we impose conditions on a linear functional. These conditions are related to the **fitting space** \mathcal{S} which contains

- polynomials :

$$\{t^q | q = 0, \dots, K\}$$

- exponential or trigonometric functions, multiplied with powers of t :

$$\{t^q \exp(\pm \mu t) | q = 0, \dots, P\}$$

or, with $\omega = i\mu$,

$$\{t^q \cos(\omega t), t^q \sin(\omega t) | q = 0, \dots, P\}$$

EF method can be characterized by the couple (K, P)

Classical method : $P = -1$

number of basis functions : $M = 2P + K + 3$

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(K, P)				
$M = 2$	$M = 4$	$M = 6$	$M = 8$	$M = 10$
$(1, -1)$	$(3, -1)$	$(5, -1)$	$(7, -1)$	$(9, -1)$
$(-1, 1)$	$(1, 0)$	$(3, 0)$	$(5, 0)$	$(7, 0)$
	$(-1, 1)$	$(1, 1)$	$(3, 1)$	$(5, 1)$
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			$(-1, 3)$	$(1, 3)$
				$(-1, 4)$

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Exponential Fitting



L. Ixaru and G. Vanden Berghe

Exponential fitting

Kluwer Academic Publishers, Dordrecht, 2004

$$\eta_{-1}(Z) = \begin{cases} \cos(|Z|^{1/2}) & \text{if } Z < 0 \\ \cosh(Z^{1/2}) & \text{if } Z \geq 0 \end{cases}$$

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$$\eta_n(Z) := \frac{1}{Z}[\eta_{n-2}(Z) - (2n-1)\eta_{n-1}(Z)], \quad n = 1, 2, 3, \dots$$

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 ω is step-dependent
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Fourth-order boundary value problem

$$y^{(4)} = F(t, y) \quad a \leq t \leq b$$

$$y(a) = A_1 \quad y''(a) = A_2$$

$$y(b) = B_1 \quad y''(b) = B_2$$

- special case : $y^{(4)} + f(t)y = g(t)$
- mathematical modeling of viscoelastic and inelastic flows, deformation of beams, plate deflection theory, ...
- work by Doedel, Usmani, Agarwal, Cherruault et al., Van Daele et al., ...
- finite differences, B-splines, ...

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The formulae

$$t_j = a + jh, j = 0, 1, \dots, N+1 \quad N \geq 5 \quad h := \frac{b-a}{N+1}$$

- central formula for $j = 2, \dots, N-1$

$$y_{j-2} + a_1 y_{j-1} + a_0 y_j + a_1 y_{j+1} + y_{j+2} = h^4 (b_2 F_{j-2} + b_1 F_{j-1} + b_0 F_j + b_1 F_{j+1} + b_2 F_{j+2})$$

whereby y_j is approximate value of $y(t_j)$ and $F_j := F(t_j, y_j)$.

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$$c_1 y_0 + c_2 y_1 + c_3 y_2 + y_3 = d_1 h^2 y_0'' + h^4 (d_2 F_0 + d_3 F_1 + d_4 F_2 + d_5 F_3 + d_6 F_4 + d_7 F_5)$$

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- **end formula**

Central formula

$$\mathcal{L}[y] := y(t-2h) + a_1 y(t-h) + a_0 y(t) + a_1 y(t+h) + y(t+2h) \\ - h^4 \left(b_2 y^{(4)}(t-2h) + b_1 y^{(4)}(t-h) + b_0 y^{(4)}(t) + b_1 y^{(4)}(t+h) + b_2 y^{(4)}(t+2h) \right)$$

$$P = -1 : \mathcal{S} = \left\{ 1, t, t^2, \dots, t^{M-1} \right\}$$

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case $M = 10$: order 6

$$y_{p-2} - 4y_{p-1} + 6y_p - 4y_{p+1} + y_{p+2} = \\ \frac{h^4}{720} \left(-y_{p-2}^{(4)} + 124y_{p-1}^{(4)} + 474y_p^{(4)} + 124y_{p+1}^{(4)} - y_{p+2}^{(4)} \right)$$

$$\mathcal{L}[y](t) = \frac{1}{3024} h^{10} y^{(10)}(t) + \mathcal{O}(h^{12})$$

Central formula

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case $M = 8$ and $b_2 = 0$: order 4

$$y_{p-2} - 4y_{p-1} + 6y_p - 4y_{p+1} + y_{p+2} = \frac{h^4}{6} \left(y_{p-1}^{(4)} + 4y_p^{(4)} + y_{p+1}^{(4)} \right)$$

$$\mathcal{L}[y](t) = -\frac{1}{720} h^8 y^{(8)}(t) + \mathcal{O}(h^{10})$$

Central formula

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case $M = 6$ and $b_1 = b_2 = 0$: order 2

$$y_{p-2} - 4y_{p-1} + 6y_p - 4y_{p+1} + y_{p+2} = h^4 y_p^{(4)}$$

$$\mathcal{L}[y](t) = \frac{1}{6} h^6 y^{(6)}(t) + \mathcal{O}(h^8)$$

EF Central formula

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case $M = 10$:

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$$b_0 = \frac{4 \cos^2 \theta - 2 - 11 \cos \theta}{6 (\cos \theta - 1)^2} + \frac{6}{\theta^4} \quad b_1 = \frac{\cos^2 \theta + 5}{6 (\cos \theta - 1)^2} - \frac{4}{\theta^4} \quad b_2 = -\frac{\cos \theta + 2}{12 (\cos \theta - 1)^2} + \frac{1}{\theta^4}$$

$$\mathcal{L}[y](t) = \frac{1}{3024} h^{10} \left(y^{(10)}(t) + \omega^2 y^{(8)}(t) \right) + \mathcal{O}(h^{12})$$

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$$b_0 = \frac{\cos \theta}{\cos \theta - 1} + \frac{4(1 - \cos \theta)}{\theta^4} \quad b_1 = \frac{1}{2(1 - \cos \theta)} + \frac{2(\cos \theta - 1)}{\theta^4}$$

$$\mathcal{L}[y](t) = -\frac{1}{720} h^8 \left(y^{(8)}(t) + \omega^2 y^{(6)}(t) \right) + \mathcal{O}(h^{10})$$

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case $M = 6$ and $b_1 = b_2 = 0$:

$$y_{p-2} - 4y_{p-1} + 6y_p - 4y_{p+1} + y_{p+2} = \frac{\sin^4(\theta/2)}{(\theta/2)^4} h^4 y_p^{(4)}$$

$$\mathcal{L}[y](t) = \frac{1}{6} h^6 (y^{(6)}(t) + \omega^2 y^{(4)}(t)) + \mathcal{O}(h^8)$$

EF Central formula

$$\mathcal{L}[y] := y(t-2h) + a_1 y(t-h) + a_0 y(t) + a_1 y(t+h) + y(t+2h) \\ - h^4 \left(b_2 y^{(4)}(t-2h) + b_1 y^{(4)}(t-h) + b_0 y^{(4)}(t) + b_1 y^{(4)}(t+h) + b_2 y^{(4)}(t+2h) \right)$$

$$P = 1 : \mathcal{S} = \left\{ \cos(\omega t), \sin(\omega t), t \cos(\omega t), t \sin(\omega t), 1, t, t^2, \dots, t^{M-5} \right\}$$

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case $M = 6$ and $b_1 = b_2 = 0$:

$$y_{p-2} + a_1 y_{p-1} + a_0 y_p + a_1 y_{p+1} + y_{p+2} = b_0 h^4 y_p^{(4)}$$

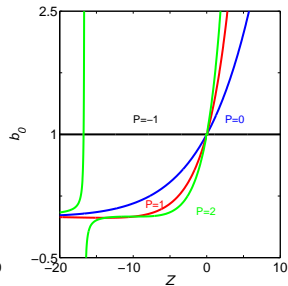
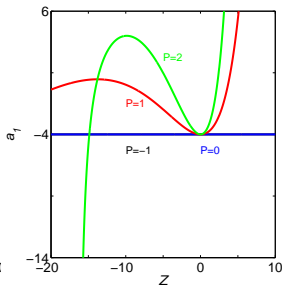
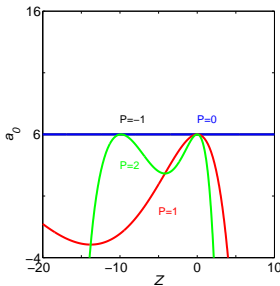
$$a_0 = 2 \frac{-8 \sin^2 \theta + \theta (4 \cos \theta - 1) \sin \theta - 4 \cos \theta + 4}{\theta \sin \theta + 4 \cos \theta - 4} \quad a_1 = -4 \frac{\sin \theta (\theta \cos \theta - 2 \sin \theta)}{\theta \sin \theta + 4 \cos \theta - 4}$$

$$b_0 = 4 \frac{\sin \theta (\sin^2 \theta - 2 + 2 \cos \theta)}{\theta^3 (\theta \sin \theta + 4 \cos \theta - 4)}$$

Coefficients of central formula

e.g. case $M = 6$:

$$y_{p-2} + a_1 y_{p-1} + a_0 y_p + a_1 y_{p+1} + y_{p+2} = b_0 h^4 y_p^{(4)}$$



$$Z = (\mu h)^2 = -(\omega h)^2$$

Coefficients of central formula

e.g. case $M = 6$

- $P = -1$:

$$b_0 = 1$$

- $P = 0$:

$$b_0 = 4 \frac{(\cos \theta - 1)^2}{\theta^4}$$

- $P = 1$:

$$b_0 = -4 \frac{\sin \theta (\cos \theta - 1)^2}{\theta^3 (4 \cos \theta - 4 + \theta \sin \theta)}$$

- $P = 2$:

$$b_0 = -2 \frac{\sin^3 \theta}{\theta^2 (\theta \cos \theta - 3 \sin \theta)}$$

Central formula : coefficients

e.g. case $M = 6$

- $P = -1$:

$$b_0 = 1$$

- $P = 0$:

$$b_0 = 1 - \frac{1}{6}\theta^2 + \frac{1}{80}\theta^4 + \mathcal{O}(\theta^6)$$

- $P = 1$:

$$b_0 = 1 - \frac{1}{3}\theta^2 + \frac{37}{720}\theta^4 + \mathcal{O}(\theta^6)$$

- $P = 2$:

$$b_0 = 1 - \frac{1}{2}\theta^2 + \frac{7}{60}\theta^4 + \mathcal{O}(\theta^6)$$

Central formula : local truncation error

$$\text{lte} = \mathcal{L}[y](t)$$

As an **inifinite series** :

$$\text{lte} = h^M C_M D^{K+1} (D^2 + \omega^2)^{P+1} y(t) + \mathcal{O}(h^{M+2})$$

In **closed form** : (Coleman and Ixaru)

$$\text{lte} = h^M \Phi_{K,P}(Z) D^{K+1} (D^2 + \omega^2)^{P+1} y(\xi)$$

$$Z \in \text{some interval} \quad \Phi_{K,P}(0) \neq 0 \quad \xi \in (t - 2h, t + 2h)$$

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- $P = 0 :$

$$y^{(K+3)}(t_j) + y^{(K+1)}(t_j) \omega_j^2 = 0$$

- $P = 1 :$

$$y^{(K+5)}(t_j) + 2 y^{(K+3)}(t_j) \omega_j^2 + y^{(K+1)}(t_j) \omega_j^4 = 0$$

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$$y^{(K+7)}(t_j) + 3 y^{(K+5)}(t_j) \omega_j^4 + 3 y^{(K+3)}(t_j) \omega_j^4 + y^{(K+1)}(t_j) \omega_j^6 = 0$$

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Parameter selection

$$\text{lte} = h^M C_M D^{K+1} (D^2 - \mu^2)^{P+1} y(t) + \mathcal{O}(h^{M+2})$$

Suppose $y(t)$ takes the form $t^{P_0} e^{\mu_0 t}$

Then $\text{lte} = 0$ for any EF rule with $P \geq P_0$ and $\mu_j = \mu_0$

Theorem

If $y(t) = t^{P_0} e^{\mu_0 t}$ then $\nu = \mu_0^2$ is a root of multiplicity $P - P_0 + 1$ of $D^{K+1} (D^2 - \nu)^{P+1} y(t) = 0$.

- if $P = P_0$, then $\mu = \mu_0$ will be a single root
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Suppose $y(t)$ does not take the form $t^{P_0} e^{\mu_0 t}$.

Then $y(t) \notin \mathcal{S}$ for any P .

For a given value of P :

$$D^{(K+1)} (D^2 - \mu_j^2)^{(P+1)} y(t) \Big|_{t=t_j} = 0$$

At each point t_j , this gives $P + 1$ values for μ_j^2 .

Idea : keep $|\mu_j h|$ as small as possible.

If possible, choose $P \geq 1$ to avoid too large values for $|\mu_j|$.

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Numerical Illustrations

Problem 1

$$y^{(4)} - \frac{384 t^4}{(2 + t^2)^4} y = 24 \frac{2 - 11 t^2}{(2 + t^2)^4}$$

$$y(-1) = \frac{1}{3} \quad y(1) = \frac{1}{3}$$

$$y''(-1) = \frac{2}{27} \quad y''(1) = \frac{2}{27}$$

$$\text{Solution : } y(t) = \frac{1}{2 + t^2}$$

Since $y(t)$ does not belong to the fitting space of a EF-rule, the parameter μ will not be constant over the interval of integration.

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Solution obtained by a fourth-order EF method

Computation of μ_j with $M = 8$:

$$P = 0 : y^{(8)}(t_j) - y^{(6)}(t_j) \mu_j^2 = 0$$

- re-express higher order derivatives in terms of y , y' , y'' and y'''
- approximate y' , y'' and y''' in terms of y
- an initial approximation for y can be computed with the classical, polynomial rule

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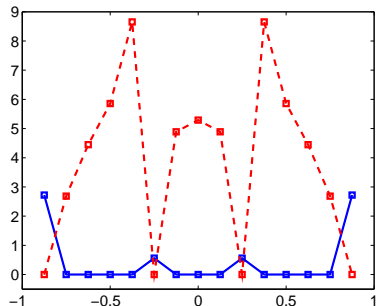
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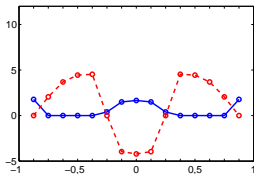
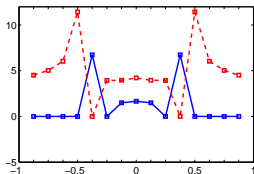


Real and imaginary part
of μ_j

Solution obtained by a fourth-order EF method

Computation of μ_j with $M = 8$:

$$P = 1 : y^{(8)}(t_j) - 2y^{(6)}(t_j)\mu_j^2 + y^{(4)}(t_j)\mu_j^4 = 0$$

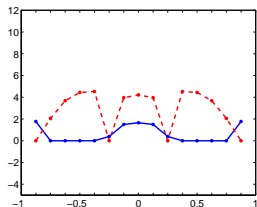
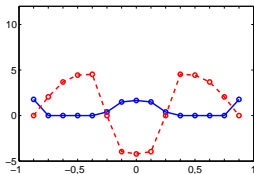
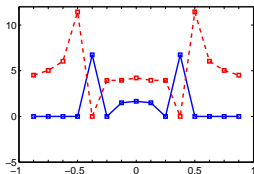


Real and imag. part of $\mu_{1,j}$ and $\mu_{2,j}$

Solution obtained by a fourth-order EF method

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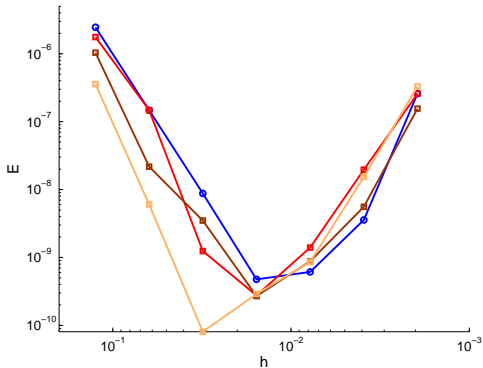
Real and imag. part of μ_j with smallest norm

Real and imag. part of $\mu_{1,j}$ and $\mu_{2,j}$

Solution obtained by a fourth-order EF method

Computation of μ_j with $M = 8$:

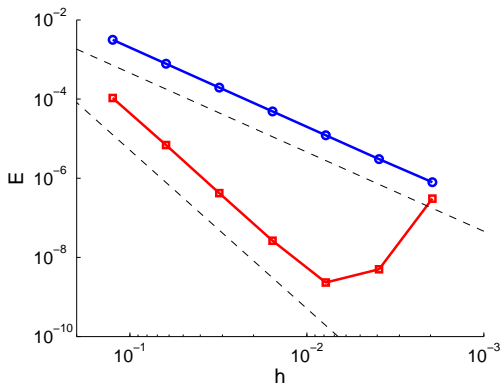
$$P = 1 : y^{(8)}(t_j) - 2y^{(6)}(t_j)\mu_j^2 + y^{(4)}(t_j)\mu_j^4 = 0$$



error obtained with $\mu_{1,j}$, $\mu_{2,j}$ and μ with smallest norm

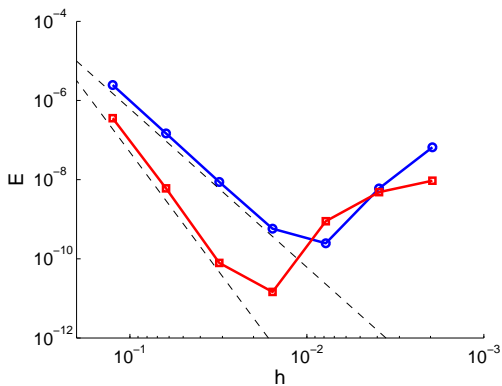
Global error

$M = 6$: $(K, P) = (5, -1)$: second-order method
 $(K, P) = (1, 1)$: fourth-order method



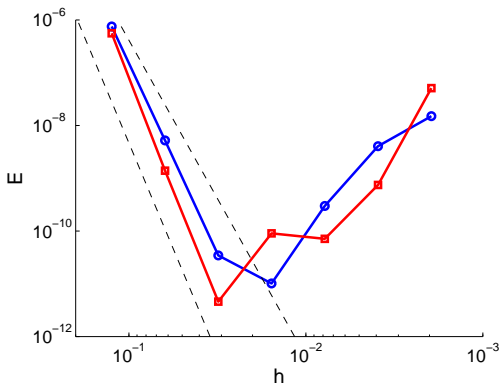
Global error

$M = 8$: $(K, P) = (7, -1)$: fourth-order method
 $(K, P) = (3, 1)$: sixth-order method

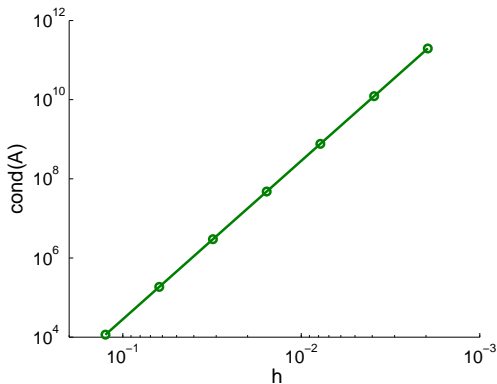


Global error

$M = 10$: $(K, P) = (9, -1)$: sixth-order method
 $(K, P) = (5, 1)$: eighth-order method



Condition number of the coefficient matrix



Condition number of the coefficient matrix

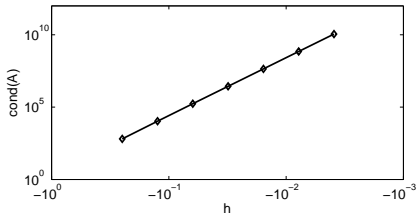
The (classical) discretisation of $y_p^{(4)}$ gives rise to the coefficient matrix

$$\begin{pmatrix} 5 & -4 & 1 & & & & & & \\ -4 & 6 & -4 & 1 & & & & & \\ 1 & -4 & 6 & -4 & 1 & & & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & & & \\ & & 1 & -4 & 6 & -4 & 1 & & \\ & & & 1 & -4 & 6 & -4 & & \\ & & & & 1 & -4 & 5 & & \end{pmatrix}$$

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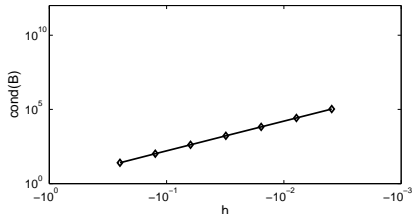
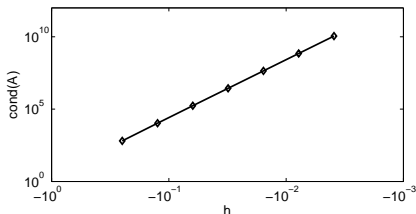




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Factorisation of the coefficient matrix

$$\begin{pmatrix} c_2 & c_3 & 1 & & & & \\ a_1 & a_2 & a_1 & 1 & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & \\ & & 1 & a_1 & a_2 & a_1 & 1 \\ & & & 1 & a_1 & a_2 & a_1 \\ & & & & 1 & c_3 & c_2 \end{pmatrix} = \begin{pmatrix} a_2 - 1 & a_1 & 1 & & & & \\ a_1 & a_2 & a_1 & 1 & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & \\ & & & 1 & a_1 & a_2 & a_1 & 1 \\ & & & & 1 & a_1 & a_2 & a_1 \\ & & & & & 1 & a_1 & a_2 - 1 \end{pmatrix}$$

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$$\begin{pmatrix} c_2 & c_3 & 1 & & & & \\ a_1 & a_2 & a_1 & 1 & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & \\ & & 1 & a_1 & a_2 & a_1 & 1 \\ & & & 1 & a_1 & a_2 & a_1 \\ & & & & 1 & c_3 & c_2 \end{pmatrix} = \begin{pmatrix} a_2 - 1 & a_1 & 1 & & & & \\ a_1 & a_2 & a_1 & 1 & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & \\ & & 1 & a_1 & a_2 & a_1 & 1 \\ & & & 1 & a_1 & a_2 & a_1 \\ & & & & 1 & a_1 & a_2 \\ & & & & & 1 & a_1 \\ & & & & & & 1 & a_1 \\ & & & & & & & 1 & a_2 - 1 \end{pmatrix} \\
 = \begin{pmatrix} \alpha & 1 & & & & & \\ 1 & \alpha & 1 & & & & \\ & \ddots & \ddots & \ddots & & & \\ & & 1 & \alpha & 1 & & \\ & & & 1 & \alpha \end{pmatrix} \begin{pmatrix} \beta & 1 & & & & & \\ 1 & \beta & 1 & & & & \\ & \ddots & \ddots & \ddots & & & \\ & & 1 & \beta & 1 & & \\ & & & 1 & \beta \end{pmatrix}$$



Factorisation of the coefficient matrix

$$\begin{pmatrix} c_2 & c_3 & 1 & & & & & & & \\ a_1 & a_2 & a_1 & 1 & & & & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & & & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & & & & \\ & & 1 & a_1 & a_2 & a_1 & 1 & & & \\ & & & 1 & a_1 & a_2 & a_1 & & & \\ & & & & 1 & c_3 & c_2 & & & \\ & & & & & & & & & \end{pmatrix} = \begin{pmatrix} a_2 - 1 & a_1 & 1 & & & & & & & \\ a_1 & a_2 & a_1 & 1 & & & & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & & & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & & & & \\ & & 1 & a_1 & a_2 & a_1 & 1 & & & \\ & & & 1 & a_1 & a_2 & a_1 & & & \\ & & & & 1 & a_1 & a_2 & a_1 & & \\ & & & & & 1 & a_1 & a_2 - 1 & & \end{pmatrix}$$

$$= \begin{pmatrix} \alpha & 1 & & & & & & & & \\ 1 & \alpha & 1 & & & & & & & \\ & \ddots & \ddots & \ddots & & & & & & \\ & & 1 & \alpha & 1 & & & & & \\ & & & 1 & \alpha & & & & & \\ & & & & & 1 & \alpha & & & \end{pmatrix} \begin{pmatrix} \beta & 1 & & & & & & & & \\ 1 & \beta & 1 & & & & & & & \\ & \ddots & \ddots & \ddots & & & & & & \\ & & 1 & \beta & 1 & & & & & \\ & & & 1 & \beta & & & & & \\ & & & & & 1 & \beta & & & \end{pmatrix}$$

$$M = 6: \quad \begin{array}{c|cc} P & \alpha & \beta \\ \hline -1 & -2 & -2 \end{array}$$

Factorisation of the coefficient matrix

$$\begin{pmatrix} c_2 & c_3 & 1 & & & & \\ a_1 & a_2 & a_1 & 1 & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & \\ & \ddots & \ddots & \ddots & \ddots & & \\ & & 1 & a_1 & a_2 & a_1 & 1 \\ & & & 1 & a_1 & a_2 & a_1 \\ & & & & 1 & c_3 & c_2 \end{pmatrix} = \begin{pmatrix} a_2 - 1 & a_1 & 1 & & & & \\ a_1 & a_2 & a_1 & 1 & & & \\ 1 & a_1 & a_2 & a_1 & 1 & & \\ & \ddots & \ddots & \ddots & \ddots & & \\ & & 1 & a_1 & a_2 & a_1 & 1 \\ & & & 1 & a_1 & a_2 & a_1 \\ & & & & 1 & a_1 & a_2 - 1 \end{pmatrix} \\
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Factorisation of the coefficient matrix

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$$M = 6: \begin{array}{c|cc} P & \alpha & \beta \\ \hline -1 & -2 & -2 \\ 0 & -2 & -2 \\ 1 & -2 - 4 \frac{\sin \theta (2 \cos \theta - 2 + \theta \sin \theta)}{4 \sin \theta - \theta (1 + \cos \theta)} & -2 \end{array}$$

Problem 2

$$y^{(4)} - t = 4e^t$$

$$y(-1) = -1/e \quad y(1) = e$$

$$y''(-1) = 1/e \quad y''(1) = 3e$$

$$\text{Solution : } y(t) = e^t t$$

In theory, this problem is solved up to machine accuracy by any EF-rule with $P \geq 1$ and $\mu_j = 1$.

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$$P = 1 : y^{(6)}(t_j) - 2y^{(4)}(t_j)\mu_j^2 + y^{(2)}(t_j)\mu_j^4 = 0$$

differentiating the differential equation :

$$(y^{(2)}(t_j) + 4e^{t_j}) - 2(y_j + 4e^{t_j})\mu_j^2 + y^{(2)}(t_j)\mu_j^4 = 0$$

approximating $y^{(2)}(t_j)$ by $\mathcal{O}(h^2)$ finite difference scheme

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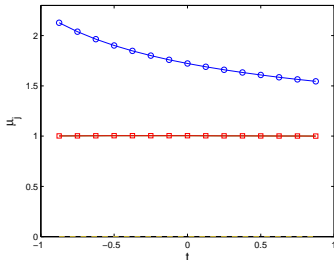
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two real roots $\mu^{(1)}$ and $\mu^{(2)}$

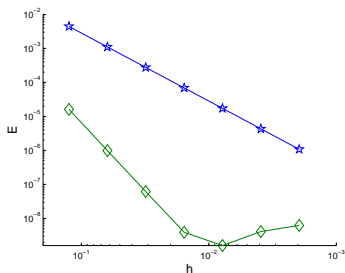
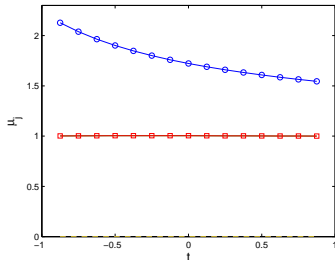
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two real roots $\mu^{(1)}$ and $\mu^{(2)}$

How to improve the accuracy ?

$$y^{(0)} \xrightarrow{\mu^{(1)}} y^{(1)} \xrightarrow{\mu^{(2)}} y^{(2)} \dots$$

- $y^{(0)}$ is obtained from classical, second order method
- compute $\mu^{(1)}$ from $y^{(0)}$ with classical second order schemes to approximate the derivatives that appear in the lte
- $y^{(1)}$ is obtained from EF method with $P = 1$ and $\mu = \mu^{(1)}$
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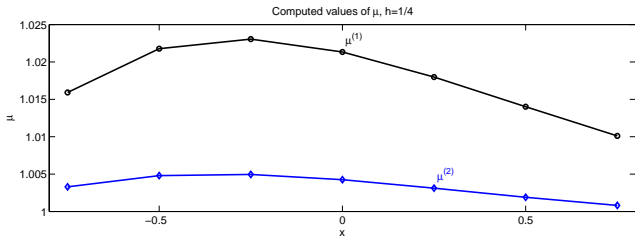
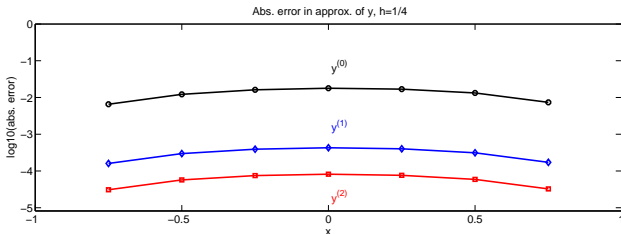
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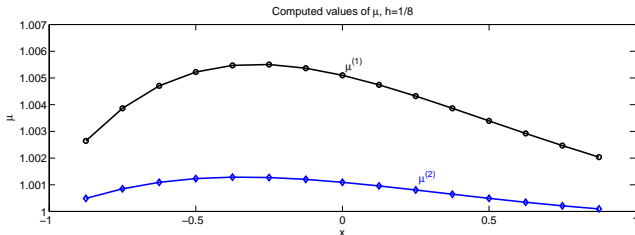
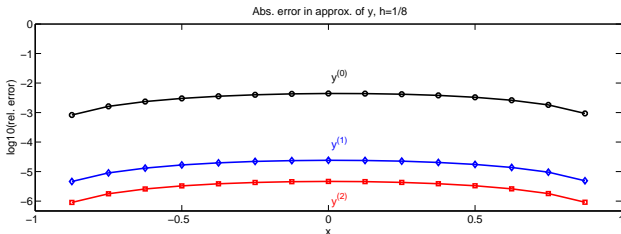
How to improve the accuracy ?

case $M = 6, h = 1/4$



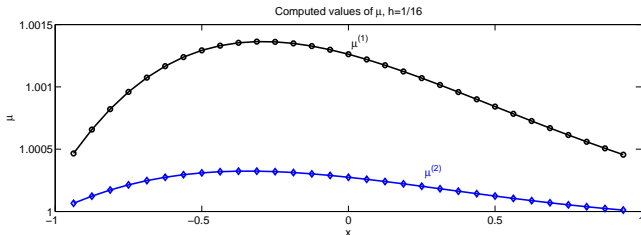
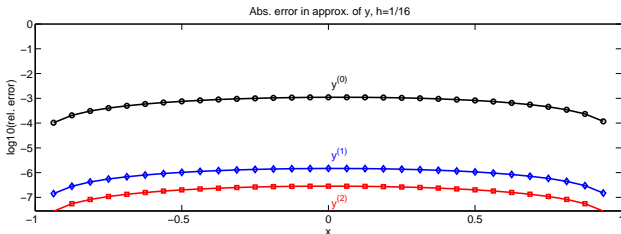
How to improve the accuracy ?

case $M = 6, h = 1/8$



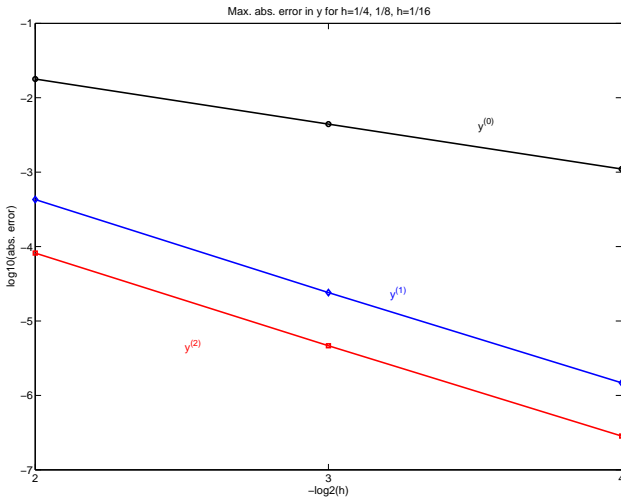
How to improve the accuracy ?

case $M = 6, h = 1/16$



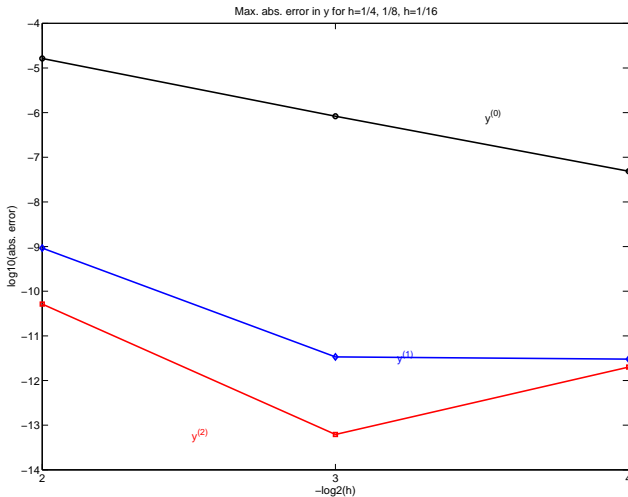
How to improve the accuracy ?

case $M = 6$



How to improve the accuracy ?

case $M = 8$



Conclusions

- Fourth-order boundary value problems are solved by means of parameterized exponentially-fitted methods.
- A suitable value for the parameter can be found from the roots of the leading term of the local truncation error.
- If a constant value is found, then a very accurate solution can be obtained.
- However, the methods strongly suffer from the fact that the system to be solved is ill-conditioned for small values of the mesh size.

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