THE DYNAMICAL STRUCTURE OF DARK MATTER HALOS WITH UNIVERSAL PROPERTIES

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ABSTRACT

N-body simulations have unveiled several apparently universal properties of dark matter halos, including a cusped density profile, a power-law pseudo-phase-space density ρ/σ_r^3 , and a linear $\beta-\gamma$ relation between the density slope and the velocity anisotropy. We present a family of self-consistent phase-space distribution functions (DFs) F(E, L), based on the Dehnen–McLaughlin Jeans models, that incorporate these universal properties very accurately. These DFs, derived using a quadratic programming technique, are analytical, positive, and smooth over the entire phase space and are able to generate four-parameter velocity anisotropy profiles $\beta(r)$ with arbitrary asymptotic values β_0 and β_{∞} . We discuss the orbital structure of six radially anisotropic systems in detail and argue that, apart from its use for generating initial conditions for *N*-body studies, our dynamical modeling provides a valuable complementary approach to understand the processes involved in the formation of dark matter halos.

Key words: dark matter - methods: analytical

1. INTRODUCTION

In theoretical astrophysics the steady increase in computational power has sparked a proportional interest and progress in the study of large-scale structure formation. In particular, as *N*-body simulations of cold dark matter halos have become more detailed, several "universal" properties have emerged. We highlight three important characteristics.

First, numerous cosmological studies (e.g., Dubinski & Carlberg 1991; Crone et al. 1994; Navarro et al. 1996, 1997; Fukushige & Makino 1997; Carlberg et al. 1997; Moore et al. 1998, 1999; Jing & Suto 2000) revealed similar density profiles over several orders of magnitude in halo mass, with a central cusp and a $\rho(r) \propto r^{-3}$ falloff at large radii. These generalized Navarro–Frenk–White (NFW) models can be described by a general three-parameter family, referred to as the Zhao models (or $\alpha\beta\gamma$ -models; Hernquist 1990; Zhao 1996). They are defined by the density

$$\rho(r) = \frac{2^{(\gamma_{\infty} - \gamma_0)/\eta} \rho_{\rm s}}{(r/r_{\rm s})^{\gamma_0} (1 + (r/r_{\rm s})^{\eta})^{(\gamma_{\infty} - \gamma_0)/\eta}},\tag{1}$$

or in terms of the logarithmic slope,

$$\gamma(r) = -\frac{d\ln\rho}{d\ln r}(r) = \frac{\gamma_0 + \gamma_\infty (r/r_s)^{\eta}}{1 + (r/r_s)^{\eta}}.$$
 (2)

Although in recent years alternative profiles based on the Sérsic law have produced equally good results (Navarro et al. 2004; Merritt et al. 2005), the generalized NFW models remain very popular and successful to represent dark matter halos.

A second relation was found by Taylor & Navarro (2001). These authors identified that the quantity $Q(r) = \rho/\sigma^3(r)$, which has become known as the pseudo-phase-space density, behaves as a power law over 2–3 orders of magnitude in radius inside the virial radius,

$$Q(r) \propto r^{-\alpha}.$$
 (3)

Other studies (e.g., Rasia et al. 2004; Ascasibar et al. 2004) have confirmed the scale-free nature of Q(r), and their results indicate that its slope lies in the range $\alpha = 1.90 \pm 0.05$. This

property is remarkable since the density $\rho(r)$ nor the velocity dispersion $\sigma(r)$ separately shows a power-law behavior.

Finally, the velocity anisotropy profiles $\beta(r)$ of dark matter systems also evolve toward a similar shape, steepening gradually from isotropic in the center to radially anisotropic in the outer regions. Hansen & Moore (2006) suggested a nearly linear relation between the logarithmic density slope $\gamma(r)$ and the velocity anisotropy profile, based on various types of equilibrated simulations. They proposed the $\beta-\gamma$ relation

$$\beta(\gamma) \simeq 1 - 1.15(1 + \gamma/6).$$
 (4)

Several theoretical studies have been made to investigate whether solutions of the Jeans equation exist that encompass the observed properties of dark matter halos. In particular, Dehnen & McLaughlin (2005) investigated the anisotropic Jeans equation constrained by a slightly different form of the pseudophase-space density, namely $Q_r(r) = \rho / \sigma_r^3$ with $\sigma_r(r)$ the radial velocity dispersion. They found a special solution, namely an analytical self-consistent potential-density pair of the form of Equation (1) with an anisotropy profile

$$\beta(r) = \frac{\beta_0 + \beta_\infty (r/r_a)^{2\delta}}{1 + (r/r_a)^{2\delta}},$$
(5)

that also has an exactly linear $\beta - \gamma$ relation (in other words, $r_a = r_s$ and $2\delta = \eta$). As these Jeans models satisfy the three universal relations mentioned above, we can consider them as representative models for realistic dark matter halos.

The goal of this paper is to take the analytical study of dark matter systems a step further, i.e., to look for full dynamical models that encompass the universal properties found in *N*-body simulations. In *concreto* we will look for phase-space distribution functions (DFs) $F(\vec{r}, \vec{v})$ that self-consistently generate the required density, potential, and anisotropy profiles encountered in dark matter halos. Such dynamical models would provide a very useful complementary approach to gain insight into the structure of dark matter halos.

We shall focus on spherical models, for which a dynamical description simplifies substantially, and as in this case, the DF can be expressed as a function F(E, L) of the binding energy and the angular momentum. But even if we limit ourselves

to the spherical case, it is not straightforward to obtain such dynamical models. A simple approach is to solve the Jeans equation and approximate the velocity dispersion profiles by a multivariate Gaussian (Hernquist 1993). However, Kazantzidis et al. (2004) demonstrated that these systems are far from equilibrium, thus losing their initial dynamical structure as they evolve to non-Gaussian velocity distributions in subsequent *N*-body simulations. We therefore need the tools to derive full self-consistent equilibrium models, governed by DFs with a sufficiently general velocity anisotropy profile.

Simple analytical models are found for only a few special cases, such as the Plummer, Hernquist, isochrone, and γ -models (e.g., Dejonghe 1987; Hernquist 1990; Baes & Dejonghe 2002; An & Evans 2006; Buyle et al. 2007a), none of which are able to describe realistic dark matter halos. For general potentialdensity pairs, Osipkov (1979) and Merritt (1985) provided an algorithm to construct dynamical models with a specific velocity anisotropy profile of the form (5), with $\beta_0 = 0$, $\beta_{\infty} = 1$, and $\delta = 1$, leaving r_a as a free parameter. While the Osipkov–Merritt method has been widely adopted (e.g., Widrow 2000; Łokas & Mamon 2001; Kazantzidis et al. 2004), comparison with simulations shows that such anisotropy profiles are too steep to describe dark matter (Mamon & Łokas 2005). Halos are not completely radial at infinity (i.e., $\beta_{\infty} < 1$) and the linear $\beta - \gamma$ relation can only be realized with a lower transition rate $\delta < 1$. On a dynamical note, the associated DFs are of the form F(Q)with $Q = E - L^2/2r_a^2$, creating an unphysical cutoff boundary for orbits with Q' < 0. Hence, the Osipkov–Merritt framework is too limited to generate realistic dark matter systems, and a more extensive method is needed.

Recently, Wojtak et al. (2008) presented an interesting approach to generate dynamical models for potential-density pairs with a more general anisotropy profile. They proposed to express the DF as a separable function of the form $f_E(E) f_L(L)$ where $f_L(L)$ is a double power-law function with three parameters β_0 , β_{∞} , and L_0 . Once their values have been determined, the function $f_E(E)$ is derived from the observed density profile by a numerical inversion. This technique yields a three-parameter anisotropy profile that resembles Equation (5), where L_0 has a similar role as r_a , and a fixed transition rate $0.5 < \delta < 1$. In this manner, the authors were able to construct models with an NFW density with velocity dispersion profiles that agreed with their dark matter simulations.

In this paper, we present a technique that enables us to obtain dynamical models with exactly the four-parameter anisotropy profile of Equation (5). We demonstrated in a previous paper (Baes & Van Hese 2007, hereafter Paper I) how this can be achieved, by postulating a separable parameterized form of the so-called augmented density, which provides an equivalent description of a dynamical system. In certain special cases the transformation from the augmented density to the DF is analytically tractable. We were thus able to derive a family of DFs for the generalized Plummer models (also called α -models or Veltmann models, Veltmann 1979) with a linear β – γ relation.

Since the generalized Plummer potential-density pairs form a special class of the Zhao models (1), we will now demonstrate that this result is a first step toward more representative dark matter profiles. In particular, we seek a family of DFs for the Dehnen-McLaughlin systems, because of their unique property to satisfy a universal density, a power-law $Q_r(r)$, and a linear $\beta-\gamma$ relation. We use a quadratic programming technique (Dejonghe 1989) to build DFs as a linear combination of base functions of the form derived in Paper I. In this manner, we demonstrate that it is indeed possible to generate full dynamical models for the Dehnen–McLaughlin Jeans models, thus providing DFs that encompass the observed properties of dark matter halos.

Our paper is organized as follows. In Section 2, we describe the notion of a dynamical model and briefly summarize the main aspects of the Dehnen–McLaughlin halos. Next we outline our modeling technique in Section 3: we explain the quadratic programming algorithm and recapitulate the functions that we derived in Paper I. With these components, we can build a library to apply the QP-method to the Dehnen–McLaughlin halos. In Section 4, we present our results for a set of systems with different velocity anisotropy profiles and discuss the moments, phase-space DFs, and energy and angular momentum distributions for these models. Finally, we formulate our conclusions in Section 5.

2. PRELIMINARIES

2.1. Dynamical Models

The dynamical structure of a gravitational equilibrium system is completely determined by the DF $F(\vec{r}, \vec{v})$, which describes the probability distribution of particles in six-dimensional phase space. A dynamical model is only physical if its DF is nonnegative everywhere. In the case of spherical symmetry, this DF can be written as a function F(E, L) of two isolating integrals, namely the binding energy and the angular momentum

$$E = \psi(r) - \frac{1}{2}v_r^2 - \frac{1}{2}v_T^2, \tag{6}$$

$$L = r v_T, \tag{7}$$

with

$$v_T = \sqrt{v_\theta^2 + v_\varphi^2},\tag{8}$$

the transverse velocity, and $\psi(r)$ the positive binding potential. For circular orbits the integrals of motion can be written as a function of the radius r,

$$E_{\rm c}(r) = \psi(r) + \frac{r}{2} \frac{d\psi}{dr}(r), \qquad (9)$$

$$L_{\rm c}(r) = -r^3 \frac{d\psi}{dr}(r),\tag{10}$$

which can be solved to obtain $E_c(L)$ and $L_c(E)$. All dynamical properties can be derived from the DF, such as the anisotropic velocity moments

$$\mu_{2n,2m}(r) = 2\pi M_{\text{tot}} \int_{-\infty}^{+\infty} dv_r \int_{0}^{+\infty} F(E,L) v_r^{2n} v_T^{2m+1} dv_T,$$
(11)

with M_{tot} the total mass. If the system is self-consistent, then the density $\rho(r) = \mu_{00}(r)$ is connected to the potential via the Poisson equation

$$\frac{1}{r^2}\frac{d}{dr}\left(r^2\frac{d\psi}{dr}\right)(r) = -4\pi G\rho(r).$$
(12)

Furthermore, the second-order moments determine the radial and tangential velocity dispersions $\mu_{20}(r) = \rho \sigma_r^2(r)$ and $\mu_{02}(r) = 2\rho \sigma_{\theta}^2(r)$, and the velocity anisotropy profile

$$\beta(r) = 1 - \frac{\sigma_{\theta}^2(r)}{\sigma_r^2(r)}.$$
(13)

A DF is only fully determined when all velocity moments in Equation (11) are known (Dejonghe 1987). However, it is already far from trivial to obtain *any* nonnegative DF that adequately generates a given density $\rho(r)$ and anisotropy profile $\beta(r)$. In this paper, we will focus our attention on one specific family of halos, namely the Dehnen–McLaughlin Jeans models, and demonstrate that a family of DFs can indeed be constructed for these systems.

2.2. The Dehnen-McLaughlin Halos

In the context of theoretical dark matter studies, the model derived by Dehnen & McLaughlin (2005) is of particular interest. We summarize their main results in this section. Instead of fitting a parameterized density profile to *N*-body simulations, they investigated the solution space of the Jeans equation to search for models that explicitly obey the power-law behavior of the pseudo-phase-space density. With the extra condition of a linear $\beta - \gamma$ relation they found a critical solution that satisfies the condition

$$\frac{\rho}{\sigma_r^{\varepsilon}}(r) = \frac{\rho}{\sigma_r^{\varepsilon}}(r_{\rm s}) \left(\frac{r}{r_{\rm s}}\right)^{-\alpha_{\rm crit}},\tag{14}$$

with r_s being the scale radius. In the remainder of this paper, we adopt the common value $\varepsilon = 3$ and use the notation $Q_r(r) = \rho / \sigma_r^3$. Dehnen and McLaughlin derived for this case the exponent

$$\alpha_{\rm crit} = \eta + \frac{3}{2},\tag{15}$$

$$\eta = \frac{4 - 2\beta_0}{9},\tag{16}$$

with β_0 being the central velocity anisotropy. The corresponding potential–density pair is fully analytical, given by

$$\psi(r) = \frac{GM_{\text{tot}}}{r_{\text{s}}} \frac{1}{\eta} B_{\frac{1}{1+x^{\eta}}} \left(\frac{1}{\eta}, \frac{1-\beta_0}{\eta} + \frac{1}{2}\right), \quad (17)$$

$$\rho(r) = \frac{4 + \eta - 2\beta_0}{8\pi} \frac{M_{\text{tot}}}{r_s^3} x^{-\gamma_0} (1 + x^\eta)^{-(\gamma_\infty - \gamma_0)/\eta}, \quad (18)$$

where $x = r/r_s$, $B_y(a, b)$ is the incomplete beta function and

$$\gamma_0 = \frac{7 + 10\beta_0}{9},\tag{19}$$

$$\gamma_{\infty} = \frac{31 - 2\beta_0}{9}.\tag{20}$$

The density can be equivalently written in terms of the slope $\gamma(r)$, which has the same elegant form as the velocity anisotropy profile $\beta(r)$,

$$\gamma(r) = \frac{\gamma_0 + \gamma_\infty x^\eta}{1 + x^\eta},\tag{21}$$

$$\beta(r) = \frac{\beta_0 + \beta_\infty x^\eta}{1 + x^\eta}.$$
(22)

Finally, the authors derived the corresponding velocity dispersions

$$\sigma_r^2(r) = \frac{1}{4 + \eta - 2\beta_{\infty}} \frac{GM_{\text{tot}}}{r_{\text{s}}} x^{-1} \left(\frac{x^{\eta}}{1 + x^{\eta}}\right)^{(\gamma_{\infty} - \gamma_0)/\eta - 2}, \quad (23)$$

$$\sigma_{\theta}^{2}(r) = \sigma_{\varphi}^{2}(r) = \frac{1}{2}\sigma_{T}^{2}(r) = (1 - \beta(r))\sigma_{r}^{2}(r).$$
(24)

Equations (14)–(24) characterize the Dehnen–McLaughlin models; we refer to their paper for more details. These systems are determined by five parameters: the exponent ε in the pseudo-phase-space density, two scaling constants, i.e., the total mass M_{tot} and the scale radius r_{s} , and the asymptotic anisotropy parameters β_0 and β_{∞} . The authors also noted the remarkable property that the shape of the density profile (and hence the gravitational potential) only depends on β_0 and not on β_{∞} .

While the Dehnen–McLaughlin Jeans models are derived from theoretical considerations, they also fit adequately galaxysized and certain cluster-sized halos generated by *N*-body simulations (Diemand et al. 2005; Merritt et al. 2006). But as mentioned in the previous section, the density and velocity dispersions alone do not determine the complete dynamical state of dark matter systems. We therefore aim to incorporate these profiles into self-consistent dynamical models, described by non-negative DFs.

3. THE MODELING TECHNIQUE

To find DFs that describe the Dehnen–McLaughlin Jeans models, we adopt the mathematical framework that we derived in Paper I. These tools enabled us to construct a family of components with the anisotropy profile of Equation (5), by means of the powerful augmented density concept. We summarize these results and demonstrate how to build a linear combination of these components using a quadratic programming (QP) technique (Dejonghe 1989). In this manner, we can fit a dynamical model to a given halo.

3.1. The Augmented Density Concept

Since our dynamical models have to reproduce the moments in Equations (18), (23), and (24), we first seek DFs that are specifically designed for this task. This can be done by introducing the augmented densities $\tilde{\rho}(\psi, r)$ (Dejonghe 1986), which extend the densities to explicit functions of both the radius and the gravitational potential. Like the DF, the augmented density uniquely determines the dynamical state of a spherical equilibrium system. Both functions are connected by the relation

$$\tilde{\rho}(\psi, r) = 2\pi M_{\text{tot}} \int_0^{\psi} dE \int_0^{2(\psi-E)} \frac{F(E, r \, v_T)}{\sqrt{2(\psi-E) - v_T^2}} \, dv_T^2.$$
(25)

If we define that all functions are zero when their arguments lie outside their physical bounds, we can use the Laplace–Mellin transforms

$$\mathcal{L}_{E \to \xi} \mathcal{M}_{L \to \lambda} \{F\} = \int_0^{+\infty} e^{-\xi E} dE \int_0^{+\infty} L^{\lambda - 1} F(E, L) dL, \quad (26)$$

$$\mathcal{L}_{\psi \to \xi} \mathcal{M}_{r \to \lambda} \{\tilde{\rho}\} = \int_{0} e^{-\xi \psi} d\psi \int_{0} r^{\lambda - 1} \tilde{\rho}(\psi, r) dr, \quad (27)$$

with the inverse transforms

$$F(E, L) = -\frac{1}{4\pi^2} \int_{\xi_0 - i\infty}^{\xi_0 + i\infty} e^{\xi E} dE$$

$$\times \int_{\lambda_0 - i\infty}^{\lambda_0 + i\infty} L^{-\lambda} \mathop{\mathcal{L}}_{E \to \xi} \mathop{\mathcal{M}}_{L \to \lambda} \{F\} dL, \qquad (28)$$

$$\tilde{\epsilon}(h, r) = -\frac{1}{4\pi^2} \int_{\xi_0 + i\infty}^{\xi_0 + i\infty} e^{\xi \Psi} d\mu$$

$$\tilde{\rho}(\psi, r) = -\frac{1}{4\pi^2} \int_{\xi_0 - i\infty}^{\xi_0 + i\infty} e^{\xi\psi} d\psi \\ \times \int_{\lambda_0 - i\infty}^{\lambda_0 + i\infty} r^{-\lambda} \mathop{\mathcal{L}}_{\psi \to \xi} \mathop{\mathcal{M}}_{r \to \lambda} \{\tilde{\rho}\} dr.$$
(29)

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Combining these expressions with Equation (25), we obtain

$$\mathcal{L}_{\psi \to \xi} \mathcal{M}_{r \to \lambda} \{ \tilde{\rho} \} = 2\pi M_{\text{tot}} \int_{0}^{+\infty} e^{-\xi \psi} d\psi \int_{0}^{+\infty} v_{T}^{-\lambda} L^{\lambda - 1} dL$$

$$\times \int_{0}^{\psi} dE \int_{0}^{2(\psi-E)} \frac{F(E,L) dv_{T}^{2}}{\sqrt{2(\psi-E) - v_{T}^{2}}}.$$
 (30)

Interchanging the integrals yields the formal relation

$$\mathcal{L}_{E \to \xi} \mathcal{M}_{L \to \lambda} \{F\} = \frac{2^{\lambda/2}}{M_{\text{tot}}(2\pi)^{3/2}} \frac{\xi^{(3-\lambda)/2}}{\Gamma\left(1-\frac{\lambda}{2}\right)} \mathcal{L}_{\psi \to \xi} \mathcal{M}_{r \to \lambda}\{\tilde{\rho}\}.$$
 (31)

The main strength of the augmented density formalism is the ability to impose very specific conditions on these functions, to obtain our objective. More precisely, we demonstrated in Paper I that separable functions of the form

$$\tilde{\rho}(\psi, r) = f(\psi) g(r) \tag{32}$$

are particularly interesting, since in this case g(r) is directly related to the velocity anisotropy profile,

$$\beta(r) = -\frac{1}{2} \frac{d \ln g}{d \ln r}(r). \tag{33}$$

With this formalism it is therefore at least formally possible to generate a DF for a dynamical system with a given potential $\psi(r)$, density $\rho(r)$, and velocity anisotropy profile $\beta(r)$. If we postulate an anisotropy profile of the form of Equation (5), the modeling procedure reduces to the computation of $f(\psi)$ such that

$$\rho(r) = f(\psi(r)) \left(\frac{r}{r_{\rm a}}\right)^{-2\beta_0} \left(1 + \frac{r^{2\delta}}{r_{\rm a}^{2\delta}}\right)^{\beta_\delta},\qquad(34)$$

with $0 < \delta \leq 1$ and

$$\beta_{\delta} = \frac{\beta_0 - \beta_{\infty}}{\delta}.$$
(35)

Evidently, the exact solution $f(\psi)$ is generally of numerical form, except for a few special cases. This creates a problem to recover the DF from the augmented density, because a direct inversion of the Laplace–Mellin transformation in Equation (31) is, in general, numerically unstable (Dejonghe 1986). Indeed, the double integration in Equation (25) smoothes features in F(E, L), and the inversion procedure of determining F(E, L) from $\tilde{\rho}(\psi, r)$ has the delicate job of unsmoothing the information contained in $\tilde{\rho}(\psi, r)$. Consequently, a direct inversion can only be performed safely for sufficiently simple forms of $f(\psi)$.

We therefore take an alternative approach. Instead of solving Equation (34) directly, we will approximate the given density profile by a linear combination of simple base functions $\tilde{\rho}_i(\psi(r), r)$ for which the Laplace–Mellin inversions are analytical. The corresponding DF is then simply the same linear combination of the associated base DFs $F_i(E, L)$, resulting in an analytically tractable function. This can be achieved by a least-squares fit to a set of density data points, defining a quadratic programming problem in the unknown coefficients. Various authors have successfully used a similar modeling technique (Kuijken & Merrifield 1993; Merrifield & Kuijken 1994; Gerhard et al. 1998). A QP-algorithm, suited for this task, has been developed in our department (Dejonghe 1989), which we outline in the following section.

3.2. The Quadratic Programming Procedure

Consider a given potential $\psi(r)$, an anisotropy profile $\beta(r)$ of the form of Equation (5) and a set of *M* density data points $\rho_{obs}(r_m), m = 1, ..., M$. To model these data, we first construct a library of N_{lib} base functions

$$\tilde{\rho}_i(\psi, r) = f_i(\psi) \left(\frac{r}{r_a}\right)^{-2\beta_0} \left(1 + \frac{r^{2\delta}}{r_a^{2\delta}}\right)^{\beta_\delta}, \qquad (36)$$

with $f_i(\psi)$ sufficiently simple to compute the associated distributions $F_i(E, L)$. From these components, we can extract the corresponding values

$$\rho_i(r_m) = \tilde{\rho}_i(\psi(r_m), r_m), \qquad m = 1, \dots, M.$$
(37)

Now our aim is to construct a linear combination of *N* components from this library that provides an adequate fit to the given data. Such a fit can be obtained in a statistically meaningful way by minimizing the quantity

$$\chi_N^2 = \frac{1}{M} \sum_{m=1}^M w_m \left(\rho_{\text{obs}}(r_m) - \sum_{i=1}^N a_{N,i} \rho_i(r_m) \right)^2, \quad (38)$$

which is a quadratic function of the coefficients $a_{N,i}$, consequently defining a quadratic programming problem. The data points are given equal weights by setting the constants $w_m = 1/\rho_{obs}^2(r_m)$.

To find such a set, we use an iterative algorithm (Dejonghe 1989). With this method, a set of components is successively built in N steps. In the first step, $N_{\rm lib}\chi^2$ -minimizations are performed using in turn each component of the library. The base function that yields the lowest χ^2 -value (hereafter denoted as χ_1^2) is retained as the first element of our best-fitting set, with the corresponding coefficient $a_{1,1}$. In each next iteration, the functions in this set are preserved, while the coefficients are allowed to vary. The set is subsequently extended by adding the component from the library that yields the most improvement of the fit, minimizing over all coefficients. In other words, suppose we have obtained the best-fitting set of N-1 base functions, with indices n_1, \ldots, n_{N-1} . Then, we add in turn the remaining $N_{\rm lib} - N + 1$ components from the library, and calculate the N coefficients for each combination by means of the χ^2 -minimizations

$$\chi^{2}_{(n_{N})} = \min_{a_{1},...,a_{N}} \frac{1}{M} \sum_{m=1}^{M} w_{m} \left(\rho_{\text{obs}}(r_{m}) - \sum_{i=1}^{N} a_{i} \rho_{n_{i}}(r_{m}) \right)^{2},$$

with $n_{N} \in \{1, ..., N_{\text{lib}}\} \setminus \{n_{1}, ..., n_{N-1}\}.$ (39)

From these $N_{\text{lib}} - N + 1$ values, we determine the best fit

$$\chi_N^2 = \chi_{(n_{\min})}^2 = \min_{n_N} \chi_{(n_N)}^2, \tag{40}$$

and add the base function with index n_{\min} to the best-fitting set, denoting $n_N = n_{\min}$. By renaming the indices of this set, we thus obtain a linear combination of N base functions $\tilde{\rho}_i(\psi, r)$ with coefficients $a_{N,i}$ and a goodness of fit χ_N^2 . The corresponding DF is then simply

$$F(E, L) = \sum_{i=1}^{N} a_{N,i} F_i(E, L).$$
(41)

The QP-algorithm allows additional linear constraints on the coefficients. In particular, we impose upper and lower boundaries

$$a_{\min} \leq a_{N,i} \leq a_{\max}, \qquad \forall N; i = 1, \dots, N.$$
 (42)

These constraints are not necessary, but they greatly reduce the computational cost in the calculation of the DF. The reason for this is straightforward: if the components are computed with numerical errors $\delta_i F_i$ then the total numerical error of the DF is

$$\delta F(E,L) = \frac{\sum_{i=1}^{N} |a|_{N,i} \,\delta_i F_i(E,L)}{\sum_{i=1}^{N} a_{N,i}}.$$
(43)

The higher the absolute values of the coefficients $|a|_{N,i}$, the smaller the errors $\delta_i F_i$ need to be to obtain a given δF , which increases the computational time. Sensible boundary values in (42) enable efficient calculations of the DF, while maintaining satisfactory fits.

The resulting DF also needs to be physical, i.e., nonnegative everywhere in phase space. We found that all our DFs automatically satisfy this condition without imposing explicit constraints.

This procedure has several advantages. The resulting DF remains analytically tractable, which also simplifies the computation of all the moments of this dynamical model. Furthermore, only a limited number of data points are required, rather than the entire density profile. The same algorithm can also be applied to data extracted from simulations or observations, and a variety of different moments besides the density can be used in the fitting procedure.

Finally, since all components have a priori the desired $\beta(r)$, their linear combination will automatically generate the same anisotropy profile. This is a very significant benefit. Indeed, practice has shown that it is particularly difficult to construct radially anisotropic systems from base functions that are too simple (such as Fricke components, Fricke 1952) with different constant anisotropies. In this case an additional fitting is required to the second-order moments. But more importantly, because radial orbits influence the density at both small and large radii, the summation of components with different anisotropies results in a delicate fine-tuning to obtain adequate fits to both the density and the velocity anisotropy. These problems are avoided if the components already have the correct anisotropy profile, and although it is more intricate to design such functions, this approach greatly reduces the complexity of the quadratic programming procedure.

3.3. The Base Functions

We are now left with the construction of a library of adequate base functions $\tilde{\rho}_i(\psi, r)$. The success of our modeling is largely determined by this library. As stated above, the components have to generate the anisotropy profile of (5), while being sufficiently simple to retrieve the corresponding DFs $F_i(E, L)$ from Equation (31). In addition, the subsequent densities $\rho_i(r_m)$ need to be able to reproduce the specific characteristics of the given data to obtain a satisfactory fit. In the particular case of the Dehnen–McLaughlin halos of Equation (18), this implies that the components should incorporate the central density cusp and the asymptotic density slope at large radii, using the given potential in Equation (17). In Paper I, we derived a family of base functions that meet all these requirements. Consider the family of augmented densities

$$\tilde{\rho}_i(\psi, r) = \rho_{0i} \left(\frac{\psi}{\psi_0}\right)^{p_i} \left(1 - \frac{\psi^{s_i}}{\psi_0^{s_i}}\right)^{q_i} \left(\frac{r}{r_a}\right)^{-2\beta_0} \left(1 + \frac{r^{2\delta}}{r_a^{2\delta}}\right)^{\beta_\delta},\tag{44}$$

where ρ_{0i} are normalization constants such that

$$4\pi \int_0^{+\infty} \tilde{\rho}_i(\psi(r), r) r^2 \, dr = 1, \tag{45}$$

and ψ_0 denotes the depth of the (finite) potential well, $\psi_0 = \psi(0)$. The normalization constants are chosen such that the sum of the coefficients of a good fit should approximate the total mass of the input data, i.e., $\sum_{i=1}^{N} a_{N,i} \simeq M_{\text{tot}}$.

Apart from the four fixed parameters that determine the anisotropy profile of Equation (22), the $f(\psi)$ -part of these functions contains three additional free parameters p_i , q_i , and s_i , which respectively determine the asymptotic behavior at infinity, the inner slope, and the transition rate between these two regions. They satisfy the conditions $p_i + 2\beta_{\infty} > 3$, $q_i \leq 0$, and $s_i > 0$.

All other dynamical properties can be calculated from these augmented densities. The augmented higher-order moments are derived in the Appendix, and we demonstrated in the Appendices of Paper I that for these $\rho_i(\psi, r)$ the inverse Laplace–Mellin transforms can be performed analytically in Equation (31). The corresponding DFs can be expressed as a series of Fox *H*-functions (Fox 1961):

$$F_{i}(E, L) = \frac{\rho_{0i}}{M_{\text{tot}}(2\pi \ \psi_{0})^{3/2}} \times \sum_{j=0}^{\infty} (-1)^{j} {q_{i} \choose j} \frac{\Gamma(1+p_{i}+js_{i})}{\delta \Gamma(-\beta_{\delta})} \left(\frac{E}{\psi_{0}}\right)^{p_{i}+js_{i}-3/2} \times H_{2,2}^{1,1} \left(\frac{L^{2}}{2r_{a}^{2}E} \middle| \begin{array}{c} (1-\frac{\beta_{\infty}}{\delta}, \frac{1}{\delta}), (p_{i}+js_{i}-\frac{1}{2}, 1) \\ (-\frac{\beta_{0}}{\delta}, \frac{1}{\delta}), (0, 1) \end{array} \right),$$
(46)

which can be written as a double series

$$F_{i}(E, L) = \frac{\rho_{0i}}{M_{\text{tot}}(2\pi \,\psi_{0})^{3/2}} \sum_{j=0}^{\infty} (-1)^{j} \begin{pmatrix} q_{i} \\ j \end{pmatrix} \left(\frac{E}{\psi_{0}}\right)^{p_{i}+js_{i}-3/2} \\ \times \sum_{k=0}^{\infty} \binom{\beta_{\delta}}{k} \frac{\Gamma(1+p_{i}+js_{i})}{\Gamma\left(p_{i}+js_{i}-\frac{1}{2}+\beta_{k}\right)\Gamma(1-\beta_{k})} \\ \times \left(\frac{L^{2}}{2r_{a}^{2}E}\right)^{-\beta_{k}}, \qquad (47)$$

where we used the auxiliary notation

$$\beta_k = \begin{cases} \beta_0 - k\delta & \text{for } L^2 < 2r_a^2 E, \\ \beta_\infty + k\delta & \text{for } L^2 > 2r_a^2 E. \end{cases}$$
(48)

The double summation $\sum_{j} \sum_{k}$ can be computed by changing the indices to $\sum_{l} \sum_{j+k=l}$, so that the inner summation becomes a finite sum of l+1 terms for each value of l; the index l is increased until the total sum alters by less than a required numerical error $\delta_i F_i$. Due to the double summation, the computational time is approximately an inverse quadratic function of $\delta_i F_i$.

We proved in Paper I that these base DFs are continuous and nonnegative everywhere in physical phase space. Moreover, No. 2, 2009

we showed that they generate exactly the generalized Plummer potential–density pairs (Veltmann 1979)

$$\psi_{\rm gp}(r) = \frac{GM_{\rm tot}}{\left(r_{\rm s}^{\eta} + r^{\eta}\right)^{1/\eta}},\tag{49}$$

$$\rho_{\rm gp}(r) = \frac{(1+\eta) M_{\rm tot}}{4\pi} \frac{r_{\rm s}^{\eta}}{r^{2-\eta} \left(r_{\rm s}^{\eta} + r^{\eta}\right)^{2+1/\eta}},\tag{50}$$

with a linear $\beta - \gamma$ relation. Since these systems are closely related to the Dehnen–McLaughlin halos, this is a promising result for the success of the quadratic programming routine.

The FORTRAN source code with the DF base functions and the augmented moments is available on request.

3.4. The Library of Components

Every given Dehnen–McLaughlin halo requires a specific component library. In particular, the parameters p_i and q_i are constrained by the potential. If we examine the asymptotic behavior of the Dehnen–McLaughlin potential in Equation (17) in more detail, we find

$$\psi(r) \sim \psi_0 - a r^{(11-10\beta_0)/9} + \cdots \quad \text{for} \quad r \to 0,$$

$$\psi(r) \sim \frac{1}{r} \qquad \qquad \text{for} \quad r \to \infty.$$
 (51)

Introducing these asymptotic expansions in the expression (44) we find for the inner and outer slopes of the density

$$\widetilde{\rho}_{i}(\psi(r), r) \sim r^{-2\beta_{0}+q_{i}(11-10\beta_{0})/9} \quad \text{for} \quad r \to 0,
\widetilde{\rho}_{i}(\psi(r), r) \sim r^{-2\beta_{\infty}-p_{i}} \quad \text{for} \quad r \to \infty.$$
(52)

Evidently, the parameters p_i stipulate the density slope at large radii. Because the models fall as $r^{-\gamma_{\infty}}$, no components can be used in the fitting routine that fall less rapidly. Using Equation (20), this puts a boundary on the p_i ,

$$p_i \geqslant \frac{31 - 2\beta_0 - 18\beta_\infty}{9} \equiv p_{\min}(\beta_0, \beta_\infty).$$
(53)

Conversely, the density slope at small radii depends on the parameters q_i . The density diverges toward the center as $r^{-\gamma_0}$, and we cannot use components in the fitting routine that have a steeper slope. Thus we obtain from Equation (20)

$$q_i \ge -\frac{7 - 8\beta_0}{11 - 10\beta_0} \equiv q_{\min}(\beta_0).$$
 (54)

So if a fit to a halo has at least one component with parameter p_{\min} and one with q_{\min} , this fit has the same slope as the given density at small and large radii.

Finally, the parameters s_i have a similar role as δ , in the sense that they control the transition rate between the inner and outer density slopes. Their value can be chosen freely, but we found that excellent results are obtained with a single fixed value

$$s_i \equiv 2\delta = \eta, \tag{55}$$

for all components. This is the same choice as the generalized Plummer models in Paper I. It also simplifies the computation of the DFs in Equations (47) and (48), and it further facilitates the fitting process, leaving only p_i and q_i as free parameters.



Figure 1. Obtained χ_N^2 for the six QP-models, explicitly as a function of the number of components in the fit. The different curves correspond to $\beta_{\infty} = 0$, 0.2, 0.4, 0.6, 0.8, and 1, with a gray scale ranging from black ($\beta_{\infty} = 0$) to light gray ($\beta_{\infty} = 1$).

4. RESULTS

4.1. The Minimization

Now that we have derived the necessary mathematical tools, we can present the results for the Dehnen–McLaughlin halos. Without loss of generality, we can work in dimensionless units $G = M_{\text{tot}} = r_{\text{s}} = r_{\text{a}} = 1$, and we limit ourselves to $\varepsilon = 3$. Consequently, the models are determined by the anisotropy parameters β_0 and β_{∞} . Although we are able to generate models with arbitrary values for these parameters, realistic dark matter halos are nearly isotopic near the center and radially anisotropic at large radii, so that we concentrate on six representative models with $\beta_0 = 0$ and $\beta_{\infty} = 0$, 0.2, 0.4, 0.6, 0.8, 1. We verified that the modeling procedure works equally well for models with nonzero values of β_0 . Finally, it is evident from Equation (16) that $\beta_0 = 0$ sets the parameters $s_i \equiv 2\delta = \eta = 4/9$.

As we demonstrated above, the very specific form of the base functions in Equation (44) simplifies our QP-algorithm considerably for these models. Only the parameters p_i and q_i remain to construct a library of components, and we have found that only 30 components are sufficient to yield excellent fits. The parameters p_i take five values, ranging from $p_{\min}(0, \beta_{\infty})$ to 10 or 12, depending on the model. The parameters q_i take six values from $q_{\min}(0)$ to 0. We list these values for each model in the headers of Table 1.

We extract M = 25 values of the density (18) at radii r_m , distributed logarithmically between $10^{-3} r_s$ and $10^4 r_s$, that serve as input data $\rho_{obs}(r_m)$ in each QP-procedure. Evidently, this range is much larger than the virialized region in *N*-body simulations. This larger range is therefore not intended to be realistic, but rather to demonstrate that our models are accurate to arbitrary distances. Furthermore, this makes it possible to create discrete equilibrium systems from the DFs, by means of Monte Carlo simulators, that trace very closely the Dehnen– McLaughlin halos. After calculating the densities in Equation (44) of every library component at these radii $\tilde{\rho}_i(\psi(r_m), r_m)$, we can perform the QP-algorithm for the six values of β_{∞} , constructing iteratively the best-fitting linear combination (38) of *N* components with additional constraints of the form (42),

$$-100 \leqslant a_{N,i} \leqslant 100, \quad \forall N; \ i = 1, \dots, N.$$
 (56)

We show the results for the six models in Table 1. The columns list the components of the fits. Every χ_N^2 denotes the goodness of fit of the best linear combination of the components in columns

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Table 1 Components of the Six QP-models

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|-------------|-------------------------|-------------------------|-----------------------|-----------------------|--|-----------------------|--|-----------------------|-----------------------|-----------------------|
| | $\beta_{\infty} = 0.0,$ | $\beta_{\infty} = 0.0,$ | s = 4/9, | $\delta = 2/9$ | $p_i = 3.4\overline{4}, 4, 5, 7.5, 10$ | | $q_i = -0.\overline{63}, -0.5, -0.4, -0.3, -0.15, 0$ | | | |
| $a_{10,i}$ | 0.2047 | -0.0380 | -0.5411 | 1.6652 | 0.0414 | -3.8806 | 0.1312 | 2.5207 | -0.2684 | 1.1652 |
| ρ_{0i} | 0.0053 | 1.9783 | 0.0009 | 2.5540 | 0.4890 | 3.0677 | 0.0384 | 3.6728 | 6.1920 | 0.0008 |
| p_i | 4.0000 | 10.0000 | 3.4444 | 10.0000 | 7.5000 | 10.0000 | 5.0000 | 10.0000 | 10.0000 | 3.4444 |
| q_i | -0.6364 | -0.6364 | 0.0000 | -0.5000 | -0.6364 | -0.4000 | -0.6364 | -0.3000 | 0.0000 | -0.6364 |
| χ^2_N | 0.44×10^{0} | 0.17×10^{0} | 0.67×10^{-1} | 0.33×10^{-1} | 0.24×10^{-2} | 0.17×10^{-2} | 0.53×10^{-4} | 0.36×10^{-4} | 0.48×10^{-5} | 0.82×10^{-7} |
| | $\beta_0 = 0.0$ | $\beta_{\infty} = 0.2,$ | s = 4/9, | $\delta = 2/9$ | $p_i = 3.0\overline{4}, 4, 5, 7.5, 10$ | | $q_i = -0.\overline{63}, -0.5, -0.4, -0.3, -0.15, 0$ | | | |
| $a_{10,i}$ | -0.1534 | 15.5467 | -0.0006 | 0.4549 | -0.2707 | 74.2329 | -88.6417 | 0.5880 | -0.7724 | 0.0165 |
| ρ_{0i} | 0.0238 | 0.0017 | 3.4087 | 4.4609 | 11.3269 | 0.0014 | 0.0015 | 8.6356 | 5.4102 | 0.9797 |
| p_i | 4.0000 | 3.0444 | 10.0000 | 10.0000 | 10.0000 | 3.0444 | 3.0444 | 10.0000 | 10.0000 | 7.5000 |
| q_i | -0.6364 | 0.0000 | -0.6364 | -0.5000 | 0.0000 | -0.6364 | -0.5000 | -0.1500 | -0.4000 | -0.6364 |
| χ^2_N | 0.48×10^{0} | 0.27×10^{0} | 0.43×10^{-1} | 0.93×10^{-2} | 0.13×10^{-2} | 0.88×10^{-3} | 0.10×10^{-4} | 0.95×10^{-5} | 0.48×10^{-5} | 0.32×10^{-7} |
| | $\beta_0 = 0.0$ | $\beta_{\infty} = 0.4,$ | s = 4/9, | $\delta = 2/9$ | $p_i = 2.6\overline{4}$ | , 4, 5, 8, 12 | $q_i = -0.\overline{63}, -0.5, -0.4, -0.3, -0.15, 0$ | | | |
| $a_{10,i}$ | 8.2375 | -1.4318 | -0.0467 | 0.2297 | 2.2705 | -0.0111 | 0.1299 | 10.3097 | -0.3108 | -18.3771 |
| ρ_{0i} | 0.0832 | 0.0032 | 10.9019 | 14.9246 | 0.0028 | 2.4301 | 23.3335 | 0.1015 | 18.6978 | 0.0934 |
| p_i | 4.0000 | 2.6444 | 12.0000 | 12.0000 | 2.6444 | 8.0000 | 12.0000 | 4.0000 | 12.0000 | 4.0000 |
| q_i | -0.6364 | 0.0000 | -0.6364 | -0.5000 | -0.6364 | -0.6364 | -0.3000 | -0.4000 | -0.4000 | -0.5000 |
| χ^2_N | 0.48×10^{0} | 0.18×10^0 | $0.28 	imes 10^{-1}$ | 0.93×10^{-2} | 0.42×10^{-2} | 0.14×10^{-3} | 0.36×10^{-4} | 0.13×10^{-4} | 0.68×10^{-5} | 0.24×10^{-6} |
| | $\beta_0 = 0.0,$ | $\beta_{\infty} = 0.6,$ | s = 4/9, | $\delta = 2/9$ | $p_i=2.2\overline{4},$ | 3.5, 5, 8, 12 | $q_i = -0.\overline{63}, -0.5, -0.4, -0.3, -0.15, 0$ | | | |
| $a_{10,i}$ | 0.3552 | 2.0738 | -0.0094 | 0.0086 | 16.3498 | -17.4861 | 0.0731 | -0.3019 | -0.2109 | 0.1477 |
| ρ_{0i} | 0.1222 | 0.0063 | 16.7922 | 23.2672 | 0.0053 | 0.0055 | 4.3156 | 0.1372 | 8.0592 | 10.5109 |
| p_i | 3.5000 | 2.2444 | 12.0000 | 12.0000 | 2.2444 | 2.2444 | 8.0000 | 3.5000 | 8.0000 | 8.0000 |
| q_i | -0.6364 | 0.0000 | -0.6364 | -0.5000 | -0.6364 | -0.5000 | -0.6364 | -0.5000 | -0.3000 | -0.1500 |
| χ^2_N | 0.44×10^{0} | 0.15×10^{0} | 0.18×10^{-1} | 0.67×10^{-2} | 0.31×10^{-2} | 0.16×10^{-4} | 0.13×10^{-4} | 0.10×10^{-4} | 0.17×10^{-5} | 0.20×10^{-6} |
| | $\beta_0 = 0.0,$ | $\beta_{\infty} = 0.8,$ | s = 4/9, | $\delta = 2/9$ | $p_i = 1.8\overline{4}, 3, 5, 8, 12$ | | $q_i = -0.\overline{63}, -0.5, -0.4, -0.3, -0.15, 0$ | | | |
| $a_{10,i}$ | -0.0321 | -6.1421 | 0.0008 | -0.0013 | 24.5830 | -100.0000 | -0.0163 | -0.0926 | 40.5233 | 42.1774 |
| ρ_{0i} | 0.1791 | 0.0121 | 25.3820 | 35.5933 | 0.0101 | 0.0109 | 2.3877 | 0.2367 | 0.0105 | 0.0116 |
| p_i | 3.0000 | 1.8444 | 12.0000 | 12.0000 | 1.8444 | 1.8444 | 5.0000 | 3.0000 | 1.8444 | 1.8444 |
| q_i | -0.6364 | 0.0000 | -0.6364 | -0.5000 | -0.6364 | -0.4000 | -0.3000 | -0.3000 | -0.5000 | -0.1500 |
| χ^2_N | 0.40×10^0 | 0.11×10^0 | $0.11 	imes 10^{-1}$ | 0.46×10^{-2} | 0.22×10^{-2} | $0.66 	imes 10^{-5}$ | $0.26 	imes 10^{-5}$ | 0.13×10^{-5} | 0.47×10^{-6} | 0.24×10^{-6} |
| | $\beta_0 = 0.0,$ | $\beta_{\infty} = 1.0,$ | s = 4/9, | $\delta = 2/9$ | $p_i = 1.4\overline{4}, 3, 5, 8, 12$ | | $q_i = -0.\overline{63}, -0.5, -0.4, -0.3, -0.15, 0$ | | | |
| $a_{10,i}$ | -5.2047 | 0.1086 | 62.6962 | 40.1800 | -0.0002 | 0.0003 | -96.6969 | -0.1234 | 0.0273 | 0.0128 |
| ρ_{0i} | 0.0192 | 2.9967 | 0.0201 | 0.0213 | 37.6938 | 44.2497 | 0.0207 | 3.7237 | 7.8118 | 0.8543 |
| p_i | 1.4444 | 5.0000 | 1.4444 | 1.4444 | 12.0000 | 8.0000 | 1.4444 | 5.0000 | 5.0000 | 3.0000 |
| q_i | -0.6364 | -0.6364 | -0.5000 | -0.3000 | -0.6364 | 0.0000 | -0.4000 | -0.5000 | 0.0000 | -0.1500 |
| χ^2_N | 0.35×10^0 | 0.36×10^{-1} | $0.10 	imes 10^{-1}$ | 0.24×10^{-3} | 0.41×10^{-4} | $0.16 	imes 10^{-4}$ | 0.13×10^{-4} | 0.45×10^{-6} | 0.89×10^{-7} | 0.22×10^{-8} |

Notes. Our six models are determined by the anisotropy parameters $\beta_0 = 0$ and β_{∞} . With the QP-algorithm, we built linear combinations up to 10 components, each characterized by s, δ , p_i , q_i , and ρ_{0i} . The parameters s and δ are the same for each component, while p_i and q_i are selected from a library of 30 components. The five p_i values and six q_i values in each library are given in the headers. Every *N*th column lists the value χ_N^2 of the best fit with the first *N* components. The coefficients are given for the final fit with 10 components, i.e., $a_{10,i}$.

1 to *N*. Each component is determined by the parameters p_i and q_i , which in turn define the normalization constants ρ_{0i} from Equation (45). The coefficients are only given for the final fit with 10 components, i.e., $a_{10,i}$. It can be checked that for each model

$$\sum_{i=1}^{10} a_{10,i} \simeq M_{\text{tot}} = 1, \tag{57}$$

indicating excellent fits. Combining this result with Equations (43) and (56), it can be seen that if N = 10, the numerical errors of the base functions $\delta_i F_i$ need at most to be a factor of 10^3 smaller than a given error δF , allowing efficient computations of the DF with sufficient accuracy.

The resulting χ_N^2 for each model are also displayed in Figure 1. Evidently, N = 10 components are more than sufficient to obtain very accurate dynamical models. As an example, Figure 2 shows the 10 individual components of the QP-model with $\beta_{\infty} = 0.4$. Although this fit has the highest χ_{10}^2 of our set,

its total density is a very close approximation to the given data over the entire range in radius.

4.2. The Moments

Figure 3 displays several moments for our six models, with 10 components. The top row shows the density $\rho(r)$, the pseudophase-space density $Q_r(r)$, and the $\beta-\gamma$ relation. Below each graph, we calculated the residual errors between the QP-fits and the theoretical curves, i.e., for each profile f(r) we have

$$\Delta f(r) = \frac{f_{\rm obs}(r) - f_{\rm qp}(r)}{f_{\rm obs}(r)}.$$
(58)

As can be seen, the relative errors on the densities are less than 10^{-3} along 7 orders of magnitude in radius, and the exact asymptotic slopes of the models ensure excellent fits even beyond this range. The power-law trend of $Q_r(r)$ and the $\beta-\gamma$ relations are also reproduced very accurately with errors



Figure 2. Ten individual components of the fitted density for the QP-model with $\beta_0 = 0$ and $\beta_{\infty} = 0.4$. Their sum is the QP-density (black thick curve), fitting the 25 data points (dots).

~ 10^{-3} . Note that the small offset between the pseudo-phasespace density profiles for the different models is due to the dependence of $\sigma_r(r)$ on β_{∞} .

In the central row, we display the velocity dispersion profiles $\sigma_r(r)$, $\sigma_{\theta}(r)$, and the anisotropies $\beta(r)$. It is striking that, while the dispersion data were not used in the fit, the deviations of these moments from the theoretical values are even smaller, less than 5×10^{-4} . Evidently, since the models have the anisotropies of Equation (22) by construction, the $\beta(r)$ profiles are exact, without errors. Note also that all tangential velocity dispersion profiles $\sigma_{\theta}(r)$ intersect at a common radius $r = r_s (9/11)^{1/\eta}$.

While the density and dispersions are defined by the Dehnen– McLaughlin halos, the higher-order moments are determined by the QP-models. The fourth-order moments (see the Appendix) allow us to derive the radial and tangential kurtosis,

$$\kappa_r(r) = \frac{\langle v_r^4 \rangle}{\sigma_r^4}(r) - 3, \tag{59}$$

$$\kappa_{\theta}(r) = \frac{\langle v_{\theta}^4 \rangle}{\sigma_{\theta}^4}(r) - 3, \tag{60}$$



Figure 3. Most important moments for our set of representative models with 10 components. Top row: the density $\rho(r)$, the pseudo-phase-space density $Q_r(r)$, and the β - γ relation. Below each graph, the relative errors with respect to the theoretical profiles are shown. Middle row: the radial velocity dispersion $\sigma_r(r)$, the tangential velocity dispersion $\sigma_r(r)$, and the anisotropy $\beta(r)$, also with the relative errors. Bottom row: the radial kurtosis $\kappa_r(r)$, the tangential kurtosis $\kappa_{\theta}(r)$, and fourth-order anisotropy $\beta_4(r)$. The models and gray scaling are the same as in Figure 1.



Figure 4. Phase-space DFs for our set of models with 10 components. The six top panels show F(E, L) as isoprobability contours in the integral space. The energy is scaled to the central potential and the angular momentum is scaled to the angular momentum $L_c(E)$ of a circular orbit with energy *E*. The contour levels and the coloring are scaled logarithmically. The six bottom panels show the orbital DFs $N(E, L/L_c(E))$ for the same models.

and the fourth-order anisotropy

$$\beta_4(r) = 1 - \frac{\langle v_\theta^4 \rangle}{\langle v_r^4 \rangle}(r).$$
(61)

Interestingly, as a result of the separable form of the augmented densities, we find that the $\beta_4(r)$ profiles are only a function of the $\beta(r)$,

$$\beta_4(r) = \frac{1}{2}\beta(r)(3 - \beta(r)) + \frac{1}{2\beta_\delta}(\beta_0 - \beta(r))(\beta_\infty - \beta(r)).$$
(62)

These profiles are shown in the bottom row of Figure 3. The kurtosis values describe the non-Gaussianity of the velocity distributions at a certain radius. Our radial kurtosis values are very large in the center, which indicates that the v_r -distributions are very peaked (leptokurtic) at small radii. The $\kappa_r(r)$ curves decrease rapidly as a function of radius: they reach zero at radii between 0.26 and 0.36 and become negative at larger radii, leading to flat-topped (platykurtic) radial velocity distributions. This behavior is in accordance with *N*-body simulations (Kazantzidis et al. 2004; Wojtak et al. 2005). Clearly,



Figure 5. Energy and angular momentum distributions of the six QP-models with 10 components. The angular momenta are scaled to the values L_s of a circular orbit with radius r_s . The models and gray scaling are the same as in Figure 1.

the value of β_{∞} has little influence on the radial kurtosis, as in the case of $Q_r(r)$. In contrast, the tangential kurtosis $\kappa_{\theta}(r)$ curves do depend significantly on β_{∞} . All v_{θ} -distributions are highly peaked at small radii. For $\beta_{\infty} < 0.4$, the tangential kurtosis decreases to slightly negative values, i.e., at larger radii the tangential velocity distributions become slightly flat-topped. Models with $\beta_{\infty} \approx 0.4$ have nearly Gaussian v_{θ} -distributions for $r > r_s$. If $\beta_{\infty} > 0.4$, the $\kappa_{\theta}(r)$ profiles reach a minimum value and increase again for larger radii.

4.3. The Distribution Functions

The six top panels of Figure 4 show the DFs F(E, L) of our radially anisotropic systems with $\beta_0 = 0$ and $\beta_\infty = 0, \ldots, 1$, expressed as logarithmic isoprobability contours and a logarithmic color gradient in the integral space, with *L* scaled to $L_c(E)$, denoting the angular momentum of a circular orbit with energy *E*. All models are clearly physical, i.e., the DFs are nonnegative everywhere. This means that the Dehnen–McLaughlin Jeans models can actually be realized by full dynamical models. Moreover, contrary to the Osipkov–Merritt models, these functions fill the entire integral space. In the isotropic case, the contours are horizontal (no dependence on angular momentum), and their orientation alters gradually with increasing β_∞ in an intuitive way, as orbits with high eccentricities (i.e., low angular momentum) become more abundant.

The DFs describe the probability distributions of particles in phase space, but not in the integral space. It is more physically meaningful to consider the true orbital distributions

$$N(E, L/L_{c}(E)) = F(E, L) g(E, L) L_{c}(E),$$
(63)

with the so-called "density of states" function

$$g(E,L) = 16\pi^2 L \int_{r_-}^{r_+} \frac{dr}{\sqrt{2(\psi(r) - E) - L^2/r^2}},$$
 (64)

where r_{-} and r_{+} are the pericenter and apocenter of an orbit with energy *E* and angular momentum *L*, respectively. In other words, the functions $N(E, L/L_c(E))$ express the likelihood of an orbit with energy *E* and scaled angular momentum $L/L_c(E)$.

The results are displayed in the bottom panels of Figure 4 as logarithmic isoprobability contours and a logarithmic color gradient in the integral space. For high binding energies, all orbital distributions contain increasing probabilities toward circular orbits (high angular momentum). For low binding energies, i.e., at large radii, the abundance of orbits with low angular momentum gradually increases from the isotropic case to models with high values of β_{∞} .

4.4. The Marginal Distributions

We conclude the discussion of our Dehnen–McLaughlin DFs with an analysis of the marginal distributions. The differential energy and angular momentum distributions are the integrals of the orbital distributions,

$$N(E) = \int_{0}^{L_{c}(E)} N(E, L) \, dL, \tag{65}$$

$$N(L) = \int_{0}^{E_{\rm c}(L)} N(E, L) \, dE, \tag{66}$$

with

$$N(E, L) = \frac{1}{L_{\rm c}(E)} N(E, L/L_{\rm c}(E)).$$
(67)

These curves are displayed in Figure 5. The differential energy distributions are all monotonously decreasing functions of *E*. It is striking that these profiles are almost identical, regardless of the anisotropy β_{∞} . This result reinforces previous dynamical studies (Binney 1982) and suggests that $\rho(r)$, $Q_r(r)$, and $\kappa_r(r)$ are linked to a universal differential energy distribution, independent of β_{∞} , caused by the same physical processes.

In contrast, the angular momentum distributions depend on β_{∞} , most notably for high radial anisotropies. For increasing values of β_{∞} , the fraction of orbits with low angular momentum increases. Bullock et al. (2001) proposed a universal form for the integrated angular momentum distribution in dark matter halos M(L). Alternatively, Sharma & Steinmetz (2005) found a differential distribution

$$N_{\rm ss}(L) = \frac{1}{L_d^a \Gamma(a)} L^{a-1} e^{-L/L_d}.$$
 (68)

Our models indicate a similar profile, with a > 0.9, although the functions in Equation (68) fall steeper than ours as *L* increases.

5. CONCLUSIONS

In this paper, we presented a set of anisotropic DFs F(E, L) for the Dehnen–McLaughlin Jeans models. We constructed these DFs as a linear combination of base functions, which we fitted to the halo density by means of a quadratic programming algorithm. The base functions were specifically designed for this task, derived from a separable augmented density that generates exactly the general four-parameter velocity anisotropy profiles as given by Equation (5). We demonstrated that the resulting fits are very accurate, from the center to large radii, far beyond the range of *N*-body simulations.

This method has several advantages. The DFs can be written as a sum of a double series, without numerical integrations or inversions. Consequently, the DFs and all subsequent moments can be computed with high accuracy. Moreover, the advanced form of the base functions makes the QP-fitting very fast, requiring only a small number of library components.

In this manner, we have constructed a family of dynamical models that incorporate the observed features in *N*-body simulations. We summarize their properties:

- 1. The models a priori have the universal properties encountered in *N*-body studies of dark matter halos, which formed the building bricks of the Jeans models by Dehnen & McLaughlin (2005): they generate a universal density profile, a power-law pseudo-phase-space density $Q_r(r)$, four-parameter velocity anisotropy profiles with arbitrary values of β_0 and β_{∞} , and a linear $\beta \gamma$ relation. In particular, we analyzed six models that are isotropic in the center and radially anisotropic at large radii.
- 2. The DFs are physical, i.e., they are non-negative over the entire phase space. This means that the Dehnen– McLaughlin Jeans models can actually be realized by self-consistent dynamical systems. In addition, the DFs are continuous and smooth functions and, contrary to the popular Osipkov–Merritt models, they fill the entire accessible phase space.
- 3. The energy distributions are monotonously decreasing functions, and like the radial kurtosis profiles, these functions are nearly independent of β_{∞} . This suggests that $\rho(r)$, $Q_r(r)$, $\kappa_r(r)$, and N(E) have a universal form, caused by the same physical processes.

In addition, we have also been able to generate dynamical models with a nonlinear $\beta - \gamma$ relation, i.e., $\delta \neq \eta/2$ and $r_a \neq r_s$, albeit with higher χ_N^2 values. From these successful results for the Dehnen–McLaughlin halos, we expect equally adequate fits for other Zhao models, such as the NFW halos. Other profiles, such as the Sérsic-type densities, might require a modified family of base functions. Such a systematic study could unravel more hitherto hidden properties of dark matter halos and the various connections between these characteristics.

Our set of dynamical models is not only useful for a purely theoretical analysis. The DFs can also serve to generate initial conditions with Monte Carlo simulators (e.g., Kazantzidis et al. 2004; Buyle et al. 2007b) to investigate the physical processes within these equilibrium models by means of controlled numerical *N*-body simulations. Finally, our algorithm and base functions can be used in other dynamical studies, using different data moments than the density. This could lead to a significant improvement in the dynamical modeling of observed stellar systems, such as clusters of galaxies.

APPENDIX

DERIVATION OF THE AUGMENTED MOMENTS

In a spherical dynamical model, the anisotropic velocity moments of the DF are

$$\mu_{2n,2m}(r) = 2\pi M_{\text{tot}} \int_{-\infty}^{+\infty} dv_r \int_{0}^{+\infty} F(E,L) v_r^{2n} v_T^{2m+1} dv_T.$$
(A1)

Using the augmented density formalism, these moments can be calculated as $\mu_{2n,2m}(r) = \tilde{\mu}_{2n,2m}(\psi(r), r)$, with

$$\tilde{\mu}_{2n,2m}(\psi,r) = \frac{2^{m+n}}{\sqrt{\pi}} \frac{\Gamma\left(n+\frac{1}{2}\right)}{\Gamma(m+n)} \int_{0}^{\psi} (\psi-\psi')^{m+n-1} \\ \times D_{r^{2}}^{m}[r^{2m}\tilde{\rho}(\psi',r)] d\psi', \qquad (A2)$$

where D_x^m denotes the *m*th differentiation with respect to *x*. Applying this to our base functions in Equation (44), we obtain for the augmented second-order moments

$$\tilde{\mu}_{20,i}(\psi, r) = \frac{\rho_{0i}\psi_0}{s_i} \left(\frac{r}{r_a}\right)^{-2\beta_0} \left(1 + \frac{r^{2\delta}}{r_a^{2\delta}}\right)^{\beta_\delta} \times B_y\left(\frac{1+p_i}{s_i}, 1+q_i\right),$$
(A3)

with $y = (\psi/\psi_0)^{s_i}$, and

$$\tilde{\mu}_{02,i}(\psi, r) = 2(1 - \beta(r))\,\tilde{\mu}_{20,i}(\psi, r). \tag{A4}$$

The augmented fourth-order moments have the form

$$\tilde{\mu}_{40,i}(\psi, r) = \frac{3\rho_{0i}\psi_0^2}{s_i} \left(\frac{r}{r_a}\right)^{-2\beta_0} \left(1 + \frac{r^{2\delta}}{r_a^{2\delta}}\right)^{\beta_\delta} \\ \times \left[\frac{\psi}{\psi_0} B_y\left(\frac{1+p_i}{s_i}, 1+q_i\right)\right] \\ - B_y\left(\frac{2+p_i}{s_i}, 1+q_i\right)\right],$$
(A5)

$$\tilde{\mu}_{22,i}(\psi, r) = 2(1 - \beta(r))\,\tilde{\mu}_{40,i}(\psi, r),\tag{A6}$$

$$\begin{split} \tilde{\mu}_{04,i}(\psi,r) &= \frac{2}{3} \bigg[(1-\beta(r)) (2-\beta(r)) \\ &- \frac{1}{\beta_{\delta}} (\beta_0 - \beta(r)) (\beta_{\infty} - \beta(r)) \bigg] \\ &\times \tilde{\mu}_{40,i}(\psi,r). \end{split}$$
(A7)

The true velocity moments are connected with the anisotropic velocity moments through the relation

$$\tilde{\mu}_{2l,2m,2n}(\psi,r) = \frac{1}{\pi} B\left(m + \frac{1}{2}, n + \frac{1}{2}\right) \tilde{\mu}_{2l,2(m+n)}(\psi,r),$$
(A8)

so that

$$\rho \sigma_r^2(r) = \mu_{200}(r) = \sum_{i=1}^N a_{N,i} \,\tilde{\mu}_{20,i}(\psi(r), r), \tag{A9}$$

$$\rho \sigma_{\theta}^{2}(r) = \mu_{020}(r) = \frac{1}{2} \sum_{i=1}^{N} a_{N,i} \,\tilde{\mu}_{02,i}(\psi(r), r), \qquad (A10)$$

$$\rho \langle v_r^4 \rangle (r) = \mu_{400}(r) = \sum_{i=1}^N a_{N,i} \, \tilde{\mu}_{40,i}(\psi(r), r), \qquad (A11)$$

$$\rho \langle v_{\theta}^{4} \rangle (r) = \mu_{040}(r) = \frac{3}{4} \sum_{i=1}^{N} a_{N,i} \,\tilde{\mu}_{04,i} \,(\psi(r), r) \,. \tag{A12}$$

Finally, the fourth-order anisotropy profile can be derived by combining Equations (A7), (A11), and (A12),

$$\beta_4(r) = 1 - \frac{\langle v_\theta^4 \rangle}{\langle v_r^4 \rangle}(r) = \frac{1}{2}\beta(r)\left(3 - \beta(r)\right) + \frac{1}{2\beta_\delta}\left(\beta_0 - \beta(r)\right)\left(\beta_\infty - \beta(r)\right).$$
(A13)

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